Arm® Streamline
Target Setup Guide for Bare-metal Applications

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Release Information

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<th>Date</th>
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<tr>
<td>0701-00</td>
<td>25 September 2019</td>
<td>Non-Confidential</td>
<td>New document for v7.1.</td>
</tr>
<tr>
<td>0701-01</td>
<td>30 October 2019</td>
<td>Non-Confidential</td>
<td>Updated document for v7.1.</td>
</tr>
<tr>
<td>0702-00</td>
<td>14 February 2020</td>
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LES-PRE-20349
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Web Address
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Preface

This preface introduces the Arm® Streamline Target Setup Guide for Bare-metal Applications. It contains the following:

• About this book on page 7.
About this book

This book describes how to set up Arm® Streamline on a Bare-metal target.

Using this book

This book is organized into the following chapters:

**Chapter 1 Bare-metal Support**

Describes the bare-metal support available within Arm Streamline.

**Chapter 2 Profiling with the bare-metal agent**

**Chapter 3 Profiling with Instruction Trace**

This section describes how to import an instruction trace, and restrictions related to this task.

**Chapter 4 Examples**

**Chapter 5 Fastline**

Describes the Fastline Wizard, which automates the process of profiling Fast Models with Arm Streamline.

Glossary

The Arm® Glossary is a list of terms used in Arm documentation, together with definitions for those terms. The Arm Glossary does not contain terms that are industry standard unless the Arm meaning differs from the generally accepted meaning.

See the *Arm® Glossary* for more information.

Typographic conventions

*italic*

Introduces special terminology, denotes cross-references, and citations.

**bold**

Highlights interface elements, such as menu names. Denotes signal names. Also used for terms in descriptive lists, where appropriate.

*monospace*

Denotes text that you can enter at the keyboard, such as commands, file and program names, and source code.

*monospace italic*

Denotes arguments to monospace text where the argument is to be replaced by a specific value.

*monospace bold*

Denotes language keywords when used outside example code.

<and>

Encloses replaceable terms for assembler syntax where they appear in code or code fragments. For example:

```
MRC p15, 0, <Rd>, <CRn>, <CRm>, <Opcode_2>
```
SMALL CAPITALS

Used in body text for a few terms that have specific technical meanings, that are defined in the
Arm® Glossary. For example, IMPLEMENTATION DEFINED, IMPLEMENTATION SPECIFIC, UNKNOWN, and
UNPREDICTABLE.

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• The number 101815_0702_00_en.
• If applicable, the page number(s) to which your comments refer.
• A concise explanation of your comments.

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Other information

• Arm® Developer.
• Arm® Information Center.
• Arm® Technical Support Knowledge Articles.
• Technical Support.
• Arm® Glossary.
Chapter 1
Bare-metal Support

Describes the bare-metal support available within Arm Streamline.

It contains the following section:
• 1.1 Bare-metal support overview on page 1-10.
1.1 Bare-metal support overview

Bare-metal support allows Arm Streamline to visualize elements of the system state of a target device that is running with no operating system or a light-weight real-time operating system.

For bare-metal support, you can profile your application using either of the following:

- The agent Barman.
- Instruction Trace.

Barman consists of two C source files that you build into the executable that runs on the target device. A configuration and generation utility generates these files.

To profile with Instruction Trace, import a trace of the instructions that your application executed. Arm Streamline can then analyze this trace.

Related references

2.1 Profiling with Barman on page 2-12
Chapter 3 Profiling with Instruction Trace on page 3-44
Chapter 2
Profiling with the bare-metal agent

It contains the following sections:

• 2.1 Profiling with Barman on page 2-12.
• 2.2 Data storage on page 2-13.
• 2.3 Profiling with on-target RAM buffer on page 2-14.
• 2.4 Profiling with System Trace Macrocell on page 2-20.
• 2.5 Profiling with Instrumentation Trace Macrocell on page 2-23.
• 2.6 Profiling with Embedded Trace Macrocell on page 2-26.
• 2.7 Interfacing with Barman on page 2-30.
• 2.8 Custom counters on page 2-41.
• 2.9 Using the bare-metal generation mechanism from the command line on page 2-43.
2.1 Profiling with Barman

Barman consists of two C source files, barman.c and barman.h, that you build into the executable that runs on the target device. A configuration and generation utility generates these files.

To use Barman, you must modify your existing executable to do the following:

- Initialize Barman at runtime.
- Periodically call the data collection routines that Barman provides.
- Optionally, stop the capture.
- Optionally, extract the raw data that Barman collects and provide it to Arm Streamline for analysis.

Barman has the following features:

- It captures PMU counter values from Cortex®-A and Cortex-R class processors.
- It captures sampled PC values.
- It captures custom counters.
- It allows you to control the sample rate.
- It writes the data that it collects to memory.
- It has low data collection overhead.

Barman supports the following Arm architectures:

- Armv7-A
- Armv7-R
- Armv7-M
- Armv8-A, both AArch32 and AArch64.
- Armv8-R
- Armv8-M

--- Warning ---

Barman is only intended for use in a development environment. Arm does not recommend including Barman in a released product without performing a security audit of the source code.

---

Related concepts
2.2 Data storage on page 2-13
2.7 Interfacing with Barman on page 2-30

Related references
2.3 Profiling with on-target RAM buffer on page 2-14
2.4 Profiling with System Trace Macrocell on page 2-20
2.5 Profiling with Instrumentation Trace Macrocell on page 2-23
2.6 Profiling with Embedded Trace Macrocell on page 2-26
2.2 Data storage

Barman uses a simple abstraction layer for handling the storage of collected data. Typically, the data that Barman collects is stored in a RAM buffer on the target.

You can choose from the following data storage modes provided:

**Linear RAM buffer mode**
Data collection stops when the buffer is full. This mode ensures that no collected data is lost, but no further data can be recorded.

**Circular RAM buffer mode**
Data collection continues after the buffer is full and the oldest data is lost as it is overwritten by the newest data. This mode gives you control over when the data collection ends.

**STM Interface**
System Trace Macrocell (STM) data is collected on a DSTREAM device that is connected to the target, or by another similar method. You then dump the STM trace into a host directory, which you can import into Arm Streamline for analysis.

**ITM Interface**
Instrumentation Trace Macrocell (ITM) data is collected on a DSTREAM device that is connected to the target, or by another similar method. You then dump the ITM trace into a host directory, which you can import into Arm Streamline for analysis.

**ETM Interface**
Embedded Trace Macrocell (ETM) data is collected on a DSTREAM device that is connected to the target, or by another similar method. You then dump the ETM trace into a host directory, which you can import into Arm Streamline for analysis.
2.3 Profiling with on-target RAM buffer

For Barman to be able to use either of the RAM buffer modes, you must provide the RAM buffer on the target device. The RAM buffer is a dedicated, contiguous area of RAM that Barman can write data to.

On multiprocessor systems, the RAM buffer must be at the same address for all processors. It is your responsibility to allocate memory for the RAM buffer, either statically or dynamically.

This section describes how to collect profiling data using the RAM buffer on the target device.

2.3.1 Configuring Barman

You must configure Barman with the configuration and generation utility before you compile the binary executable to be analyzed. Barman must then be built into the executable.

The configuration and generation utility is a wizard dialog available from the Streamline menu. The generated header and source files, and the configuration XML file, are then saved into a folder of your choice. The generation mechanism is also accessible from the command line.

