ARM® Debug Interface
Architecture Specification
ADlv5.0 to ADlv5.2
ARM Debug Interface Architecture Specification
ADIv5.0 to ADIv5.2

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Release Information

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ADlv5.0 to ADlv5.2

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Glossary
Preface

This preface introduces the *ARM Debug Interface Architecture Specification ADIv5.0 to ADIv5.2*. It contains the following sections:

- *About this manual* on page x.
- *Using this book* on page xi.
- *Conventions* on page xiii.
- *Additional reading* on page xv.
- *Feedback* on page xvi.
About this manual

This manual describes the Architecture Specification for the ARM Debug Interface v5, ADIv5.0 to ADIv5.2 (ADIv5).

Intended audience

This specification is written for system designers and engineers who specify, design, or implement ADIv5-compliant debug interfaces. The audience includes system designers and engineers who specify, design, or implement a System-on-Chip (SoC) that incorporates an ADIv5-compliant debug interface.

This specification is also intended for engineers who work with an ADIv5-compliant debug interface. This audience includes designers and engineers who:

- Specify, design, or implement hardware debuggers.
- Specify, design, or write debug software.

These engineers have no control over the design decisions that are made in the ADIv5 interface implementation to which they connect, but must be able to identify the ADIv5 interface components that are present, and understand how they operate.

This specification provides an architectural description of an ADIv5 interface. It does not describe how to implement the interface.
Preface
Using this book

This specification is organized into the following chapters:

**Chapter A1 About the ARM Debug Interface**
Read this chapter for a high-level view of the ARM Debug Interface (ADI). This chapter defines the logical subdivisions of an ADI, and summarizes the design choices that are made when implementing an ADI.

**Chapter B1 About the DP**
Every ADI includes a single Debug Port (DP). The DP can be one of several types: a JTAG Debug Port (JTAG-DP), a Serial Wire Debug Port (SW-DP), or a Serial Wire/JTAG Debug Port (SWJ-DP). Read this chapter for a description of the features that must be implemented on the DP of any ADI.

**Chapter B2 DP Reference Information**
Read this chapter for detailed reference information that applies to all DP types.

**Chapter B3 The JTAG Debug Port (JTAG-DP)**
Read this chapter for a description of the JTAG Debug Port (JTAG-DP), and in particular, the Debug Test Access Port State Machine (DBGTAPSM) and the scan chains that access the JTAG-DP.

**Chapter B4 The Serial Wire Debug Port (SW-DP)**
Read this chapter for a description of the Serial Wire Debug Port (SW-DP), and the Serial Wire Debug (SWD) protocols, which are used to access an SW-DP.

**Chapter B5 The Serial Wire/JTAG Debug Port (SWJ-DP)**
Read this chapter for a description of multiple protocol interoperability as implemented in the Serial Wire/JTAG Debug Port (SWJ-DP) CoreSight component.

**Chapter C1 About the AP**
Read this chapter for a description of ADI Access Ports (APs), and details of the features that every AP must implement.

**Chapter C2 The Memory Access Port (MEM-AP)**
Read this chapter for a description of the ADI Memory Access Port (MEM-AP).

**Chapter C3 The JTAG Access Port (JTAG-AP)**
Read this chapter for a description of the ADI JTAG Access Port (JTAG-AP).

**Chapter D1 Component and Peripheral ID Registers**
Read this chapter for a description of the Component and Peripheral ID Registers. These registers are part of the register space of every debug component that complies with the ADIv5 specification.

**Chapter D2 About ROM Tables**
Read this chapter for a general description of ARM debug component ROM Tables. Any ADI can include a ROM Table, and an ADI with more than one debug component must include at least one ROM Table.

**Chapter D3 Class 0x1 ROM Tables**
Read this chapter for detailed information about Class 0x1 ROM Tables. Class 0x1 ROM Tables have a Component class value of 0x1.

**Chapter D4 Class 0x9 ROM Tables**
Read this chapter for detailed information about Class 0x9 ROM Tables. Class 0x9 ROM Tables have a Component class value of 0x9, which identifies them as CoreSight components. A value of the Component Architecture ID of 0xF7 identifies the component as a Class 0x9 ROM Table.
Appendix E1 **Standard Memory Access Port Definitions**
Read this appendix for information on implementing the Memory Access Port (MEM-AP).

Appendix E2 **Cross-over with the ARM Architecture**
Read this appendix for a description of the required or recommended options for the ARM Debug Interface for ARM architecture profiles.

Appendix E3 **Pseudocode Definition**
Read this appendix for a description of the pseudocode that is used in this document.

**Glossary**
Read the Glossary for definitions of some of the terms that are used in this manual.
Conventions

The following sections describe conventions that this specification can use:

- **Typographic conventions**.
- **Signals**.
- **Timing diagrams**.
- **Numbers on page xiv**.
- **Pseudocode descriptions on page xiv**.

