ARM® Compiler

Version 6.4

Migration and Compatibility Guide

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ARM® Compiler

Migration and Compatibility Guide

Release Information

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A	14 March 2014	Non-Confidential	ARM Compiler v6.00 Release
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ARM Limited. Company 02557590 registered in England.

110 Fulbourn Road, Cambridge, England CB1 9NJ.

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Preface

This preface introduces the *ARM® Compiler Migration and Compatibility Guide*.

It contains the following:

About this book

The ARM® Compiler Migration and Compatibility Guide provides migration and compatibility information for users moving from older versions of ARM Compiler to ARM Compiler 6.

Using this book

This book is organized into the following chapters:

Chapter 1 Configuration and Support Information

Summarizes the support levels, and locales and FlexNet versions supported by the ARM® compilation tools.

Chapter 2 Command-line Options Comparison

Compares ARM Compiler 6 command-line options to older versions of ARM Compiler.

Chapter 3 Compiler Source Code Compatibility

Provides details of source code compatibility between ARM Compiler 6 and older `armcc` compiler versions.

Chapter 4 Migrating ARM syntax assembly code to GNU syntax

Describes how to migrate assembly code from the legacy ARM syntax (used by `armasm`) to GNU syntax (used by `armclang`).

Glossary

The ARM Glossary is a list of terms used in ARM documentation, together with definitions for those terms. The ARM Glossary does not contain terms that are industry standard unless the ARM meaning differs from the generally accepted meaning.

See the *ARM Glossary* for more information.

Typographic conventions

italic
: Introduces special terminology, denotes cross-references, and citations.

bold
: Highlights interface elements, such as menu names. Denotes signal names. Also used for terms in descriptive lists, where appropriate.

`monospace`
: Denotes text that you can enter at the keyboard, such as commands, file and program names, and source code.

`mono`space
: Denotes a permitted abbreviation for a command or option. You can enter the underlined text instead of the full command or option name.

`monospace italic`
: Denotes arguments to monospace text where the argument is to be replaced by a specific value.

`monospace bold`
: Denotes language keywords when used outside example code.

`<and>`
: Encloses replaceable terms for assembler syntax where they appear in code or code fragments. For example:

```
MRC p15, 0, <Rd>, <CRn>, <CRm>, <Opcode_2>
```

SMALL CAPITALS
: Used in body text for a few terms that have specific technical meanings, that are defined in the *ARM glossary*. For example, IMPLEMENTATION DEFINED, IMPLEMENTATION SPECIFIC, UNKNOWN, and UNPREDICTABLE.

Feedback

Feedback on this product

If you have any comments or suggestions about this product, contact your supplier and give:

- The product name.
- The product revision or version.
- An explanation with as much information as you can provide. Include symptoms and diagnostic procedures if appropriate.

Feedback on content

If you have comments on content then send an e-mail to *errata@arm.com*. Give:

- The title *ARM® Compiler Migration and Compatibility Guide*.
- The number ARM DUI0742E.
- If applicable, the page number(s) to which your comments refer.
- A concise explanation of your comments.

ARM also welcomes general suggestions for additions and improvements.

Note

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Other information

- *ARM Information Center*.
- *ARM Technical Support Knowledge Articles*.
- *Support and Maintenance*.
- *ARM Glossary*.

Chapter 1
Configuration and Support Information

Summarizes the support levels, and locales and FlexNet versions supported by the ARM® compilation tools.

It contains the following sections:

1.1 Support level definitions

Describes the levels of support for various ARM Compiler features.

ARM Compiler 6 is built on Clang and LLVM technology and as such, has more functionality than the set of product features described in the documentation. The following definitions clarify the levels of support and guarantees on functionality that are expected from these features.

ARM welcomes feedback regarding the use of all ARM Compiler 6 features, and endeavors to support users to a level that is appropriate for that feature. You can contact support at *http://www.arm.com/support*.

Identification in the documentation

All features that are documented in the ARM Compiler 6 documentation are product features, except where explicitly stated. The limitations of non-product features are explicitly stated.

Product features

Product features are suitable for use in a production environment. The functionality is well-tested, and is expected to be stable across feature and update releases.

- ARM endeavors to give advance notice of significant functionality changes to product features.
- If you have a support and maintenance contract, ARM provides full support for use of all product features.
- ARM welcomes feedback on product features.
- Any issues with product features that ARM encounters or is made aware of are considered for fixing in future versions of ARM Compiler.

In addition to fully supported product features, some product features are only alpha or beta quality.

Beta product features

Beta product features are implementation complete, but have not been sufficiently tested to be regarded as suitable for use in production environments.
Beta product features are indicated with [BETA].

- ARM endeavors to document known limitations on beta product features.
- Beta product features are expected to eventually become product features in a future release of ARM Compiler 6.
- ARM encourages the use of beta product features, and welcomes feedback on them.
- Any issues with beta product features that ARM encounters or is made aware of are considered for fixing in future versions of ARM Compiler.

Alpha product features

Alpha product features are not implementation complete, and are subject to change in future releases, therefore the stability level is lower than in beta product features.
Alpha product features are indicated with [ALPHA].

- ARM endeavors to document known limitations of alpha product features.
- ARM encourages the use of alpha product features, and welcomes feedback on them.
- Any issues with alpha product features that ARM encounters or is made aware of are considered for fixing in future versions of ARM Compiler.

Community features

ARM Compiler 6 is built on LLVM technology and preserves the functionality of that technology where possible. This means that there are additional features available in ARM Compiler that are not listed in the documentation. These additional features are known as community features. For information on these community features, see the *documentation for the Clang/LLVM project*.

Where community features are referenced in the documentation, they are indicated with [COMMUNITY].

- ARM makes no claims about the quality level or the degree of functionality of these features, except when explicitly stated in this documentation.
- Functionality might change significantly between feature releases.
- ARM makes no guarantees that community features are going to remain functional across update releases, although changes are expected to be unlikely.

Some community features might become product features in the future, but ARM provides no roadmap for this. ARM is interested in understanding your use of these features, and welcomes feedback on them. ARM supports customers using these features on a best-effort basis, unless the features are unsupported. ARM accepts defect reports on these features, but does not guarantee that these issues are going to be fixed in future releases.

Guidance on use of community features

There are several factors to consider when assessing the likelihood of a community feature being functional:

- The following figure shows the structure of the ARM Compiler 6 toolchain:

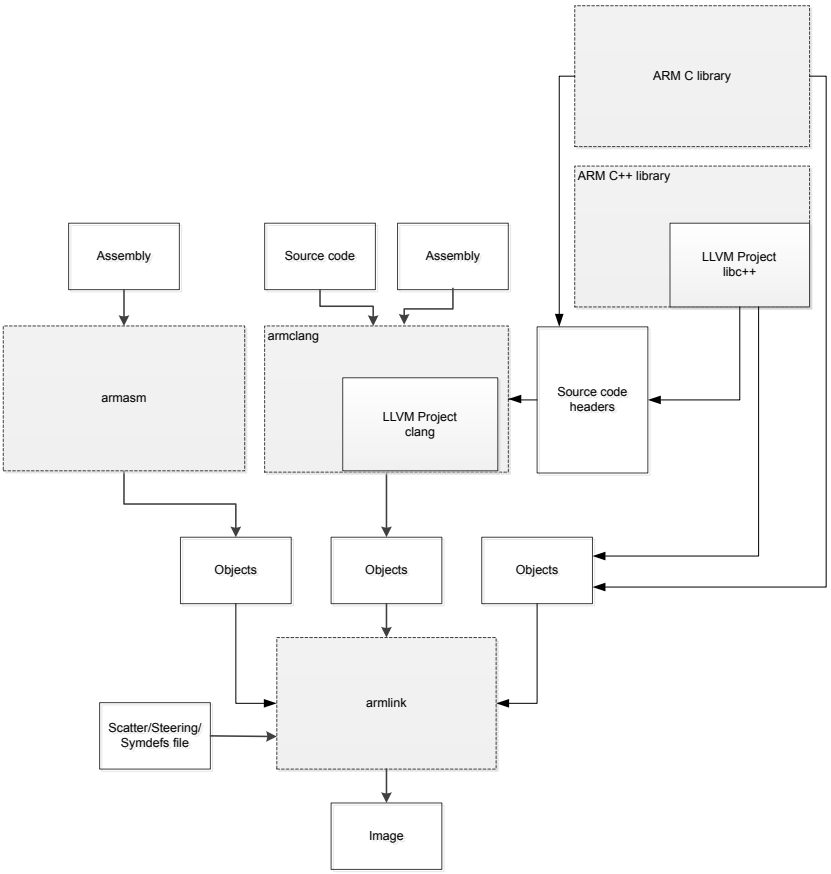

Figure 1-1 Integration boundaries in ARM Compiler 6.

The dashed boxes are toolchain components, and any interaction between these components is an integration boundary. Community features that span an integration boundary might have significant limitations in functionality. The exception to this is if the interaction is codified in one of the standards supported by ARM Compiler 6. See *Application Binary Interface (ABI) for the ARM®*

Architecture. Community features that do not span integration boundaries are more likely to work as expected.
- Features primarily used when targeting hosted environments such as Linux or BSD, might have significant limitations, or might not be applicable, when targeting bare-metal environments.
- The Clang implementations of compiler features, particularly those that have been present for a long time in other toolchains, are likely to be mature. The functionality of new features, such as support for new language features, is likely to be less mature and therefore more likely to have limited functionality.

Unsupported features

With both the product and community feature categories, specific features and use-cases are known not to function correctly, or are not intended for use with ARM Compiler 6.

Limitations of product features are stated in the documentation. ARM cannot provide an exhaustive list of unsupported features or use-cases for community features. The known limitations on community features are listed in *Community features* on page 1-12.

List of known unsupported features

The following is an incomplete list of unsupported features, and might change over time:
- The Clang option `-stdlib=libstdc++` is not supported.
- The ARM Compiler 6 libc++ libraries do not support the Thread support library <thread>.
- Use of C11 library features is unsupported.
- Any community feature that exclusively pertains to non-ARM architectures is not supported by ARM Compiler 6.

1.2 Compiler configuration information

Summarizes the locales and FlexNet versions supported by the ARM compilation tools.

FlexNet versions in the compilation tools

Different versions of ARM Compiler support different versions of FlexNet.

The FlexNet versions in the compilation tools are:

Table 1-1 FlexNet versions

Compilation tools version	Windows	Linux
ARM Compiler 6.01 and later	11.12.1.0	11.12.1.0
ARM Compiler 6.00	11.10.1.0	11.10.1.0

Locale support in the compilation tools

ARM Compiler only supports the English locale.

Related information

ARM DS-5 License Management Guide.

Chapter 2
Command-line Options Comparison

Compares ARM Compiler 6 command-line options to older versions of ARM Compiler.

It contains the following sections:

2.1 Comparison of ARM Compiler 6 compiler command-line options and older versions of ARM Compiler

ARM Compiler provides many command-line options, including most Clang command-line options as well as several ARM-specific options.

Note

This topic includes descriptions of *[BETA]* on page 1-12 and *[COMMUNITY]* on page 1-12 features.

The following table describes the most common ARM Compiler command-line options, and shows equivalent options for ARM Compiler 6 and older versions of ARM Compiler.

Additional information about command-line options is available:

- The *armclang Reference Guide* provides more detail about a number of command-line options.
- For a full list of Clang command-line options, consult the Clang and LLVM documentation.

Table 2-1 Comparison of ARM Compiler 6 compiler command-line options and older versions of ARM Compiler

Older ARM Compiler option	ARM Compiler 6 option	Description
`--allow_fpreg_for_nonfpdata`, `--no_allow_fpreg_for_nonfpdata`	[COMMUNITY] `-mimplicit-float`, `-mno-implicit-float`	Enables or disables the use of VFP and SIMD registers and data transfer instructions for non-VFP and non-SIMD data.
`--apcs=/ropi`	[BETA] `-fropi`	Enables or disables the generation of Read-Only Position-Independent (ROPI) code.
`--apcs=/rwpi`	[BETA] `-frwpi`	Enables or disables the generation of Read/Write Position-Independent (RWPI) code.
`--arm`	`-marm`	Targets the ARM instruction set. The compiler is permitted to generate both ARM and Thumb code, but recognizes that ARM code is preferred.
`-c`	`-c`	Performs the compilation step, but not the link step.
`--c90`	`-xc -std=c90`	Enables the compilation of C90 source code. `-xc` is a positional argument and only affects subsequent input files on the command line
`--c99`	`-xc -std=c99`	Enables the compilation of C99 source code. `-xc` is a positional argument and only affects subsequent input files on the command line
`--cpp`	`-xc++ -std=c++98`	Enables the compilation of C++ source code. `-xc++` is a positional argument and only affects subsequent input files on the command line
`--cpu 8-A.32`	`--target=arm-arm-none-eabi -march=armv8-a`	Targets ARMv8-A, AArch32 state.
`--cpu 8-A.64`	`--target=aarch64-arm-none-eabi`	Targets ARMv8-A, AArch64 state. (Implies `-march=armv8-a` if `-mcpu` is not specified.)

Table 2-1 Comparison of ARM Compiler 6 compiler command-line options and older versions of ARM Compiler (continued)

Older ARM Compiler option	ARM Compiler 6 option	Description
`--cpu 7-A`	`--target=arm-arm-none-eabi -march=armv7-a`	Targets ARMv7-A.
`--cpu=Cortex-M4`	`--target=arm-arm-none-eabi -mcpu=cortex-m4`	Targets the Cortex M4
`--cpu=Cortex-A15`	`--target=arm-arm-none-eabi -mcpu=cortex-a15`	Targets the Cortex A15 processor.
`-D`	`-D`	Defines a preprocessing macro.
`-E`	`-E`	Executes only the preprocessor step.
`--fpmode=fast`	`-ffast-math`	Performs aggressive floating-point optimizations at the cost of IEEE compliance.
`--fpu`	`-mfpu`	Specifies the target FPU architecture. **Note** `--fpu=none` checks the source code for floating-point operations, and if any are found it produces an error. `-mfpu=none` prevents the compiler from using hardware-based floating-point functions. If the compiler encounters floating-point types in the source code, it uses software-based floating-point library functions.
`-I`	`-I`	Adds the specified directories to the list of places that are searched to find included files.
`--inline`	Default at `-O2` and `-O3`.	There is no equivalent of the `--inline` option. ARM Compiler 6 automatically decides whether to inline functions at optimization levels `-O2` and `-O3`.
`-L`	`-Xlinker`	Specifies command-line options to pass to the linker when a link step is being performed after compilation.
`--licretry`	No equivalent.	There is no equivalent of the `--licretry` option. The ARM Compiler 6 tools automatically retry failed attempts to obtain a license.
`--list_macros`	`-E -dM`	List all the macros that are defined at the end of the translation unit, including the predefined macros
`--lower_ropi`, `--no_lower_ropi`	[BETA] `-fropi-lowering`, `-fno-ropi-lowering`	Enables or disables less restrictive C when generating Read-Only Position-Independent (ROPI) code. **Note** In ARM Compiler 5, when `--acps=/ropi` is specified, `--lower_ropi` is not switched on by default. In ARM Compiler 6, when `-fropi` is specified, `-fropi-lowering` is switched on by default.