Procedure

1. Access this utility from Streamline > Generate Barman Sources.
2. Configure the default configuration options, such as the number of processor elements, whether you intend to supply executable image memory map information, whether you intend to provide process or task level information (for example if you are running an RTOS), and configure data storage mode (linear or circular RAM buffer).

Barman uses statically allocated, fixed sized headers for information such as details of the active processors on the system, and task, thread, and process information.

Max number of mmap layout records and Max number of task information records are the maximum amount of space in the header for storing the task, thread, and process information. For
example, if you have an RTOS with a fixed number of threads, specify the number of threads here. **Max number of mmap layout records** specifies the number of address mapping entries for mapping sections of the ELF image to addresses in memory. If you have a single ELF image that is physically mapped to memory, leave this value as zero.

The **Minimum sample period** is the minimum time in nanoseconds between samples. Set this value to be an integer multiple of the timer sampling rate. For example, if you have a fixed timer interrupt operating at 1000Hz, but due to memory constraints you want to sample at 100Hz, set **Minimum sample period** to 10000000. This value ensures that there is at least 10ms between each sample.

To provide your own implementation of the memory functions for Barman, for example memcpy and memset, deselect **Enable builtin memory functions**.

---

**Note**

See **2.4 Profiling with System Trace Macrocell** on page 2-20 for information about using the **STM Interface** data storage backend.

See **2.5 Profiling with Instrumentation Trace Macrocell** on page 2-23 for information about using the **ITM Interface** data storage backend.

See **2.6 Profiling with Embedded Trace Macrocell** on page 2-26 for information about using the **ETM Interface** data storage backend.

See the gator protocol documentation in `<install_directory>/sw/streamline/protocol/gator/` for more information about pmus.xml and events.xml.

---

3. Select the target processor from the pre-defined list.

![Barman Generator Wizard](image)

![Select processors to target](image)

4. Select the PMU counters to collect during the capture session by double-clicking on them in the **Available events** list. Alternatively you can drag and drop the events into the **Selected events** list. To deselect events, drag and drop them back into the **Available events** list.
5. Add custom counters.

6. Select generator options.
7. Finish.

---

Your bare metal agent files will be generated into 'CA'.

- You selected to generate source files, you will find two files named 'barman.h' and 'barman.c' which must be compiled and linked into your program.

- You selected to save the configuration file, you will also find a file named 'barman.xml' in the same location. This file contains the configuration settings specified in this wizard, allowing you to reload, edit or recreate the source files at a later date, or with the command line tool.

By pressing the Finish button you will complete the generation process.

For more information please see the Streamline documentation.
The setup process produces the following output:

- A configuration file, `barman.xml`, which contains the settings that were entered into the configuration wizard, and which can be used to reproduce the same configuration later.
- `barman.c`. You must compile and link this file into the bare-metal executable.
- `barman.h`. You must include this header when calling any of the functions within the agent. It also declares function prototypes for the functions you must implement.
- `barman_in_memory_helpers.py`. You can use this file as a use case script in Arm Development Studio. It helps you dump the contents of the in-memory capture buffer.

You need the compiler flag `--gnu` for `armcc` (Arm Compiler 5) to compile `barman.c`.

**Related references**

2.3.3 Barman use case script on page 2-18

### 2.3.2 Extracting and importing data

You must extract the data from the RAM buffer when the capture is complete.

For example, you could choose to do one of the following:

- Save the data to the file system of the target device, if one exists.
- Retrieve the data from RAM using JTAG during a debug session.
- Transfer the data over one of the available communication interfaces, for example ethernet or USB.

After extracting the raw data, give the data file a `.raw` extension. You can import this file into Arm Streamline by clicking **Import Capture File(s)**... The imported data is then available for Arm Streamline to analyze.

If you added a custom `pmus.xml` or `events.xml` file during the configuration and generation stage, you must provide a copy of the same file into the `.apc` directory that is created for the imported capture. The files must be named `pmus.xml` and `events.xml` and must be placed in the directory alongside the `barman.raw` file for them to be detected and used.

### 2.3.3 Barman use case script

Arm Streamline generates the file `barman_in_memory_helpers.py` with the Barman agent sources when you select an in-memory data storage backend. You can use it as a use case script in Arm Development Studio to help you dump the contents of the in-memory capture buffer.

Run the script with the following command:

```
usecase run "barman_in_memory_helpers.py" <usecase_command>
```

Two use case commands are available:

- **get_parameters**
  
  Prints the current details of the buffer and information about how to dump it.

- **dump**
  
  Dumps the contents of the memory buffer in a file that you specify with the option `--file <PATH>`.

**Examples**

The following examples show how to use these use case commands.

- To use the `get_parameters` use case command, enter:

  ```
  usecase run "barman_in_memory_helpers.py" get_parameters
  ```

Output:

```
Barman memory buffer details:
Base address: 0x0000000000001580
Dump length: 1787404
Bytes written: 1785996 of 67099264 (2.7%)
```

To dump this buffer use the command:
To use the dump use case command, enter:

```
usecase run "barman_in_memory_helpers.py" dump --file <PATH>
```

Output:

```
Executing command:
  dump binary memory "barman.raw" 0x1580 +1787404
Memory successfully dumped to file barman.raw
```
2.4 Profiling with System Trace Macrocell

This section describes the collection of profiling data using System Trace Macrocell (STM).

Further information about STM, including the Technical Reference Manual, can be found on Arm Developer.

2.4.1 STM workflow

The workflow for STM involves a complex series of interactions between the applications involved.

1. Generate Barman agent code for STM using the Barman Generator Wizard dialog in Arm Streamline.
   a. Select STM Interface as the data storage backend.
   b. Specify the STM parameters for your project.
Barman reserves the channels following the channel number that you specify. The number of channels reserved is the **Maximum number of CPU cores** specified on the previous page of the wizard.

c. Complete the remainder of the wizard as for a standard bare-metal project.

---

**Note**

If you are using Arm Development Studio, you can dump the STM trace into a directory using the following command:

```
trace dump <directory> STM
```

If you do not launch your bare-metal application from within Arm Development Studio, you must handle connecting to DSTREAM, obtaining the trace file, and importing it into Arm Streamline.

---

**Related tasks**

2.3.1 Configuring Barman on page 2-14

---

### 2.4.2 Importing an STM trace

Import STM trace files into Arm Streamline for analysis.
Note
You can also import the STM trace from the command line.

Procedure
1. Click **Import Capture File(s)**… in the **Streamline Data** view.
2. Select the import file type **STM Trace Files (STPv2)**.

   ![Import Capture File(s) dialog box](image)

3. Select the trace file to import.
4. Click **Open** and a new dialog box opens.
5. Enter the location of the **barman.xml** file that the **Barman Generator Wizard** produced.
   This file contains information about how to find relevant data in the trace file. For example, the channel numbers used.
6. Click **OK**.

   Arm Streamline then reformats the data, and converts the STM trace file into a Barman agent raw file.
2.5 Profiling with Instrumentation Trace Macrocell

This section describes the collection of profiling data using Instrumentation Trace Macrocell (ITM).

2.5.1 ITM workflow

The workflow for ITM involves a complex series of interactions between the applications involved.