**Typographic conventions**

The typographical conventions are:

- **italic**: Introduces special terminology, and denotes citations.
- **bold**: Denotes signal names, and is used for terms in descriptive lists, where appropriate.
- **monospace**: Used for assembler syntax descriptions, pseudocode, and source code examples. Also used in the main text for instruction mnemonics and for references to other items appearing in assembler syntax descriptions, pseudocode, and source code examples.
- **SMALL CAPITALS**: Used for a few terms that have specific technical meanings, and are included in the Glossary.
- **Colored text**: Indicates a link:
  - A URL, for example [http://infocenter.arm.com](http://infocenter.arm.com).
  - A cross-reference, that, if it is not on the current page, includes the page number of the referenced information. For example, Pseudocode descriptions on page xiv.
  - A link, to a chapter or appendix, or to a glossary entry, or to the section of the document that defines the colored term, for example AMBA.

**Signals**

The signal conventions are:

- **Signal level**: The level of an asserted signal depends on whether the signal is active-HIGH or active-LOW. Asserted means:
  - HIGH for active-HIGH signals.
  - LOW for active-LOW signals.
- **Lower-case n**: At the start or end of a signal name denotes an active-LOW signal.
- **Prefix DBG**: Denotes debug signals.

**Timing diagrams**

The figure that is named Key to timing diagram conventions on page xiv explains the components that are used in timing diagrams. Variations, when they occur, have clear labels. You must not assume any timing information that is not explicit in the diagrams.

Shaded bus and signal areas are undefined, so the bus or signal can assume any value within the shaded area at that time. The actual level is unimportant and does not affect normal operation.
Key to timing diagram conventions

Timing diagrams sometimes show single-bit signals as HIGH and LOW at the same time and they look similar to the bus change shown in Key to timing diagram conventions. If a timing diagram shows a single-bit signal in this way, its value does not affect the accompanying description.

Numbers

Numbers are normally written in decimal. Binary numbers are preceded by 0b, and hexadecimal numbers by 0x. In both cases, the prefix and the associated value are written in a monospace font, for example 0xFFFF0000.

Pseudocode descriptions

This specification uses a form of pseudocode to provide precise descriptions of the specified functionality. This pseudocode is written in a monospace font, and is described in Appendix E3 Pseudocode Definition.
Additional reading

This section lists relevant publications from ARM and third parties.

See the Infocenter http://infocenter.arm.com, for access to ARM documentation.

ARM publications

See the following documents for other information that is relevant to this specification:

• ARM® Architecture Reference Manual, ARMv8, for ARMv8-A architecture profile (ARM DDI 0487).
• ARM® v8-M Architecture Reference Manual (ARM DDI 0553).
• ARM® Embedded Trace Macrocell Architecture Specification, ETMv4 (ARM IHI 0064).
• ARM® CoreSight™ Architecture Specification (ARM IHI 0029).
• ARM® CoreSight™ SoC-400 Technical Reference Manual (ARM 100536).
• AMBA® Specification (Rev 2.0) (ARM IHI 0011).
• AMBA® AXT™ and ACE™ Protocol Specification (ARM IHI 0022).
• ARM® AMBA® 5 AHB™ Protocol Specification (ARM IHI 0033).
• AMBA® APB Protocol Specification (ARM IHI 0024).

Other publications

The following books are referred to in this specification, or provide more information:

• JEDEC Standard Manufacturer’s Identification Code (JEDEC JEP106).
Feedback

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If you have comments on the content of this specification, send an e-mail to errata@arm.com. Give:

• The title.
• The number, ARM IHI 0031D.
• The page numbers to which your comments apply.
• A concise explanation of your comments.

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Part A

The ARM Debug Interface
Chapter A1
About the ARM Debug Interface

This chapter introduces the ARM Debug Interface (ADI) architecture and summarizes the design decisions that are required for an ADI implementation. It contains the following sections:

• ADI versions on page A1-20.
• Purpose of the ADI on page A1-23.
• The subdivisions of an ADIv5 implementation on page A1-25.
• The Debug Port (DP) on page A1-27.
• Design choices and implementation examples on page A1-32.
A1.1 ADI versions

The ARM Debug Interface version 5 (ADIv5) is the fifth major version of the ARM Debug Interface.

Note

The term ADIv5 refers to ADIv5.0, ADIv5.1, ADIv5.2, or any other release of the fifth major revision of ADI.

ADI versions before v5 are based on the IEEE 1149.1 JTAG interface, but are intended only for accessing ARM processor cores and Embedded Trace Macrocells (ETMs):

Debug interface versions 1 and 2

Implemented on the ARM7TDMI® and ARM9® families of processor cores.

Debug interface version 3

Introduced for the ARM10™ processor family.