Table 2-1 Comparison of ARM Compiler 6 compiler command-line options and older versions of ARM Compiler (continued)

Older ARM Compiler option	ARM Compiler 6 option	Description
`--lower_rwpi`, `--no_lower_rwpi`	[BETA] `-frwpi-lowering`, `-fno-rwpi-lowering`	Enables or disables less restrictive C when generating Read-Write Position-Independent (RWPI) code.
`-M`	`-M`	Instructs the compiler to produce a list of makefile dependency lines suitable for use by a make utility.
`--depend`	`-MF`	Specifies a filename for the makefile dependency rules.
`--depend_format=unix_escaped`		Dependency file entries use UNIX-style path separators and escapes spaces with \. This is the default in ARM Compiler 6.
`--depend_target`	`-MT`	Changes the target name for the makefile dependency rule.
`--ignore_missing_headers`	`-MG`	Prints dependency lines for header files even if the header files are missing.
`--phony_targets`	`-MP`	Emits dummy makefile rules.
`--md`	`-MD`	Creates makefile dependency files, including the system header files. In ARM Compiler 5, this is equivalent to `--md --depend_system_headers`.
`--md --no_depend_system_headers`	`-MMD`	Creates makefile dependency files, without the system header files.
`--mm`	`-MM`	Creates a single makefile dependency file, without the system header files. In ARM Compiler 5, this is equivalent to `-M --no_depend_system_headers`.
`-o`	`-o`	Specifies the name of the output file.
`-O`*num*	`-O`*num*	Specifies the level of optimization to be used when compiling source files. The default for older compiler versions is `-O2`. The default for ARM Compiler 6 is `-O0`.
`-Ospace`	`-Oz / -Os`	Performs optimizations to reduce image size at the expense of a possible increase in execution time.
`-Otime`	Default.	Performs optimizations to reduce execution time at the expense of a possible increase in image size. There is no equivalent of the `-Otime` option. ARM Compiler 6 optimizes for execution time by default, unless you specify the `-Os` or `-Oz` options.
`--preinclude`	`-include`	Include the source code of a specified file at the beginning of the compilation.
`--relaxed_ref_def`	`-fcommon`	Places zero-initialized definitions in a common block.
`-S`	`-S`	Outputs the disassembly of the machine code generated by the compiler. The output from this option differs between releases. Older ARM Compiler versions produce output with `armasm` syntax while ARM Compiler 6 produces output with GNU syntax.

Table 2-1 Comparison of ARM Compiler 6 compiler command-line options and older versions of ARM Compiler (continued)

Older ARM Compiler option	ARM Compiler 6 option	Description
`--show_cmdline`	`-v`	Shows how the compiler processes the command line. The commands are shown normalized, and the contents of any via files are expanded.
`--split_ldm`	`-fno-ldm-stm`	Disables the generation of `LDM` and `STM` instructions. Note that while the `armcc --split_ldm` option limits the size of generated LDM/STM instructions, the `armclang -fno-ldm-stm` option disables the generation of `LDM` and `STM` instructions altogether.
`--split_sections`	`-ffunction-sections`	Generates one ELF section for each function in the source file.
`--thumb`	`-mthumb`	Targets the Thumb instruction set.
`--vectorize`	`-fvectorize`	Enables the generation of Advanced SIMD vector instructions directly from C or C++ code.
`--via`	`@file`	Reads an additional list of compiler options from a file.
`--vsn`	`--version`	Displays version information and license details.

Related information

The LLVM Compiler Infrastructure Project.

2.2 Command-line options for preprocessing assembly source code

The functionality of the `--cpreproc` and `--cpreproc_opts` command-line options in the version of `armasm` supplied with ARM Compiler 6 is different from the options used in earlier versions of `armasm` to preprocess assembly source code.

If you are using `armasm` to assemble source code that requires the use of the preprocessor, you must use both the `--cpreproc` and `--cpreproc_opts` options together. Also:

- As a minimum, you must include the `armclang` options `--target` and either `-mcpu` or `-march` in `--cpreproc_opts`.
- The input assembly source must have an upper-case extension `.S`.

Example

The options to the preprocessor in this example are `--cpreproc_opts=--target=arm-arm-none-eabi,-mcpu=cortex-a9,-D,DEF1,-D,DEF2`.

```
armasm --cpu=cortex-a9 --cpreproc --cpreproc_opts=--target=arm-arm-none-eabi, -mcpu=cortex-a9,-D,DEF1,-D,DEF2 -I /path/to/includes1 -I /path/to/includes2 input.S
```

Note

Ensure that you specify compatible architectures in the `armclang` options `--target`, `-mcpu` or `-march`, and the `armasm` `--cpu` option.

Related information

--cpreproc assembler option.
--cpreproc_opts assembler option.
Specifying a target architecture, processor, and instruction set.
-march armclang option.
-mcpu armclang option.
--target armclang option.

Chapter 3
Compiler Source Code Compatibility

Provides details of source code compatibility between ARM Compiler 6 and older `armcc` compiler versions.

It contains the following sections:

3.1 Language extension compatibility: keywords

ARM Compiler 6 provides support for some keywords that were supported in older `armcc` compiler versions. Other keywords are not supported, or must be replaced with alternatives.

The following table lists some of the commonly used keywords that are supported by older versions of the compiler but are not supported by ARM Compiler 6. Replace any instances of these keywords in your code with the recommended alternative.

Note

This is not an exhaustive list of all unsupported keywords.

Table 3-1 Keyword language extensions that must be replaced

Keyword supported by older compiler versions	Recommended ARM Compiler 6 alternative
`__align(x)`	`__attribute__((aligned(x)))`
`__clz`	Use an inline `CLZ` assembly instruction or equivalent routine.
`__const`	`__attribute__((const))`
`__forceinline`	`__attribute__((always_inline))`
`__ldrex`	Use an inline `LDREX` assembly instruction.
`__packed`	`__attribute__((packed, aligned(1)))`
`__pure`	`__attribute__((pure))`
`__rev`	Use an inline `REV` assembly instruction.
`__sev`	Use an inline `SEV` assembly instruction.
`__softfp`	`__attribute__((__pcs__("aapcs")))`
`__strex`	Use an inline `STREX` assembly instruction.
`__weak`	`__attribute__((weak))`
`__wfe`	Use an inline `WFE` assembly instruction.

Related references

3.5 C and C++ implementation compatibility on page 3-30.
3.2 Language extension compatibility: attributes on page 3-24.
3.3 Language extension compatibility: pragmas on page 3-25.

3.2 Language extension compatibility: attributes

ARM Compiler 6 provides support for some function, variable, and type attributes that were supported in older `armcc` compiler versions. Other attributes are not supported.

The following attributes are supported by older compiler versions and ARM Compiler 6. These attributes do not require modification in your code:

- `__attribute__((aligned(x)))`
- `__attribute__((always_inline))`
- `__attribute__((const))`
- `__attribute__((deprecated))`
- `__attribute__((noinline))`
- `__declspec(noinline)`
- `__attribute__((nonnull))`
- `__attribute__((noreturn))`
- `__declspec(noreturn)`
- `__attribute__((nothrow))`
- `__declspec(nothrow)`
- `__attribute__((pcs("calling convention")))`
- `__attribute__((pure))`
- `__attribute__((section("name")))`

  Note

  Older compiler versions supported the `zero_init` attribute. ARM Compiler 6 does not support the `zero_init` attribute, but if the section name starts with `.bss.`, the variable is placed in a ZI section.