1. Generate Barman agent code for ITM using the Barman Generator Wizard dialog in Arm Streamline.
   a. Select ITM Interface as the data storage backend.

   ![Barman Generator Wizard](image)

   **Note**
   
   Barman uses ports 16-19 for ITM.

   b. Complete the remainder of the wizard as for a standard bare-metal project.
   c. If you selected a Cortex-M processor, select the number of cycles for the **PC sampling interval**.
2. Add the Barman agent files that the wizard generates to your project.
3. Instrument your bare-metal application code with Barman agent calls (initialization, periodic sampling).
4. Compile and link your project.
5. Connect your target to a DSTREAM device.
6. Configure your target for collecting ITM data into its RAM buffer.
7. Run the application on a target.
8. When you want to end the profiling, stop the application.
9. Dump the ITM trace from the DSTREAM device into a directory.
10. Let Arm Streamline import the trace file dump. Arm Streamline reformats it and prepares it for analysis.

Note
• If you are using Arm Development Studio, you can dump the ITM trace into a directory using the following command:

trace dump <directory> ITM
• If you do not launch your bare-metal application from within Arm Development Studio, you must handle connecting to DSTREAM, obtaining the trace file, and importing it into Arm Streamline.

Related tasks
2.3.1 Configuring Barman on page 2-14

2.5.2 Importing an ITM trace
Import ITM trace files into Arm Streamline for analysis.

Note
You can also import the ITM trace from the command line.

Procedure
1. Click Import Capture File(s)… in the Streamline Data view.
2. Select the import file type ITM Trace Files.
3. Select the trace file to import.
4. Click **Open** and a new dialog box opens.
5. Enter the location of the **barman.xml** file that the **Barman Generator Wizard** produced.
   
   This file contains information about how to find relevant data in the trace file. For example, the channel numbers used.

6. Click **OK**.

   Arm Streamline then reformats the data, and converts the ITM trace file into a Barman agent raw file.
2.6 Profiling with Embedded Trace Macrocell

This section describes the collection of profiling data using Embedded Trace Macrocell (ETM).

2.6.1 ETM workflow

The bare-metal agent can use the Data Trace feature that is provided with the ETM for streaming data from an R-class device in Arm Development Studio.

--- Note ---

The ETM interface requires ETM 3 or ETM 4 with data address tracing enabled.

---

To use ETM, generate the bare-metal agent as follows:

1. Open the Barman Generator Wizard by selecting Streamline > Generate Barman sources.
2. Select ETM interface as the data storage backend.
3. Click Finish.

To trace the device in Arm Development Studio, enable data address tracing from within the DTSL settings of your debug connection. For ETM 3, Arm Streamline supports data-only mode. You can enable data value tracing, however it is not required, and it slows execution and greatly increases the trace size.

---

![Figure 2-1 ETM3 configuration](image)

--- Note ---

Different devices have different sets of options so this dialog might vary from the image shown.

---

You must use either DSTREAM or a large in-memory trace buffer for storing the trace. If you select System Memory Trace Buffer (ETR/TMC), configure the in-memory trace buffer in the ETR tab. It is technically possible to use an on chip ETB for storing the trace, but the limited size, often less than 1KB, is not sufficient to store the capture.
Figure 2-2 Select the Trace capture method in the DTSL configuration dialog.

For ETM4, you must enable ETM tracing for all cores you are interested in collecting data from. On this tab, you can also enable data address tracing. If the **Enable ETM Timestamps** option is available, select it.
You can run the provided python script, `barman_etm_filter_script.py`, as part of the debug configuration. The Barman Generator Wizard outputs this script alongside the generated source files. Set it as the debug initialization debugger script in your target debug configuration in Arm Development Studio. In the Debug Configurations dialog, click the Debugger tab, and enter the location of the script in the Run debug initialization debugger script field. This script limits tracing to the part of the bare-metal agent that sends the data. This limitation prevents you from getting the instruction trace, but reducing the amount of trace data in this way leads to smaller captures, faster imports, and the possibility to capture traces for longer. If you use ETM 4, Arm strongly recommends that you run this script. ETM 4 imports are much slower than ETM 3 imports. Limiting the trace data reduces the import time.

Use the following command to dump the ETM trace data:

```
trace dump <OUTPUT> <ETM_SOURCES>
```

Import this trace data into Arm Streamline using the import button, or using the `-import-etm-dt` command-line option, in the same way as for STM and ITM.

**Related information**
- Arm debug and trace architecture
- ETM3 Architecture Specification
- ETM4 Architecture Specification
- Debug and Trace Services Layer (DTSL)
2 Profiling with the bare-metal agent
2.6 Profiling with Embedded Trace Macrocell

DTSL Configuration Editor dialog box
2.7 Interfacing with Barman

When Barman is linked into your executable code, the code must call the following functions:

1. `barman_initialize` to initialize Barman.
2. `barman_enable_sampling` to enable sampling.
3. The appropriate sample function, `barman_sample_counters` or `barman_sample_counters_with_program_counter`, to periodically collect data.

In a multiprocessor system, a call to one of the sampling functions only reads the counters for the processor element the code is currently executing on.

If you are running a preemptive kernel, RTOS, or similar, you must ensure that the thread running a call to a sampling function is not migrated from one processor element to another during the execution of the call.

In a multiprocessor system, if you are using periodic sampling (for example with a timer interrupt), you must provide a mechanism to call the sampling function for each processor element. In other words, to capture the counters of each processor element, there must be a timer interrupt or thread that is run separately on each processor element.

2.7.1 Configuration #defines

The following defines are configured by the configuration UI and stored in `barman.h`. They can be overridden at compile time as compiler parameters.

<table>
<thead>
<tr>
<th>Define</th>
<th>Description</th>
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<tr>
<td>BM_CONFIG_ENABLE_LOGGING</td>
<td>Enables logging of messages when set to true.</td>
</tr>
<tr>
<td>BM_CONFIG_ENABLE_DEBUG_LOGGING</td>
<td>If <code>BM_CONFIG_ENABLE_LOGGING</code> is true, enables debug messages when set to true.</td>
</tr>
<tr>
<td>BM_CONFIG_ENABLE_BUILTIN_MEMFUNCS</td>
<td>Enables the use of built-in memory functions such as <code>__builtin_memset</code> and <code>__builtin_memcpy</code> when set to true.</td>
</tr>
<tr>
<td>BM_CONFIG_MAX_CORES</td>
<td>The maximum number of processor elements supported.</td>
</tr>
<tr>
<td>BM_CONFIG_MAX_MMAP_LAYOUTS</td>
<td>The maximum number of <code>mmap</code> layout entries to be stored in the data header. Configure to reflect the number of sections to be mapped for any process images.</td>
</tr>
<tr>
<td>BM_CONFIG_MAX_TASK_INFOS</td>
<td>The maximum number of distinct task entries that will be stored in the data. For single-threaded applications, this can be defined as zero to indicate that no information is provided. For multi-threaded applications or RTOS, this value indicates the maximum number of entries to store in the data header for describing processes, threads, and tasks.</td>
</tr>
<tr>
<td>BM_CONFIG_MIN_SAMPLE_PERIOD</td>
<td>The minimum period between samples in nanoseconds. If this value is greater than zero, calls to sampling functions are rate limited to ensure that there is a minimum interval of nanoseconds between samples.</td>
</tr>
<tr>
<td>BARMAN_DISABLED</td>
<td>Disables the Barman entry points at compile time when defined to a nonzero value. Use to conditionally disable calls to Barman, for example in production code.</td>
</tr>
</tbody>
</table>