ADIv4

The first version of the ADI to be linked with an ARM architecture version, rather than an implementation of an ARM processor core. ARM recommends that ADIv4 is used with implementations of the ARMv5 architecture.

ADIv5 has the following major advantages:

- ADIv5 interfaces can access a greater range of devices.
- Implementing the ADI can be separated from implementing the resource, which makes it easier to reuse implementations. However, this separation is not required.
- Use of the ADIv5 abstractions permits reusing software tools, for example debuggers.

Debug interfaces that implement ADI versions older than ADIv5 require the physical connection to the interface to use an IEEE 1149.1 JTAG interface. ADIv5 specifies two alternatives for the physical connection:

- An IEEE 1149.1 JTAG interface.
- A Serial Wire Debug interface with a low pin count.

The main components of ADIv5 are split between two main architectures:

- The Access Port (AP) architecture.
- The Debug Port (DP) architecture.

A1.1.1 About the minor versions of ADIv5

ADI versions 5.1 and 5.2 are backwards-compatible extensions of the original ADIv5 specification. From the introduction of ADIv5.1, the original ADIv5 specification is described as ADIv5.0.

Note

ADIv5.1 was originally defined only as a supplement to the original ARM Debug Interface v5 Architecture Specification, which corresponds to issue A of this document. From issue B of this document, ARM IHI 0031B, the specification integrates the descriptions of ADIv5.0, ADIv5.1, and ADIv5.2.

Features that are defined by ADIv5.0

ADIv5.0 defines:

- Two Debug Ports, JTAG-DP and SW-DP.
- Two Access Ports:
  - JTAG-AP, for accessing legacy JTAG components.
A1 About the ARM Debug Interface
A1.1 ADI versions

MEM-AP, for accessing memory and components with memory-mapped interfaces.

• The identification model for Access Ports.
• A discovery mechanism for components that are attached to a MEM-AP.

Features added in v5.1

ADIv5.1 formalizes version numbering of Debug Ports:

• The programmers’ model of the JTAG-DP defined by ADIv5.0 is defined as Debug Port architecture version 0 (DPv0).
• The programmers’ model of the SW-DP defined by ADIv5.0 is defined as Debug Port architecture version 1 (DPv1).

ADIv5.1 adds the following functionality:

• Extensions to the AP identification model.
• Standard definitions for MEM-AP implementations for AMBA bus protocols.
• JTAG support in Debug Port architecture version 1.
• The Minimal Debug Port extension.
• Debug Port architecture version 2 (DPv2).
• Multiple protocol interoperability extensions that provide the following features:
  — Simple switching between Serial Wire Debug and JTAG protocols. For more information, see Chapter B5 The Serial Wire/JTAG Debug Port (SWJ-DP).
  — A dormant state, for interoperability with other protocols. For more information, see Switching between SWD and JTAG on page B5-128.
• Serial Wire Debug protocol version 2, that provides a multi-drop capability. For more information, see Chapter B4 The Serial Wire Debug Port (SW-DP).
• The Minimal Debug Port (MINDP) extension, which is a simplified version of the Debug Port that is intended for low gate-count implementations. For more information, see MINDP, Minimal DP extension on page B1-40.

Features added in ADIv5.2

ADIv5.2 adds the following functionality:

• Extensions to the MEM-AP programmers’ model to support:
  — Large physical address spaces of up to 64 bits.
  — Data sizes greater than 32 bits.
  — Barrier operations.
• Extended definitions of MEM-AP to include extensions for:
  — AMBA AXI3, AXI4, and AXI4-Lite.
  — AMBA ACE.
• Recommended implementations for:
  — ARMv7-A processors including the Large Physical Address Extension.
  — ARMv8-A processors.
• In addition to ROM Tables with a CIDR1.CLASS of 0x1, ROM Tables with a CIDR1.CLASS of 0x9, are permitted, provided their DEVID.FORMAT is 0x0, which indicates that they use the 32-bit ROM format 0. For more information, see ROM Table Types on page D2-227.
In addition to using 4-bit JTAG IR instruction encodings, it is permitted to use 8-bit encodings. The 8-bit encodings are specified in IR scan chain and IR instructions on page B3-91.

Relaxation of the CDBGWRUPREQ/CDBGWRUPACK handshake mechanism. For more information, see DLCR, Data Link Control register on page B2-61.
A1.2 Purpose of the ADI

The ADI provides access to debug functionality that is provided by debug components in an embedded System on Chip (SoC).

This section summarizes various types of debug functionality that can be found in SoCs. It contains the following subsections:

- Embedded core debug functionality.
- System debug functionality.
- Compatibility between CoreSight and ARM debug interfaces on page A1-24.

For information about compatibility with the CoreSight™ architecture, see Compatibility between CoreSight and ARM debug interfaces on page A1-24.