- `__attribute__((unused))`
- `__attribute__((used))`
- `__attribute__((visibility))`
- `__attribute__((weak))`
- `__attribute__((weakref))`

Related references

3.5 C and C++ implementation compatibility on page 3-30.
3.1 Language extension compatibility: keywords on page 3-23.
3.3 Language extension compatibility: pragmas on page 3-25.

3.3 Language extension compatibility: pragmas

ARM Compiler 6 provides support for some pragmas that were supported in older `armcc` compiler versions. Other pragmas are not supported, or must be replaced with alternatives.

The following table lists some of the commonly used pragmas that are supported by older versions of the compiler but are not supported by ARM Compiler 6. Replace any instances of these pragmas in your code with the recommended alternative.

Table 3-2 Pragma language extensions that must be replaced

Pragma supported by older `armcc` compiler versions	Recommended ARM Compiler 6 alternative
`#pragma import (`*`symbol`*`)`	`asm(" .global `*`symbol`*`\n");`

`#pragma anon_unions`
`#pragma no_anon_unions`
	In C, anonymous structs and unions are a C11 extension which is enabled by default in armclang. If you specify the `-pedantic` option, the compiler emits warnings about extensions do not match the specified language standard. For example:
	`armclang --target=aarch64-arm-none-eabi -c -pedantic --std=c90 test.c`
	`  test.c:3:5: warning: anonymous structs are a C11 extension [-Wc11-extensions]`
	In C++, anonymous unions are part of the language standard, and are always enabled. However, anonymous structs and classes are an extension. If you specify the `-pedantic` option, the compiler emits warnings about anonymous structs and classes. For example:
	`armclang --target=aarch64-arm-none-eabi -c -pedantic -xc++ test.c`
	`  test.c:3:5: warning: anonymous structs are a GNU extension [-Wgnu-anonymous-struct]`
	Introducing anonymous unions, struct and classes using a `typedef` is a separate extension in `armclang`, which must be enabled using the `-fms-extensions` option.

`#pragma arm` `#pragma thumb`	`armclang` does not support switching instruction set in the middle of a file. You can use the command line options `-marm` and `-mthumb` to specify the instruction set of the whole file.
`#pragma arm section`	`armclang` does not support setting the sections to be used for code, rodata, rwdata and zidata for the rest of the file. However the `__attribute__((section("name")))` attribute can be used to set the section of individual functions and variables.

Table 3-2 Pragma language extensions that must be replaced (continued)

Pragma supported by older armcc compiler versions	Recommended ARM Compiler 6 alternative

`#pragma diag_default`
`#pragma diag_suppress`
`#pragma diag_remark`
`#pragma diag_warning`
`#pragma diag_error`
	The following pragmas provide equivalent functionality for `diag_suppress`, `diag_warning`, and `diag_error`:
	• `#pragma clang diagnostic ignored "-Wmultichar"`
	• `#pragma clang diagnostic warning "-Wmultichar"`
	• `#pragma clang diagnostic error "-Wmultichar"`
	Note that these pragmas use `armclang` diagnostic groups, which do not have a precise mapping to `armcc` diagnostic tags.
	`armclang` has no equivalent to `diag_default` or `diag_remark`. `diag_default` can be replaced by wrapping the change of diagnostic level with `#pragma clang diagnostic push` and `#pragma clang diagnostic pop`, or by manually returning the diagnostic to the default level.
	There is an additional diagnostic level supported in armclang, `fatal`, which causes compilation to fail without processing the rest of the file. You can set this as follows:
	`#pragma clang diagnostic fatal "-Wmultichar"`

`#pragma exceptions_unwind` `#pragma no_exceptions_unwind`	`armclang` does not support these pragmas. Use the `__attribute__((nothrow))` function attribute instead.
`#pragma GCC system_header`	This pragma is supported by both `armcc` and `armclang`, but `#pragma clang system_header` is the preferred spelling in `armclang` for new code.
`#pragma hdrstop` `#pragma no_pch`	`armclang` does not support these pragmas.
`#pragma import(__use_no_semihosting)` `#pragma import(__use_no_semihosting_swi)`	`armclang` does not support these pragmas. However, in C code, you can replace these pragmas with `asm(" .global __use_no_semihosting");`
`#pragma inline` `#pragma no_inline`	`armclang` does not support these pragmas. However, inlining can be disabled on a per-function basis using the `__attribute__((noinline))` function attribute. The default behavior of both `armcc` and `armclang` is to inline functions when the compiler considers this worthwhile, and this is the behavior selected by using `#pragma inline` in `armcc`. To force a function to be inlined in `armclang`, use the `__attribute__((always_inline))` function attribute.

`#pragma Onum`
`#pragma Ospace`
`#pragma Otime`
	`armclang` does not support changing optimization options within a file. Instead these must be set on a per-file basis using command-line options.

`#pragma pop` `#pragma push`	`armclang` does not support these pragmas. If these are only used to control emission of diagnostics, `#pragma clang diagnostic push` and `#pragma clang diagnostic pop` can be used to achieve the same effect.

Table 3-2 Pragma language extensions that must be replaced (continued)

Pragma supported by older `armcc` compiler versions	Recommended ARM Compiler 6 alternative
`#pragma softfp_linkage`	`armclang` does not support this pragma. Instead, use the `__attribute__((pcs("aapcs")))` function attribute to set the calling convention on a per-function basis, or use the `-mfloat-abi=soft` command-line option to set the calling convention on a per-file basis.
`#pragma no_softfp_linkage`	`armclang` does not support this pragma. Instead, use the `__attribute__((pcs("aapcs-vfp")))` function attribute to set the calling convention on a per-function basis, or use the `-mfloat-abi=hard` command-line option to set the calling convention on a per-file basis.
`#pragma unroll[(n)]` `#pragma unroll_completely`	`armclang` supports these pragmas. The default for `#pragma unroll` (that is, with no iteration count specified) differs between `armclang` and `armcc`: • With `armclang`, the default is to fully unroll a loop. • With `armcc`, the default is `#pragma unroll(4)`.

Related references

3.5 C and C++ implementation compatibility on page 3-30.
3.1 Language extension compatibility: keywords on page 3-23.
3.2 Language extension compatibility: attributes on page 3-24.
3.4 Diagnostics for pragma compatibility on page 3-28.

Related information

armclang Reference Guide: #pragma GCC system_header.
armclang Reference Guide: #pragma once.
armclang Reference Guide: #pragma pack(n).
armclang Reference Guide: #pragma weak symbol, #pragma weak symbol1 = symbol2.
armclang Reference Guide: #pragma unroll[(n)], #pragma unroll_completely.

3.4 Diagnostics for pragma compatibility

Older `armcc` compiler versions supported many pragmas which are not supported by `armclang`, but which could change the semantics of code. When `armclang` encounters these pragmas, it generates diagnostic messages.

The following table shows which diagnostics are generated for each pragma type, and the diagnostic group to which that diagnostic belongs. `armclang` generates diagnostics as follows:

- Errors indicate use of an `armcc` pragma which could change the semantics of code.
- Warnings indicate use of any other `armcc` pragma which is ignored by armclang.
- Pragmas other than those listed are silently ignored.