2.7.2 Annotation #defines

Color macros to use for annotations.
<table>
<thead>
<tr>
<th>Define</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>BM_ANNOTATE_COLOR_&lt;color_name&gt;</td>
<td>Named annotation color, where &lt;color_name&gt; is one of the following colors:</td>
</tr>
<tr>
<td></td>
<td>RED</td>
</tr>
<tr>
<td></td>
<td>BLUE</td>
</tr>
<tr>
<td></td>
<td>GREEN</td>
</tr>
<tr>
<td></td>
<td>PURPLE</td>
</tr>
<tr>
<td></td>
<td>YELLOW</td>
</tr>
<tr>
<td></td>
<td>CYAN</td>
</tr>
<tr>
<td></td>
<td>WHITE</td>
</tr>
<tr>
<td></td>
<td>LTGRAY</td>
</tr>
<tr>
<td></td>
<td>DKGRAY</td>
</tr>
<tr>
<td></td>
<td>BLACK</td>
</tr>
<tr>
<td>BM_ANNOTATE_COLOR_CYCLIC</td>
<td>Annotation color that cycles through a predefined set.</td>
</tr>
<tr>
<td>BM_ANNOTATE_COLOR_RGB(&lt;R&gt;, &lt;G&gt;, &lt;B&gt;)</td>
<td>Create an annotation color from its components, where &lt;R&gt;, &lt;G&gt;, and &lt;B&gt; are</td>
</tr>
<tr>
<td></td>
<td>defined as follows:</td>
</tr>
<tr>
<td></td>
<td>R</td>
</tr>
<tr>
<td></td>
<td>The red component, where 0 ≤ R ≤ 255.</td>
</tr>
<tr>
<td></td>
<td>B</td>
</tr>
<tr>
<td></td>
<td>The blue component, where 0 ≤ B ≤ 255.</td>
</tr>
<tr>
<td></td>
<td>G</td>
</tr>
<tr>
<td></td>
<td>The green component, where 0 ≤ G ≤ 255.</td>
</tr>
</tbody>
</table>

### 2.7.3 Barman public API

Call the following public API functions to use the bare-metal agent.

**barman_initialize**

The prototype of barman_initialize varies depending on the datastore chosen.

When using the linear or circular RAM buffer:

```c
BM_NONNULL((1, 3, 4))
bm_bool barman_initialize(bm_uint8 * buffer, bm_uintptr buffer_length,
```

When using STM:

```c
BM_NONNULL((2, 3, 4))
bm_bool barman_initialize_with_stm_interface(void * stm_configuration_registers,
```

When using ITM on Arm M-profile architectures:

```c
BM_NONNULL((1, 2))
bm_bool barman_initialize_with_itm_interface(
```

When using ITM on Arm A- or R-profile architectures:

```c
BM_NONNULL((1, 2, 3))
bm_bool barman_initialize_with_itm_interface(void * itm_registers,
```

The remaining parameters for each datastore are the same:

```c
const char * target_name,
const struct bm_protocol_clock_info * clock_info,
#if BM_CONFIG_MAX_TASK_INFOS > 0
    bm_uint32 num_task_entries,
    const struct bm_protocol_task_info * task_entries,
#endif
#if BM_CONFIG_MAX_MMAP_LAYOUTS > 0
    bm_uint32 num_mmap_entries,
    const struct bm_protocol_mmap_layout * mmap_entries,
#endif
    bm_uint32 timer_sample_rate);
```
## Initialize Barman

### Parameters

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>buffer</td>
<td>Pointer to in memory buffer.</td>
</tr>
<tr>
<td>buffer_length</td>
<td>Length of the in memory buffer.</td>
</tr>
<tr>
<td>stm_configuration_registers</td>
<td>Base address of the STM configuration registers. This parameter can be NULL if it will be initialized elsewhere, for example by the debugger.</td>
</tr>
<tr>
<td>stm_extended_stimulus_ports</td>
<td>Base address of the STM extended stimulus ports.</td>
</tr>
<tr>
<td>itm_registers</td>
<td>Base address of the ITM registers.</td>
</tr>
<tr>
<td>datastore_config</td>
<td>Pointer to the configuration to pass to barman_ext_datastore_initialize.</td>
</tr>
<tr>
<td>target_name</td>
<td>Name of the target device.</td>
</tr>
<tr>
<td>clock_info</td>
<td>Information about the monotonic clock used for timestamps.</td>
</tr>
<tr>
<td>num_task_entries</td>
<td>Length of the array of task entries in task_entries. If this value is greater than BM_CONFIG_MAX_TASK_INFOS, it is truncated.</td>
</tr>
<tr>
<td>task_entries</td>
<td>The task information descriptors. Can be NULL.</td>
</tr>
<tr>
<td>num_mmap_entries</td>
<td>The length of the array of mmap entries in mmap_entries. If this value is greater than BM_CONFIG_MAX_MMAP_LAYOUT, it is truncated.</td>
</tr>
<tr>
<td>mmap_entries</td>
<td>The mmap image layout descriptors. Can be NULL.</td>
</tr>
<tr>
<td>timer_sample_rate</td>
<td>Timer based sampling rate in Hz. Zero indicates no timer based sampling (assumes max. 4GHz sample rate). This value is informative only, and is used for reporting the timer frequency in the Arm Streamline UI.</td>
</tr>
</tbody>
</table>

### Return value

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>BM_TRUE</td>
<td>On success.</td>
</tr>
<tr>
<td>BM_FALSE</td>
<td>On failure.</td>
</tr>
</tbody>
</table>

---

**Note**

If BM_CONFIG_MAX_TASK_INFOS ≤ 0, num_task_entries and task_entries are not present.

If BM_CONFIG_MAX_MMAP_LAYOUTS ≤ 0, num_mmap_entries and mmap_entries are not present.

---

### barman_enable_sampling

```c
void barman_enable_sampling(void);
```

**Description**

Enables sampling. Call once all PMUs are enabled and the data store is configured.

### barman_disable_sampling

```c
void barman_disable_sampling(void);
```

**Description**

Disables sampling without reconfiguring the PMU. Sampling can be resumed by a call to barman_enable_sampling.
### barman_sample_counters

```c
void barman_sample_counters(bm_bool sample_return_address);
```

**Description**
Reads the configured PMU counters for the current processing element and inserts them into the data store. Can also insert a program counter record using the return address as the PC sample.

**Parameter**
- `sample_return_address`
  - `BM_TRUE` to sample the return address as PC,
  - `BM_FALSE` to ignore.

---

#### Note
- The **Call Paths** view displays the PC values. This view is blank if the application does not call `barman_sample_counters` with `sample_return_address == BM_TRUE`, or `barman_sample_counters_with_program_counter` with `pc != BM_NULL`
- Application code that is not doing periodic sampling typically calls this function with `sample_return_address == BM_TRUE`.
- This function must be run on the processing element for the PMU that it intends to sample from, and it must not be migrated to another processing element for the duration of the call. This is necessary as it needs to program the per processing element PMU registers.

### barman_sample_counters_with_program_counter

```c
void barman_sample_counters_with_program_counter(const void * pc);
```

**Description**
Reads the configured PMU counters for the current processing element and inserts them into the data store.

**Parameter**
- `pc`
  - The PC value to record. The PC entry is not inserted if `pc == BM_NULL`.

---

#### Note
- The **Call Paths** view displays the PC values. This view is blank if the application does not call `barman_sample_counters_with_program_counter` with `pc != BM_NULL`, or `barman_sample_counters` with `sample_return_address == BM_TRUE`.
- A periodic interrupt handler typically calls this function, with `pc == <the_exception_return_address>`.
- This function must be run on the processing element for the PMU that it intends to sample from, and it must not be migrated to another processing element for the duration of the call. This is necessary as it will need to program the per processing element PMU registers.

---

The following functions are available if `BM_CONFIG_MAX_TASK_INFOS > 0`:

### barman_add_task_record

```c
bm_bool barman_add_task_record(bm_uint64 timestamp, const struct bm_protocol_task_info * task_entry);
```

**Description**
Adds a new task information record.

**Parameters**
- `timestamp`
  - The timestamp at which the record is inserted.
- `task_entry`
  - The new task entry.

**Return value**
- `BM_TRUE` on success.
- `BM_FALSE` on failure.
**barman_record_task_switch**

```c
void barman_record_task_switch(enum bm_task_switch_reason reason);
```

**Description**
Records that a task switch has occurred. Call this function after the new task is made the current task, such that a call to `barman_ext_get_current_task_id` would return the new task ID. For example, insert it into the scheduler of an RTOS just after the new task is selected to record the task switch.

**Parameter**
- `reason`
  Reason for the task switch.

---

**Note**
Call after the task switch has occurred so that `bm_ext_get_current_task` returns the `task_id` of the switched to task.

---

The following function is available if `BM_CONFIG_MAX_MMAP_LAYOUTS > 0`:

**barman_add_mmap_record**

```c
bm_bool barman_add_mmap_record(bm_uint64 timestamp, const struct bm_protocol_mmap_layout * mmap_entry);
```

**Description**
Adds a new `mmap` information record.

**Parameters**
- `timestamp`
  The timestamp at which the record is inserted.
- `mmap_entry`
  The new `mmap` entry.

**Return value**
- **BM_TRUE**
  On success.
- **BM_FALSE**
  On failure.

---

Data types associated with the public API functions:

**bm_protocol_clock_info**

```c
struct bm_protocol_clock_info
{
    bm_uint64 timestamp_base;
    bm_uint64 timestamp_multiplier;
    bm_uint64 timestamp_divisor;
    bm_uint64 unix_base_ns;
};
```
Defines information about the monotonic clock used in the trace. Timestamp information is stored in arbitrary units within samples. This reduces the overhead of making the trace by removing the need to transform the timestamp into nanoseconds at the point the sample is recorded. The host expects timestamps to be in nanoseconds. The arbitrary timestamp information is transformed to nanoseconds according to the following formula:

\[
bm\_uint64\ \text{nanoseconds} = (((\text{timestamp} - \text{timestamp\_base}) \times \text{timestamp\_multiplier}) / \text{timestamp\_divisor})
\]

Therefore for a clock that already returns time in nanoseconds, \text{timestamp\_multiplier} and \text{timestamp\_divisor} should be configured as 1 and 1. If the clock counts in microseconds then the multiplier and divisor should be set to 1000 and 1. If the clock counts at a rate of \(n\) Hertz, then the multiplier should be set to 1000000000 and the divisor to \(n\).

### Members

- **timestamp\_base**
  - The base value of the timestamp such that this value is zero in the trace.
- **timestamp\_multiplier**
  - The clock rate ratio multiplier.
- **timestamp\_divisor**
  - The clock rate ratio divisor.
- **unix\_base\_ns**
  - The unix timestamp base value, in nanoseconds, such that a \text{timestamp\_base} maps to a \text{unix\_base} unix time value.

---

#### bm\_protocol\_task\_info

```c
struct bm_protocol_task_info
{
    bm_task_id_t task_id;
    const char * task_name;
};
```

**Description**

A task information record. Describes information about a unique task within the system.

**Members**

- **task_id**
  - The task ID.
- **task_name**
  - The name of the task.

---

#### bm\_protocol\_mmap\_layout

```c
struct bm_protocol_mmap_layout
{
    #if BM_CONFIG_MAX_TASK_INFOS > 0
    bm_task_id_t task_id;
    #endif
    bm_uintptr base_address;
    bm_uintptr length;
    bm_uintptr image_offset;
    const char * image_name;
};
```

**Description**

An MMAP layout record. Describes the position of an executable image (or section thereof) in memory, allowing the host to map PC values to the appropriate executable image.

**Members**

- **task_id**
  - The task ID to associate with the map.
- **base_address**
  - The base address of the image, or image section.
- **length**
  - The length of the image, or image section.
- **image_offset**
  - The image section offset.
- **image_name**
  - The name of the image.
**bm_task_switch_reason**

```c
enum bm_task_switch_reason {
    BM_TASK_SWITCH_REASON_PREEMPTED = 0,
    BM_TASK_SWITCH_REASON_WAIT = 1
};
```

<table>
<thead>
<tr>
<th>Description</th>
<th>Reason for a task switch.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Members</td>
<td></td>
</tr>
<tr>
<td></td>
<td>BM_TASK_SWITCH_REASON_PREEMPTED</td>
</tr>
<tr>
<td></td>
<td>Thread is preempted.</td>
</tr>
<tr>
<td></td>
<td>BM_TASK_SWITCH_REASON_WAIT</td>
</tr>
<tr>
<td></td>
<td>Thread is blocked waiting, for example on IO.</td>
</tr>
</tbody>
</table>

WFI/WFE event handling functions:

**barman_wfi**

```c
void barman_wfi(void);
```

| Description | Wraps WFI instruction and sends events before and after the WFI to log the time in WFI. This function is safe to use in place of the usual WFI `asm` instruction, as it degenerates to just a WFI instruction when Barman is disabled. |

**barman_wfe**

```c
void barman_wfe(void);
```

| Description | Wraps WFE instruction and sends events before and after the WFE to log the time in WFE. This function is safe to use in place of the usual WFE `asm` instruction as it degenerates to just a WFE instruction when Barman is disabled. |

**barman_before_idle**

```c
void barman_before_idle(void);
```

| Description | Call before a WFI/WFE, or other similar halting event, to log entry into the paused state. Can be used in situations where `barman_wfi()`/`barman_wfe()` is not suitable. |

**Note**

- You must use `barman_before_idle` in a pair with `barman_after_idle()`.  
- Using `barman_wfi()`/`barman_wfe()` is preferred in most cases, as it takes care of calling the before and after functions.

**barman_after_idle**

```c
void barman_after_idle(void);
```

| Description | Call after a WFI/WFE, or other similar halting event, to log exit from the paused state. Can be used in situations where `barman_wfi()`/`barman_wfe()` is not suitable. |

**Note**

- You must use `barman_after_idle` in a pair with `barman_before_idle()`.  
- Using `barman_wfi()`/`barman_wfe()` is preferred in most cases, as it takes care of calling the before and after functions.