Table 3-3 Pragma diagnostics

Pragma supported by older compiler versions	Default diagnostic type	Diagnostic group
`#pragma anon_unions`	Warning	`armcc-pragma-anon-unions`
`#pragma no_anon_unions`	Warning	`armcc-pragma-anon-unions`
`#pragma arm`	Error	`armcc-pragma-arm`
`#pragma arm section [`*`section_type_list`*`]`	Error	`armcc-pragma-arm`
`#pragma diag_default `*`tag`*`[,`*`tag`*`,...]`	Error	`armcc-pragma-diag`
`#pragma diag_error `*`tag`*`[,`*`tag`*`,...]`	Error	`armcc-pragma-diag`
`#pragma diag_remark `*`tag`*`[,`*`tag`*`,...]`	Warning	`armcc-pragma-diag`
`#pragma diag_suppress `*`tag`*`[,`*`tag`*`,...]`	Warning	`armcc-pragma-diag`
`#pragma diag_warning `*`tag`*`[,`*`tag`*`,...]`	Warning	`armcc-pragma-diag`
`#pragma exceptions_unwind`	Error	`armcc-pragma-exceptions-unwind`
`#pragma no_exceptions_unwind`	Error	`armcc-pragma-exceptions-unwind`
`#pragma GCC system_header`	None	-
`#pragma hdrstop`	Warning	`armcc-pragma-hdrstop`
`#pragma import `*`symbol_name`*	Error	`armcc-pragma-import`
`#pragma inline`	Warning	`armcc-pragma-inline`
`#pragma no_inline`	Warning	`armcc-pragma-inline`
`#pragma no_pch`	Warning	`armcc-pragma-no-pch`
`#pragma O`*`num`*	Warning	`armcc-pragma-optimization`
`#pragma once`	None	-
`#pragma Ospace`	Warning	`armcc-pragma-optimization`
`#pragma Otime`	Warning	`armcc-pragma-optimization`
`#pragma pack`	None	-
`#pragma pop`	Error	`armcc-pragma-push-pop`
`#pragma push`	Error	`armcc-pragma-push-pop`
`#pragma softfp_linkage`	Error	`armcc-pragma-softfp-linkage`
`#pragma no_softfp_linkage`	Error	`armcc-pragma-softfp-linkage`
`#pragma thumb`	Error	`armcc-pragma-thumb`

Table 3-3 Pragma diagnostics (continued)

Pragma supported by older compiler versions	Default diagnostic type	Diagnostic group
`#pragma weak symbol`	None	-
`#pragma weak symbol1 = symbol2`	None	-

In addition to the above diagnostic groups, there are the following additional diagnostic groups:

`armcc-pragmas`
: Contains all of the above diagnostic groups.

`unknown-pragmas`
: Contains diagnostics about pragmas which are not known to armclang, and are not in the above table.

`pragmas`
: Contains all pragma-related diagnostics, including `armcc-pragmas` and `unknown-pragmas`.

Any non-fatal `armclang` diagnostic group can be ignored, upgraded, or downgraded using the following command-line options:

Suppress a group of diagnostics:
: `-Wno-diag-group`

Upgrade a group of diagnostics to warnings:
: `-Wdiag-group`

Upgrade a group of diagnostics to errors:
: `-Werror=diag-group`

Downgrade a group of diagnostics to warnings:
: `-Wno-error=diag-group`

Related references

3.3 Language extension compatibility: pragmas on page 3-25.

3.5 C and C++ implementation compatibility

ARM Compiler 6 C and C++ implementation details differ from previous compiler versions.

The following table describes the C and C++ implementation detail differences.

Table 3-4 C and C++ implementation detail differences

Feature	Older versions of ARM Compiler	ARM Compiler 6
Integer operations		
Shifts	int shifts > 0 && < 127 int left shifts > 31 == 0 int right shifts > 31 == 0 (for unsigned or positive), -1 (for negative) long long shifts > 0 && < 63	Warns when shift amount > width of type. You can use the `-Wshift-count-overflow` option to suppress this warning.
Integer division	Checks that the sign of the remainder matches the sign of the numerator	The sign of the remainder is not necessarily the same as the sign of the numerator.
Floating-point operations		
Default standard	IEEE 754 standard, rounding to nearest representable value, exceptions disabled by default.	All facilities, operations, and representations guaranteed by the IEEE standard are available in single and double-precision. Modes of operation can be selected dynamically at runtime. This is equivalent to the `--fpmode=ieee_full` option in older versions of ARM Compiler.
Unions, enums and structs		
Enum packing	Enums are implemented in the smallest integral type of the correct sign to hold the range of the enum values, unless `--enum_is_int` is specified in C++ mode.	By default enums are implemented as `int`, with `long long` used when required.
Signedness of plain bit-fields	Unsigned. Plain bit-fields declared without either the `signed` or `unsigned` qualifiers default to `unsigned`. The `--signed_bitfields` option treats plain bit-fields as `signed`.	Signed. Plain bit-fields declared without either the `signed` or `unsigned` qualifiers default to `signed`. There is no equivalent to either the `--signed_bitfields` or `--no_signed_bitfields` options.
Misc C		
`sizeof(wchar_t)`	2 bytes	4 bytes
Misc C++		
C++ library	Rogue Wave Standard C++ Library	libc++ **Note** • There is limited compatibility between objects created with ARM Compiler 6 and those created with ARM Compiler 5.

Table 3-4 C and C++ implementation detail differences (continued)

Feature	Older versions of ARM Compiler	ARM Compiler 6
Implicit inclusion	If compilation requires a template definition from a template declared in a header file `xyz.h`, the compiler implicitly includes the file `xyz.cc` or `xyz.CC`.	Not supported.
Alternative template lookup algorithms	When performing referencing context lookups, name lookup matches against names from the instantiation context as well as from the template definition context.	Not supported.
Exceptions	Off by default, function unwinding on with `--exceptions` by default.	On by default in C++ mode.

Related references

3.1 Language extension compatibility: keywords on page 3-23.
3.2 Language extension compatibility: attributes on page 3-24.
3.3 Language extension compatibility: pragmas on page 3-25.
3.6 Compatibility of C++ objects on page 3-32.

3.6 Compatibility of C++ objects

The compatibility of C++ objects compiled with ARM Compiler 5 depends on the C++ libraries used.

Compatibility with objects compiled using Rogue Wave standard library headers

ARM Compiler 6 does not support binary compatibility with objects compiled using the Rogue Wave standard library include files.

There are warnings at link time when objects are mixed. `L6869W` is reported if an object requests the Rogue Wave standard library. `L6870W` is reported when using an object that is compiled with ARM Compiler 5 with exceptions support.

The impact of mixing objects that have been compiled against different C++ standard library headers might include:

- Undefined symbol errors.
- Increased code size.
- Possible runtime errors.

If you have ARM Compiler 6 objects that have been compiled with the legacy `-stdlib=legacy_cpplib` option then these objects use the Rogue Wave standard library and therefore might be incompatible with objects created using ARM Compiler 6.4 or later. To resolve these issues, you must recompile all object files with ARM Compiler 6.4 or later.

Compatibility with C++ objects compiled using ARM Compiler 5

The choice of C++ libraries at link time must match the choice of C++ include files at compile time for all input objects. ARM Compiler 5 objects that use the Rogue Wave C++ libraries are not compatible with ARM Compiler 6 objects. ARM Compiler 5 objects that use C++ but do not make use of the Rogue Wave header files can be compatible with ARM Compiler 6 objects that use libc++ but this is not guaranteed.

ARM recommends using ARM Compiler 6 for building the object files.