Functions for recording textual annotations:

**barman_annotate_channel**

```c
void barman_annotate_channel(bm_uint32 channel, bm_uint32 color, const char * string)
```
<table>
<thead>
<tr>
<th>Description</th>
<th>Adds a string annotation with a display color, and assigns it to a channel.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Parameters</td>
<td>channel</td>
</tr>
<tr>
<td></td>
<td>The channel number.</td>
</tr>
<tr>
<td></td>
<td>color</td>
</tr>
<tr>
<td></td>
<td>The annotation color from bm_annotation_colors.</td>
</tr>
<tr>
<td></td>
<td>text</td>
</tr>
<tr>
<td></td>
<td>The annotation text, or null to end the previous annotation.</td>
</tr>
</tbody>
</table>

--- Note ---

Annotation channels and groups are used to organize annotations within the threads and processes section of the **Timeline** view. Each annotation channel appears in its own row under the thread. Channels can also be grouped and displayed under a group name, using the `barman_annotate_name_group` function.

**barman_annotate_name_channel**

```c
void barman_annotate_name_channel(bm_uint32 channel, bm_uint32 group, const char * name)
```

<table>
<thead>
<tr>
<th>Description</th>
<th>Defines a channel and attaches it to an existing group.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Parameters</td>
<td>channel</td>
</tr>
<tr>
<td></td>
<td>The channel number.</td>
</tr>
<tr>
<td></td>
<td>group</td>
</tr>
<tr>
<td></td>
<td>The group number.</td>
</tr>
<tr>
<td></td>
<td>name</td>
</tr>
<tr>
<td></td>
<td>The name of the channel.</td>
</tr>
</tbody>
</table>

--- Note ---

The channel number must be unique within the task.

**barman_annotate_name_group**

```c
void barman_annotate_name_group(bm_uint32 group, const char * name)
```

<table>
<thead>
<tr>
<th>Description</th>
<th>Defines an annotation group.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Parameters</td>
<td>group</td>
</tr>
<tr>
<td></td>
<td>The group number.</td>
</tr>
<tr>
<td></td>
<td>name</td>
</tr>
<tr>
<td></td>
<td>The name of the group.</td>
</tr>
</tbody>
</table>

--- Note ---

The group identifier, group, must be unique within the task.

**barman_annotate_marker**

```c
void barman_annotate_marker(bm_uint32 color, const char * text)
```
| Description | Adds a bookmark with a string and a color to the **Timeline** and **Log** views. The string is displayed in the **Timeline** view when you hover over the bookmark, and in the **Message** column in the **Log** view. |
| Parameters | **color**  
The marker color from `bm_annotation_colors`.  
**text**  
The marker text, or null for no text. |

**bm_annotation_colors**

| Description | Color macros for annotations. See 2.7.2 Annotation #defines on page 2-30. |

### 2.7.4 External functions to implement

You must provide the following external functions.

#### barman_ext_get_timestamp

```c
extern bm_uint64 barman_ext_get_timestamp(void);
```

| Description | Reads the current sample timestamp value, which must be provided for the time at the point of the call. The timer must provide monotonically incrementing values from an implementation defined start point. The counter must not overflow during the period that it is used. The counter is in arbitrary units. The mechanism for converting those units to nanoseconds is described as part of the protocol data header. |
| Return value | The timestamp value in arbitrary units. |

The following functions have weak linkage implementations that can be overridden if necessary:

#### barman_ext_disable_interrupts_local

```c
extern bm_uintptr barman_ext_disable_interrupts_local(void);
```

| Description | Disables interrupts on the local processor only. Used to allow atomic accesses to certain resources, for example PMU counters. |
| Return value | The current interrupt enablement status value. This value must be preserved and passed to `barman_ext_enable_interrupts_local` to restore the previous state. |

---

**Note**

A weak implementation of this function is provided that modifies DAIF on AArch64, or CPSR on AArch32.

---

#### barman_ext_enable_interrupts_local

```c
extern void barman_ext_enable_interrupts_local(bm_uintptr previous_state);
```

| Description | Enables interrupts on the local processor only. |
| Parameter | previous_state  
The value that was previously returned from `barman_ext_disable_interrupts_local` |

---

**Note**

A weak implementation of this function is provided that modifies DAIF on AArch64, or CPSR on AArch32.

---

The following functions must be defined if `BM_CONFIG_MAX_CORES > 1`: 

---

**Non-Confidential**
### barman_ext_map_multiprocessor_affinity_to_core_no

```c
extern bm_uint32 barman_ext_map_multiprocessor_affinity_to_core_no(bm_uintptr mpidr);
```

**Description**

Given the MPIDR register, returns a unique processor number. The implementation must return a value between 0 and \( N \), where \( N \) is the maximum number of processors in the system. For any valid permutation of the arguments, a unique value must be returned. This value must not change between successive calls to this function for the same argument values.

```c
//
// Example implementation where processors are arranged as follows:
//
// aff2 | aff1 | aff0 | cpuno
// ---+-----+-----+-------
//  0  | 0   | 0   |  0
//  0  | 0   | 1   |  1
//  0  | 0   | 2   |  2
//  0  | 0   | 3   |  3
//  0  | 1   | 0   |  4
//  0  | 1   | 1   |  5
//
bm_uint32 barman_ext_map_multiprocessor_affinity_to_core_no(bm_uintptr mpidr)
{
    return (mpidr & 0x03) + ((mpidr >> 6) & 0x4);
}
```

**Parameter**

- **mpidr**
  
  The value of the MPIDR register.

**Return value**

The processor number.

---

**Note**

This function need only be defined when `BM_CONFIG_MAX_CORES > 1`

### barman_ext_map_multiprocessor_affinity_to_cluster_no

```c
extern bm_uint32 barman_ext_map_multiprocessor_affinity_to_cluster_no(bm_uintptr mpidr);
```

**Description**

Given the MPIDR register, return the appropriate cluster number. Cluster IDs should be numbered from 0 to \( N \), where \( N \) is the number of clusters in the system.

```c
//
// Example implementation which is compatible with the example implementation of
// barman_ext_map_multiprocessor_affinity_to_core_no given above.
//
bm_uint32 barman_ext_map_multiprocessor_affinity_to_cluster_no(bm_uintptr mpidr)
{
    return ((mpidr >> 8) & 0x1);
}
```

**Parameter**

- **mpidr**
  
  The value of the MPIDR register.

**Return value**

The cluster number.

---

**Note**

This function need only be defined when `BM_CONFIG_MAX_CORES > 1`

---

The following function must be defined if `BM_CONFIG_MAX_TASK_INFOS > 0`:

### barman_ext_get_current_task_id

```c
extern bm_task_id_t barman_ext_get_current_task_id(void);
```

**Description**

Returns the current task ID.
The following functions must be defined if `BM_CONFIG_ENABLE_LOGGING != 0`:

**barman_ext_log_info**

```c
void barman_ext_log_info(const char * message, ...);
```

<table>
<thead>
<tr>
<th>Description</th>
<th>Prints an info message.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Parameter</td>
<td>message</td>
</tr>
</tbody>
</table>

**barman_ext_log_warning**

```c
void barman_ext_log_warning(const char * message, ...);
```

<table>
<thead>
<tr>
<th>Description</th>
<th>Prints a warning message.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Parameter</td>
<td>message</td>
</tr>
</tbody>
</table>

**barman_ext_log_error**

```c
void barman_ext_log_error(const char * message, ...);
```

<table>
<thead>
<tr>
<th>Description</th>
<th>Prints an error message.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Parameter</td>
<td>message</td>
</tr>
</tbody>
</table>

The following function must be defined if `BM_CONFIG_ENABLE_DEBUG_LOGGING != 0`:

**barman_ext_log_debug**

```c
void barman_ext_log_debug(const char * message, ...);
```

<table>
<thead>
<tr>
<th>Description</th>
<th>Prints a debug message.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Parameter</td>
<td>message</td>
</tr>
</tbody>
</table>
2.8 Custom counters

You can configure one custom chart, with one or more series, in the configuration wizard.

2.8.1 Configuring custom counters

You can configure chart properties for custom counters.

The following chart properties can be configured:

Name
Human readable name for the chart.

Series Composition
Defines how to arrange series on the chart (stacked, overlay, or logarithmic).

Rendering Type
Defines how to render series on the chart (filled, line, or bar).

Per Processor
Indicates whether the data in the chart is per processor.

Average Selection
Sets whether the Cross Section Marker in Arm Streamline displays average values.

Average Cores
Sets whether Arm Streamline averages the values of multiple cores when viewing the aggregate data of a per processor chart.

Percentage
Sets whether to display data as a percentage of the maximum value in the chart.

The following series properties can be configured:

Name
Human readable name for the series.

Units
Defines the unit type to display in Arm Streamline.

Sampled
When set to true, the value for this counter is sampled along with the PMU counters. When false, you must call a function to update the counter value.

Multiplier
Number to multiply by for fixed-point math. As the data sent from the agent is int64, it must be scaled. For example, the value 1.23 can be represented by the value 123 with a multiplier of 0.01.

Class
Specifies the nature of the data that is fed into the chart as follows:

delta
Used for values that increment or are accumulated over time, such as hardware performance counters. The exact time when the data occurs is unknown and therefore the data is interpolated between timestamps.

incident
The same as delta, except the exact time is known so no interpolation is calculated. Used for counters such as software trace.

absolute
Used for singular or impulse values, such as system memory used.
The display value determines how to calculate the data when zooming out for each time bin as follows:

**accumulate**
Sum up the data (valid only for delta and incident class counters).

**hertz**
Does the same as accumulate then normalizes the value to one second (valid only for delta and incident class counters).

**minimum**
Display the smallest value encountered (valid only for absolute class counters).

**maximum**
Display the largest value encountered (valid only for absolute class counters).

**average**
Display the average (valid only for absolute class counters).

**Color**
The color to display the series in. If not set, Arm Streamline selects a color.

**Description**
Human readable description for the series. This description becomes the tooltip when hovering over the series in Arm Streamline.

### 2.8.2 Sampled and nonsampled counters

Sampled counters are polled when the PMU counter values are read.

For each sampled custom counter, a function prototype is generated of the following form:

```c
extern bm_bool barman_cc_<chart_name>_<series_name>_sample_now(bm_uint64 * value_out);
```

For example:

```c
extern bm_bool barman_cc_interrupts_fiq_sample_now(bm_uint64 * value_out);
```

You must implement this function to set the value of the `uint64` at `*value_out` to the value of the counter, then return `BM_TRUE`. If the counter value cannot be sampled, for example due to another thread accessing the hardware, the function can return `BM_FALSE` and be skipped.

You are responsible for writing nonsampled counters to the capture. For each nonsampled series, the following two functions are declared:

```c
bm_bool barman_cc_<chart_name>_<series_name>_update_value(bm_uint64 timestamp, bm_uint32 core, bm_uint64 value);
bm_bool barman_cc_<chart_name>_<series_name>_update_value_now(bm_uint64 value);
```

For example:

```c
bm_bool barman_cc_interrupts_fiq_update_value(bm_uint64 timestamp, bm_uint32 core, bm_uint64 value);
```

The second function is a shorthand for the first that passes the current timestamp and core number to the appropriate arguments.

When you call these functions, the value for the counter is stored to the capture.
2.9 Using the bare-metal generation mechanism from the command line

You can pass the configured, and optionally modified, XML file produced in the bare-metal configuration process to the command line. The generator then outputs the source and header files.

Enter `streamline -generate-bare-metal-agent <options>`

The following command-line arguments are available:

- `-c`, `-config <config.xml>`
  The configuration file to use to generate the bare-metal agent.

- `-p`, `-pmus <pmus.xml>`
  Specify the path to your `pmus.xml` file.

- `-e`, `-events <events.xml>`
  Specify the path to your `events.xml` file.

- `-o`, `-output <output_path>`
  Specify the output path to where the generated files will be written.

Related information

Arm Streamline command-line options
Chapter 3
Profiling with Instruction Trace

This section describes how to import an instruction trace, and restrictions related to this task.

It contains the following sections:

• 3.1 Importing instruction trace on page 3-45.
• 3.2 Instruction trace notes and restrictions on page 3-48.
3.1 Importing instruction trace

Import a trace of the instructions that your application executed for Arm Streamline to analyze. The supported forms of instruction trace are PTM 1.0-1.1, ETM 3.0-3.5, and ETM 4.0-4.2.

Prerequisites

1. Collect the instruction trace for your application using Arm DS Debugger. See the Arm DS Debugger User Guide for instructions.
2. Export the instruction trace using the following command:

   `trace dump <output> <instruction_trace_sources>`

   __________ Note __________

   `<instruction_trace_sources>` must only specify valid ETM sources. For example, CSETM_APP_0.

Procedure

1. Click **Import Capture File(s)**…
2. Navigate to the directory that contains the trace dump.
3. Select any of the files in the directory.
   A wizard opens, enabling you to choose what to do with the import.
4. Select **Instruction Trace**.

5. Select the sources to import, and specify the timing information for them.

![Figure 3-1  Select Instruction Trace.](image)
6. Select the executable images that were run.

Arm Streamline uses these files to decode the trace.

7. Configure parameters for the capture that Arm Streamline generates from the trace.
Arm Streamline reads the instruction trace and generates a capture from it. The generated capture contains the following:

- Charts that give approximate information about branching, instructions, load/stores, and exceptions.
- **Call Paths** and **Functions** views that Arm Streamline derives from the instruction trace.
- Optionally, the **Exceptions** view, which shows the exceptions that were taken.

**Related information**
- Configuring trace for bare-metal or Linux kernel targets
- Capturing trace data using the command-line debugger
3.2 Instruction trace notes and restrictions

There are some restrictions to instruction traces.

- Dynamic compilation/code modification is not supported. If the modification happens before the code is traced, and you supply an ELF image containing the executable code after modification, Arm Streamline can support one-off runtime code modification. You can use the Arm Development Studio memory dump command, specifying the ELF output format.
- You must specify whether the imported files are M-profile, otherwise interrupts are not shown correctly. This does not usually affect the import of the trace, just the output.
- The **Call Paths** view tracks function entry and exit instructions, and attempts to track state across interrupts even when simple context switching is used. This functionality may not be compatible with a more complex OS.