Compatibility of arrays of objects compiled using ARM Compiler 5

ARM Compiler 6 is not compatible with objects from ARM Compiler 5 that use operator `new[]` and `delete[]`. Undefined symbol errors result at link time because ARM Compiler 6 does not provide the helper functions that ARM Compiler 5 depends on. For example:

```
class Foo
{
public:
    Foo() : x_(new int) { *x_ = 0; }
    void setX(int x) { *x_ = x; }
    ~Foo() { delete x_; }
private:
    int* x_;
};

void func(void)
{
    Foo* array;
    array = new Foo [10];
    array[0].setX(1);
    delete[] array;
}
```

Compiling this with ARM Compiler 5 compiler, `armcc`, and linking with ARM Compiler 6 linker, `armlink`, generates linker errors.

```
armcc -c construct.cpp -Ospace -O1 --cpu=cortex-a9
armlink construct.o -o construct.axf
```

This generates the following linker errors:

```
Error: L6218E: Undefined symbol __aeabi_vec_delete (referred from construct.o).
Error: L6218E: Undefined symbol __aeabi_vec_new_cookie_nodtor (referred from construct.o).
```

To resolve these linker errors, you must use the ARM Compiler 6 compiler, `armclang`, to compile all C++ files that use the `new[]` and `delete[]` operators.

Note

You do not have to specify `--stdlib=libc++` for `armlink`, because this is the default and only option in ARM Compiler 6.4, and later.

Related information

armlink User Guide: --stdlib.
armclang Reference Guide: --stdlib.

Chapter 4
Migrating ARM syntax assembly code to GNU syntax

Describes how to migrate assembly code from the legacy ARM syntax (used by `armasm`) to GNU syntax (used by `armclang`).

It contains the following sections:

4.1 Overview of differences between ARM and GNU syntax assembly code

`armasm` (for assembling legacy assembly code) uses ARM syntax assembly code.

`armclang` aims to be compatible with GNU syntax assembly code (that is, the assembly code syntax supported by the GNU assembler, `as`).

If you have legacy assembly code that you want to assemble with `armclang`, you must convert that assembly code from ARM syntax to GNU syntax.

The specific instructions in your assembly code will not change during this migration process (although in some cases, the order of operands may change).

However, you need to make changes to the syntax of your assembly code. These changes include:

- The directives in your code.
- The format of labels, comments, and some types of literals.
- Some symbol names.
- The operators in your code.

The following examples show simple, equivalent, assembly code in both ARM and GNU syntax.

ARM syntax

```
; Simple ARM syntax example
;
; Iterate round a loop 10 times, adding 1 to a register each time.

        AREA ||.text||, CODE, READONLY, ALIGN=2

main PROC
        MOV      w5,#0x64      ; W5 = 100
        MOV      w4,#0         ; W4 = 0
        B        test_loop     ; branch to test_loop
loop
        ADD      w5,w5,#1      ; Add 1 to W5
        ADD      w4,w4,#1      ; Add 1 to W4
test_loop
        CMP      w4,#0xa       ; if W4 < 10, branch back to loop
        BLT      loop
        ENDP

        END
```

GNU syntax

```
// Simple GNU syntax example 4.2 Comments on page 4-37
//
// Iterate round a loop 10 times, adding 1 to a register each time.

        .section .text,"x"     // 4.6 Sections on page 4-42
        .balign 4

main:                          // 4.3 Labels on page 4-38
        MOV      w5,#0x64      // W5 = 100  4.8 Numeric literals on page 4-44
        MOV      w4,#0         // W4 = 0
        B        test_loop     // branch to test_loop
loop:
        ADD      w5,w5,#1      // Add 1 to W5
        ADD      w4,w4,#1      // Add 1 to W4
test_loop:
        CMP      w4,#0xa       // if W4 < 10, branch back to loop
        BLT      loop
        .end                   // 4.15 Miscellaneous directives on page 4-51
```

Related references

4.2 Comments on page 4-37.
4.3 Labels on page 4-38.
4.4 Numeric local labels on page 4-39.
4.5 Functions on page 4-41.
4.6 Sections on page 4-42.

4.2 Comments

A comment identifies text that the assembler ignores.

ARM syntax

A comment is the final part of a source line. The first semicolon on a line marks the beginning of a comment except where the semicolon appears inside a string literal.

The end of the line is the end of the comment. A comment alone is a valid line.

For example:

```
; This whole line is a comment
; As is this line

myProc: PROC
    MOV     r1, #16    ; Load R0 with 16
```

GNU syntax

GNU syntax assembly code provides two different methods for marking comments:

- The `/*` and `*/` markers identify multiline comments:

```
/* This is a comment
that spans multiple
lines */
```

- The `//` marker identifies the remainder of a line as a comment:

```
MOV R0,#16    // Load R0 with 16
```

Related information

GNU Binutils - Using as: Comments.

armasm User Guide: Syntax of source lines in assembly language.

4.3 Labels

Labels are symbolic representations of addresses. You can use labels to mark specific addresses that you want to refer to from other parts of the code.

ARM syntax

A label is written as a symbol beginning in the first column. A label can appear either in a line on its own, or in a line with an instruction or directive. Whitespace separates the label from any following instruction or directive:

```
  MOV R0,#16
loop SUB R0,R0,#1 ; "loop" is a label
  CMP R0,#0
  BGT loop
```

GNU syntax

A label is written as a symbol that either begins in the first column, or has nothing but whitespace between the first column and the label. A label can appear either in a line on its own, or in a line with an instruction or directive. A colon ":" follows the label (whitespace is allowed between the label and the colon):

```
  MOV R0,#16
loop:               // "loop" label on its own line
  SUB R0,R0,#1
  CMP R0,#0
  BGT loop
```

```
  MOV R0,#16
loop: SUB R0,R0,#1  // "loop" label in a line with an instruction
  CMP R0,#0
  BGT loop
```

Related references

4.4 Numeric local labels on page 4-39.

Related information

GNU Binutils - Using as: Labels.

4.4 Numeric local labels

Numeric local labels are a type of label that you refer to by a number rather than by name. Unlike other labels, the same numeric local label can be used multiple times and the same number can be used for more than one numeric local label.

ARM syntax

A numeric local label is a number in the range 0-99, optionally followed by a scope name corresponding to a `ROUT` directive.

Numeric local labels follow the same syntax as all other labels.

Refer to numeric local labels using the following syntax:

`%[F|B][A|T]`*`n`*`[`*`routname`*`]`

Where:

- `F` and `B` instruct the assembler to search forwards and backwards respectively. By default, the assembler searches backwards first, then forwards.
- `A` and `T` instruct the assembler to search all macro levels or only the current macro level respectively. By default, the assembler searches all macros from the current level to the top level, but does not search lower level macros.
- *`n`* is the number of the numeric local label in the range 0-99.
- *`routname`* is an optional scope label corresponding to a `ROUT` directive. If *`routname`* is specified in either a label or a reference to a label, the assembler checks it against the name of the nearest preceding `ROUT` directive. If it does not match, the assembler generates an error message and the assembly fails.

For example, the following code implements an incrementing loop:

```
        MOV     r4,#1       ; r4=1
1                           ; Local label
        ADD     r4,r4,#1    ; Increment r4
        CMP     r4,#0x5     ; if r4 < 5...
        BLT     %b1         ; ...branch backwards to local label "1"
```

Here is the same example using a `ROUT` directive to restrict the scope of the local label:

```
routA   ROUT                ; Start of "routA" scope
        MOV     r4,#1       ; r4=1
1routA                      ; Local label
        ADD     r4,r4,#1    ; Increment r4
        CMP     r4,#0x9     ; if r4 < 9...
        BLT     %b1routA    ; ...branch backwards to local label "1routA"
routB   ROUT                ; Start of "routB" scope (and therefore end of "routA" scope)
```

GNU syntax

A numeric local label is a number in the range 0-99.

Numeric local labels follow the same syntax as all other labels.

Refer to numeric local labels using the following syntax:

`n``{f|b}`

Where:

- *`n`* is the number of the numeric local label in the range 0-99.
- `f` and `b` instruct the assembler to search forwards and backwards respectively. There is no default. You must specify one of `f` or `b`.

For example, the following code implements an incrementing loop:

```
        MOV     r4,#1       // r4=1
1:                          // Local label
        ADD     r4,r4,#1    // Increment r4
```

```
        CMP     r4,#0x5     // if r4 < 5...
        BLT     1b          // ...branch backwards to local label "1"
```

Note

GNU syntax assembly code does not provide mechanisms for restricting the scope of local labels.

Related references

4.3 Labels on page 4-38.

Related information

GNU Binutils - Using as: Labels.
GNU Binutils - Using as: Local labels.
armasm User Guide: Labels.
armasm User Guide: Numeric local labels.
armasm User Guide: Syntax of numeric local labels.
armasm User Guide: ROUT.

4.5 Functions

Assemblers can identify the start of a function when producing DWARF call frame information for ELF.

ARM syntax

The `FUNCTION` directive marks the start of a function. `PROC` is a synonym for `FUNCTION`.

The `ENDFUNC` directive marks the end of a function. `ENDP` is a synonym for `ENDFUNC`.

For example:

```
myproc  PROC
  ; Procedure body
  ENDP
```

GNU syntax

Use the `.type` directive to identify symbols as functions. For example:

```
  .type myproc, "function"
myproc:
  // Procedure body
```

GNU syntax assembly code provides the `.func` and `.endfunc` directives. However, these are not supported by `armclang`. `armclang` uses the `.size` directive to set the symbol size:

```
  .type myproc, "function"
myproc:
  // Procedure body
.Lmyproc_end0:
  .size myproc, .Lmyproc_end0-myproc
```

Note

Functions must be typed to link properly.

Related information

GNU Binutils - Using as: .type.
armasm User Guide: FUNCTION or PROC.
armasm User Guide: ENDFUNC or ENDP.

4.6 Sections

Sections are independent, named, indivisible chunks of code or data that are manipulated by the linker.

ARM syntax

The `AREA` directive instructs the assembler to assemble a new code or data section.

Section attributes within the `AREA` directive provide information about the section. Available section attributes include the following:

- `CODE` specifies that the section contains machine instructions.
- `READONLY` specifies that the section must not be written to.
- `ALIGN=`*n* specifies that the section is aligned on a 2^n byte boundary

For example:

```
AREA mysection, CODE, READONLY, ALIGN=3
```

Note

The `ALIGN` attribute does not take the same values as the `ALIGN` directive. `ALIGN=`*n* (the `AREA` attribute) aligns on a 2^n byte boundary. `ALIGN` *n* (the `ALIGN` directive) aligns on an *n*-byte boundary.

GNU syntax

The `.section` directive instructs the assembler to assemble a new code or data section.

Flags provide information about the section. Available section flags include the following:

- `x` specifies that the section is executable.
- `w` specifies that the section is writable.

For example:

```
.section  mysection,"x"
```

Not all ARM syntax `AREA` attributes map onto GNU syntax `.section` flags. For example, the ARM syntax `ALIGN` attribute corresponds to the GNU syntax `.balign` directive, rather than a `.section` flag:

```
.section  mysection,"x"
.balign 8
```

Related information

GNU Binutils - Using as: .section.
GNU Binutils - Using as: .align.
armasm User Guide: AREA.

4.7 Symbol naming rules

ARM syntax assembly code and GNU syntax assembly code use similar, but different naming rules for symbols.

Symbol naming rules which are common to both ARM syntax and GNU syntax include:

- Symbol names must be unique within their scope.
- Symbol names are case-sensitive, and all characters in the symbol name are significant.
- Symbols must not use the same name as built-in variable names or predefined symbol names.

Symbol naming rules which differ between ARM syntax and GNU syntax include:

- ARM syntax symbols must start with a letter or the underscore character "_".

  GNU syntax symbols must start with a letter, the underscore character "_", or a period ".".
- ARM syntax symbols use double bars to delimit symbol names containing non-alphanumeric characters (except for the underscore):

  ```
  IMPORT ||Image$$ARM_LIB_STACKHEAP$$ZI$$Limit||
  ```

  GNU syntax symbols do not require double bars:

  ```
  .global Image$$ARM_LIB_STACKHEAP$$ZI$$Limit
  ```

Related information

GNU Binutils - Using as: Symbol Names.
armasm User Guide: Symbol naming rules.

4.8 Numeric literals

ARM syntax assembly and GNU syntax assembly provide different methods for specifying some types of numeric literal.

Implicit shift operations

ARM syntax assembly allows immediate values with an implicit shift operation. For example, the `MOVK` instruction takes a 16-bit operand with an optional left shift. `armasm` accepts the instruction `MOVK x1, #0x40000`, converting the operand automatically to `MOVK x1, #0x4, LSL #16`.

GNU syntax assembly expects immediate values to be presented as encoded. The instruction `MOVK x1, #0x40000` results in the following message: `error: immediate must be an integer in range [0, 65535]`.

Hexadecimal literals

ARM syntax assembly provides two methods for specifying hexadecimal literals, the prefixes "&" and "0x".

For example, the following are equivalent:

```
ADD     r1, #0xAF
ADD     r1, #&AF
```

GNU syntax assembly only supports the "0x" prefix for specifying hexadecimal literals. Convert any "&" prefixes to "0x".

n_base-n-digits format

ARM syntax assembly lets you specify numeric literals using the following format:

n`_base-`*n*`-digits`

For example:

- `2_1101` is the binary literal 1101 (13 in decimal).
- `8_27` is the octal literal 27 (23 in decimal).

GNU syntax assembly does not support the *n*`_base-`*n*`-digits` format. Convert all instances to a supported numeric literal form.

For example, you could convert:

```
ADD     r1, #2_1101
```

to:

```
ADD     r1, #13
```

or:

```
ADD     r1, #0xD
```

Related information

GNU Binutils - Using as: Integers.
armasm User Guide: Syntax of numeric literals.

4.9 Operators

ARM syntax assembly and GNU syntax assembly provide different methods for specifying some operators.

The following table shows how to translate ARM syntax operators to GNU syntax operators.

Table 4-1 Operator translation

ARM syntax operator	GNU syntax operator
:OR:	|
:AND:	&
:NOT:	~
:SHL:	<<
:SHR:	>>
:LOR:	||
:LAND:	&&

Related information

GNU Binutils - Using as: Infix Operators.
armasm User Guide: Unary operators.
armasm User Guide: Shift operators.
armasm User Guide: Addition, subtraction, and logical operators.

4.10 Alignment

Data and code must be aligned to appropriate boundaries.

For example, The T32 pseudo-instruction `ADR` can only load addresses that are word aligned, but a label within T32 code might not be word aligned. You must use an alignment directive to ensure four-byte alignment of an address within T32 code.

An alignment directive aligns the current location to a specified boundary by padding with zeros or `NOP` instructions.

ARM syntax

ARM syntax assembly provides the `ALIGN` *n* directive, where *n* specifies the alignment boundary in bytes. For example, the directive `ALIGN 128` aligns addresses to 128-byte boundaries.

ARM syntax assembly also provides the `PRESERVE8` directive. The `PRESERVE8` directive specifies that the current file preserves eight-byte alignment of the stack.

GNU syntax

GNU syntax assembly provides the `.balign` *n* directive, which uses the same format as `ALIGN`.