Arm Streamline generates timing information from the trace in one of the following ways:

- Using timestamps, if they are included in all the relevant trace streams.
  - Use this method if it is available, especially if you are importing streams from more than one processing element.
  - Timestamps give a near-accurate representation of the relative times of different events. The accuracy of the timing information depends on the relative frequency of timestamp packets within each trace stream.
  - Timestamps allow showing periods of inactivity such as during WFE/WFI.
  - Timestamps are usually clocked using a separate clock to the processor. Arm recommends that you enter the duration of the capture rather than the clock frequency for the timestamp clock, unless you know the exact frequency.
- Using cycle counts, if cycle-accurate mode is enabled for all relevant trace streams.
  - Use this mode if timestamps are not available as it gives better relative timing information between different instructions in the trace.
  - Timing information is not synchronized across different processing elements.
  - Unless the cycle counter increments during WFE/WFI instructions, it is not possible to see how long the processor waited for.
  - Systems using dynamic frequency scaling are not clocked correctly because the cycle count for individual instructions does not change with the clock frequency.
- Using the instruction counter.
  - The only mode that is universally available.
  - This mode has all the same limitations as the cycle counter mode.
  - This mode cannot display relative timing information for different instructions.
Chapter 4
Examples

It contains the following section:

• 4.1 Examples using Barman on page 4-50.
4.1 Examples using Barman

See <install_directory>/sw/streamline/examples/barman for the following Barman examples:

**Streamline_bare_metal_ARMv8_AArch64**
A demonstration of how to use Barman with AArch64, from configuring the bare-metal agent to analyzing the results.

**Streamline_bare_metal_Cortex_R5**
A demonstration of how to use Barman with Arm Cortex-R5, from configuring the bare-metal agent to analyzing the results.

**Streamline_bare_metal_M_profile**
A demonstration of how to use Barman with Armv7-M and Armv8-M, from configuring the bare-metal agent to analyzing the results.

**u-boot-instrumentation**
An example of how to modify U-Boot to allow it to be profiled using Barman.
Chapter 5
Fastline

Describes the Fastline Wizard, which automates the process of profiling Fast Models with Arm Streamline.

It contains the following sections:

- 5.1 Fastline overview on page 5-52.
- 5.2 Fastline Wizard on page 5-53.
5.1 Fastline overview

Fastline is a plug-in for profiling Linux systems and applications, and bare-metal applications, running on Fast Models. The Fastline Wizard in Arm Streamline automates the process of configuring the plug-in.

The wizard produces one of the following outputs, depending on the options you select:
• An APC capture that Arm Streamline analyzes and opens as a report.
• A launching script and a set of configuration files for the Fastline plug-in that you can run later.

The Fastline wizard is a separate Eclipse plug-in called com.arm.streamline.fastlinewizard. You can install it in Eclipse separately from Arm Streamline without losing any functionality.

**Related information**

*Fastline in the Fast Models Reference Manual*
5.2 Fastline Wizard

The following procedure shows you how to complete the Fastline Wizard in Arm Streamline. You choose whether to start Fastline at the end of the wizard, or generate a launching script to run later.

Prerequisites

• Ensure that you have Fast Models version 11.1.
• Select Window > Preferences > Fastline Preferences. Enter the locations of the Executables Directory and the Plugins Directory, or browse for them in your filesystem. The Plugins Directory must contain FastlineTrace.dll and FastlineTrace_counter_defaults.json.
• Ensure that you have the correct licenses for Fast Models and Arm Streamline.
• For Linux systems, you need the following:
  — The Linux kernel sources that are used for Linux image compilation.
  — System.map, which the kernel build produces.
  — The .config file that the kernel build produces.
  — The vmlinuz image that the kernel build produces, with the debug information sections.
  — The PAGE_SHIFT parameter that is used.
  — Whether the OS architecture of the compiled kernel is a 32-bit or a 64-bit architecture.
  — The bootloader, RAMDisk, filesystem, device tree, and other binaries for booting Linux on Fast Models.
  — The command-line arguments to make the model load and run Linux.
• For bare-metal applications, you need the compiled ELF image with the application, symbols, and debug information in it.

Procedure

1. Select Streamline > Fastline Wizard to open the Fastline Wizard dialog.

2. Select one model to use. The wizard lists the models in the specified directory, and models provided with Arm Development Studio in sw/models/bin.
3. Optionally enter extra command-line arguments for the executable in the text field at the bottom of the dialog.

4. Click Next.

5. If the Fast Models executable cannot find the license, the wizard requests this information. Enter your license information.

6. Click Validate.

   If your license information is valid, you can progress. Otherwise, the wizard displays an error message and you cannot continue.

7. Click Next.

8. Right-click in the System Type column for each core, and select the corresponding system type from the drop-down list. The possible values are Linux, Bare Metal, and Not Used.

   The wizard supports running the following configurations:
   - One Linux system.
   - One bare-metal application.
   - One Linux system and one bare-metal application.

   By default, the wizard selects Linux for A-class processors, and Bare Metal for M- and R-class processors.

9. Click Next.

10. Provide the extra information that is required for the selected system type.

    - For Linux systems, enter the location of the following items:
      - vmlinux.o
      - System.map
      - PAGE_SHIFT Value

      You must also select whether the system is 32-bit or 64-bit.

      Enter this information manually or, to automatically complete these fields, click Scan Linux Source Tree… If you use the autoscan function, enter the location of the Linux source tree when
prompted. The wizard scans this location for the required files and displays warning messages for any it cannot find.

Figure 5-3 Enter the Linux information.

- For bare-metal applications, enter the location of the program image ELF file.

Figure 5-4 Enter the ELF file location.

11. Click Next.
12. Select counters from the list of data sources for the system. Click **Add** to add them to the list of counters to be profiled.

The Basic Mode list contains counters that have the complete set of properties that are required for JSON counter configuration.

The Advanced Mode list contains all the counters. You must specify any information missing from the JSON counter configuration to be able to use the counters on this list. A dialog opens when you select an Advanced Mode counter for entering the missing information.

**Note**

You can select multiple counters to add in Basic Mode but you can only add one counter at a time in Advanced Mode. This restriction is because the **Counter Configuration** dialog opens for each counter you select.

13. Click **Next**.

14. Check the following capture details and adjust as required:
   - Capture output location.
   - Sampling frequency.
   - Capture start time.
   - Capture end time.

   ![Capture](image)

   **Figure 5-5** Adjust capture details as required.

15. Click **Next**.

16. Select whether you want to start profiling now or generate a launch script for profiling later.
17. For Linux applications, specify a working directory to ensure that the command-line options that you provided to boot Linux properly resolve as relative paths. The working directory is usually the directory that contains the binary files.

18. Click **Finish**.

The wizard produces the following output:
- A platform-specific script that starts Fast Models with the Fastline plug-in and all the specified configuration files.
- `fastline.xml`, a file that contains all your inputs to the wizard.
- For Linux systems, the wizard produces the Linux kernel data structure offsets.
- For bare-metal systems, the wizard produces a CSV file that contains the symbol names and addresses that Fastline requires.

If requested, Fast Models launches and Arm Streamline begins profiling.

When you close Fast Models, Arm Streamline analyzes the capture data and opens the report.

To process the ELF image and fully populate the **Call Paths** view, re-analyze the capture with the image selected.

**Note**

Fastline creates an APC file when the Fast Models execution ends. This file is created in the default location for Arm Streamline, unless you specify otherwise. If you choose a different location, import the data into Arm Streamline by clicking **Import Capture File(s)**... and navigating to the chosen directory.

**Related information**

*Booting Linux on a model*