Convert all instances of `ALIGN` *n* to `.balign` *n*.

Note

GNU syntax assembly also provides the `.align` *n* directive. However, the format of *n* varies from system to system. The `.balign` directive provides the same alignment functionality as `.align` with a consistent behavior across all architectures.

Convert all instances of `PRESERVE8` to `.eabi_attribute 25, 1`.

Related information

GNU Binutils - Using as: ARM Machine Directives.
GNU Binutils - Using as: .align.
GNU Binutils - Using as: .balign.
armasm User Guide: REQUIRE8 and PRESERVE8.
armasm User Guide: ALIGN.

4.11 PC-relative addressing

ARM syntax assembly and GNU syntax assembly provide different methods for performing PC-relative addressing.

ARM syntax

ARM syntax assembly provides the symbol `{pc}` to let you use the address of the program counter.

For example:

```
ADRP x0, {pc}
```

GNU syntax

GNU syntax assembly does not support the `{pc}` symbol. Instead, it uses the special dot "." character, as follows:

```
ADRP x0, .
```

Related information

GNU Binutils - Using as: The Special Dot Symbol.

armasm User Guide: Register-relative and PC-relative expressions.

4.12 Conditional directives

Conditional directives let you specify conditions that control whether or not to assemble a sequence of assembly code.

The following table shows how to translate ARM syntax conditional directives to GNU syntax directives:

Table 4-2 Conditional directive translation

ARM syntax directive	GNU syntax directive
`IF`	`.if`
`IF :DEF:`	`.ifdef`
`IF :LNOT::DEF:`	`.ifndef`
`ELSE`	`.else`
`ELSEIF`	`.elseif`
`ENDIF`	`.endif`

Related information

GNU Binutils - Using as: .if.
GNU Binutils - Using as: .else.
GNU Binutils - Using as: .elseif.
GNU Binutils - Using as: .endif.
armasm User Guide: IF, ELSE, ENDIF, and ELIF.

4.13 Data definition directives

Data definition directives allocate memory, define data structures, and set initial contents of memory.

The following table shows how to translate ARM syntax data definition directives to GNU syntax directives:

Note

This list only contains examples of common data definition assembly directives. It is not exhaustive.

Table 4-3 Data definition directives translation

ARM syntax directive	GNU syntax directive	Description
`DCB`	`.byte`	Allocate one-byte blocks of memory, and specify the initial contents.
`DCW`	`.hword`	Allocate two-byte blocks of memory, and specify the initial contents.
`DCD`	`.word`	Allocate four-byte blocks of memory, and specify the initial contents.
`DCQ`	`.quad`	Allocate eight-byte blocks of memory, and specify the initial contents.
`SPACE`	`.space`	Allocate a zeroed block of memory.

Related information

GNU Binutils - Using as: .byte.
GNU Binutils - Using as: .word.
GNU Binutils - Using as: .hword.
GNU Binutils - Using as: .quad.
GNU Binutils - Using as: .space.

4.14 Instruction set directives

Instruction set directives instruct the assembler to interpret subsequent instructions as either A32 or T32 instructions.

The following table shows how to translate ARM syntax instruction set directives to GNU syntax directives:

Table 4-4 Instruction set directives translation

ARM syntax directive	GNU syntax directive	Description
`ARM` or `CODE32`	`.arm` or `.code 32`	Interpret subsequent instructions as A32 instructions.
`THUMB` or `CODE16`	`.thumb` or `.code 16`	Interpret subsequent instructions as T32 instructions.

Related information

GNU Binutils - Using as: ARM Machine Directives.
armasm User Guide: ARM or CODE32 directive.
armasm User Guide: CODE16 directive.
armasm User Guide: THUMB directive.

4.15 Miscellaneous directives

Miscellaneous directives perform a range of different functions.

The following table shows how to translate ARM syntax miscellaneous directives to GNU syntax directives:

Table 4-5 Miscellaneous directives translation

ARM syntax directive	GNU syntax directive	Description
`foo EQU 0x1C`	`.equ foo, 0x1C`	Assigns a value to a symbol. Note the rearrangement of operands.

`EXPORT StartHere`
`GLOBAL StartHere`
	`.global StartHere`
	`.type StartHere, @function`
		Declares a symbol that can be used by the linker (that is, a symbol that is visible to the linker).
		`armasm` automatically determines the types of exported symbols. However, `armclang` requires that you explicitly specify the types of exported symbols using the `.type` directive.
		If the `.type` directive is not specified, the linker outputs warnings of the form:
		`Warning: L6437W: Relocation #RELA:1 in test.o(.text) with respect to symbol...`
		`Warning: L6318W: test.o(.text) contains branch to a non-code symbol symbol.`

`GET file` `INCLUDE file`	`.include file`	Includes a file within the file being assembled.
`IMPORT foo`	`.global foo`	Provides the assembler with a name that is not defined in the current assembly.
`INCBIN`	`.incbin`	Partial support, `armclang` does not fully support `.incbin`.
`INFO n, "string"`	`.warning "string"`	The `INFO` directive supports diagnostic generation on either pass of the assembly (specified by *n*). The `.warning` directive does not let you specify a particular pass.
`ENTRY`	`armlink --entry=location`	The `ENTRY` directive declares an entry point to a program. `armclang` does not provide an equivalent directive. Use `armlink --entry=location` to specify the entry point directly to the linker, rather than defining it in the assembly code.
`END`	`.end`	Marks the end of the assembly file.

Related information

GNU Binutils - Using as: .type.
GNU Binutils - Using as: .warning.
GNU Binutils - Using as: .equ.
GNU Binutils - Using as: .global.
GNU Binutils - Using as: .include.
GNU Binutils - Using as: .incbin.
armasm User Guide: ENTRY.
armasm User Guide: END.
armasm User Guide: INFO.
armasm User Guide: EXPORT or GLOBAL.
armlink User Guide: --entry.

4.16 Symbol definition directives

Symbol definition directives declare and set arithmetic, logical, or string variables.

The following table shows how to translate ARM syntax symbol definition directives to GNU syntax directives:

Note

This list only contains examples of common symbol definition directives. It is not exhaustive.

Table 4-6 Symbol definition directives translation

ARM syntax directive	GNU syntax directive	Description
`LCLA var`	`.set var, 0`	Declare a local arithmetic variable, and initialize its value to 0.
`LCLL var`	`.set var, FALSE`	Declare a local logical variable, and initialize its value to FALSE.
`LCLS var`	`.set var, ""`	Declare a local string variable, and initialize its value to a null string.
`GBLA var`	`.global var` `.set var, 0`	Declare a global arithmetic variable, and initialize its value to 0.
`GBLL var`	`.global var` `.set var, FALSE`	Declare a global logical variable, and initialize its value to FALSE.
`GBLS var`	`.global var` `.set var, ""`	Declare a global string variable, and initialize its value to a null string.
`var SETA expr`	`.set var, expr`	Set the value of an arithmetic variable.
`var SETL expr`	`.set var, expr`	Set the value of a logical variable.
`var SETS expr`	`.set var, expr`	Set the value of a string variable.
`foo RN 11`	`foo .reg r11`	Define an alias foo for register R11.
`foo QN q5.I32`	`foo .qn q5.i32`	Define an I32-typed alias foo for the quad-precision register Q5.
`foo DN d2.I32`	`foo .dn d2.i32`	Define an I32-typed alias foo for the double-precision register D2.

Related information

GNU Binutils - Using as: ARM Machine Directives.
GNU Binutils - Using as: .global.
GNU Binutils - Using as: .set.