A1.2.1 Embedded core debug functionality

An embedded microprocessor can provide the following debug features to enable the debugging of applications:

**Processor state modification**

Facilities that enable an external host to modify the state of the processor, as defined by the contents of the internal registers and the memory system.

**Processor state assessment**

Facilities that enable an external host to assess the state of the processor by providing access to the contents of the internal registers and the memory system.

**Programming debug events**

Facilities that allow an external host to program debug events. An external host must be able to configure the debug logic so that when a special event occurs, such as the program flow reaching a certain instruction in the code, the core enters a special execution mode in which its state can be examined and modified by an external system. In this chapter, this special execution mode is referred to as Debug state.

**Enter or exit Debug state**

Facilities to allow an external system to force the processor to enter or exit Debug state, and determine when the core enters or leaves Debug state.

**Trace features**

Trace the program flow that is associated with programmable events.

Examples of technologies that provide these facilities are:

- The ARMv8 Debug Architecture. For more information, see the ARM® Architecture Reference Manual, ARMv8, for ARMv8-A architecture profile.
- The Embedded Trace Macrocell. For more information, see the ETM Architecture Specification.

ADIv5 implementations can also access legacy components that implement an IEEE 1149.1 JTAG interface, which enables accessing debug resources in processors that implement earlier versions of the ADI.

A1.2.2 System debug functionality

The scope of debug information extends beyond the boundaries of an embedded microprocessor core, and includes the following elements:

- Components outside the cores that are embedded in the SoC.
- The interconnection fabric of the system.

To enable debugging these elements, a SoC can provide the following system-level debug features:
External host access
   Facilities that enable an external host to access the following debug information:
   • System state parameters that might not be visible to the embedded microprocessor core.
   • Trace information about the interconnection fabric, for example accesses by the microprocessor core, or accesses by other devices such as Direct Memory Access (DMA) engines.

Access to diagnostic information
   A mechanism for the efficient collection and streaming of diagnostic information, for example program trace.

Diagnostic messaging
   Mechanisms for low-intrusion diagnostic messaging between software and debugger.

Cross-triggering
   Cross-triggering mechanisms that enable debug components to signal to each other.

Examples of technologies that provide these facilities are:
   • The ADIv5 DAP.
   • The CoreSight debug architecture. For more information, see the CoreSight Architecture Specification.
   • CoreSight components. For more information, see the CoreSight SoC Technical Reference Manual.

A1.2.3 Compatibility between CoreSight and ARM debug interfaces

ADIv5 is compatible with the ARM CoreSight architecture:
   • ADIv5 can be used to access and control CoreSight-compatible components.
   • The ADIv5 specification does not require debug components to comply with the CoreSight architecture.
A1.3 The subdivisions of an ADIv5 implementation

An implementation of the ADI is called a Debug Access Port (DAP). A DAP provides a debugger with a standard interface to access debug resources in systems that use resource-specific methods to expose their debug information.

A1.3.1 Connections to the ADI

The logical block diagram in Figure A1-1 shows how an ADI implementation is connected between a debugger and the system to be debugged.

![Figure A1-1 Block diagram of an ADIv5 implementation](image)

To access a debug resource, the debugger passes the appropriate resource address information to the DAP, which executes the request by selecting the appropriate resource and then accessing resource-specific transport methods that are presented by the system to be debugged. The DAP consists of the following elements:

**Access Port (AP)**

An AP uses a resource-specific transport mechanism to access debug information in the system to be debugged, and passes the information to the DP using the AP Access mechanism that is specified in this document. Examples of debug resources are:

- The debug registers of the core processor.
- ETM or trace port debug registers.
- A ROM Table, see Chapter D2 About ROM Tables.
- A memory system.
- A legacy JTAG device.

A debugger uses APACC accesses to exchange information held in the AP registers, as described in Access Ports (APs) on page A1-28

---

**Note**

A DAP must contain at least one AP, but if needed an ADI can implement multiple APs.

**Debug Port (DP)**

The DP provides a debugger with a common interface to access the information that is held in the APs. The DP includes the following elements:

- A physical connection to the debugger. ADIv5 supports the following physical connection types:
  - JTAG debug port (JTAG-DP).
  - Serial Wire Debug Port (SW-DP).
  - Serial Wire JTAG debug port (SWJ-DP).

For details about the supported physical connections, see Chapter B1 About the DP.
A1.3 The subdivisions of an ADIv5 implementation

• DP registers, which hold information that is required to support the transport mechanism that is implemented by the DAP, as described in Accessing the DAP. A debugger uses the DPACC scan chain to exchange information held in the DP registers.

For detailed information about the DP registers, see DP register descriptions on page B2-53.

Resource-specific transport

The connection between the DP and the APs, which performs the following tasks:

• Select the appropriate debug resource, based on the address information that was provided by the debugger.
• Transport the data between the APs and the DP.

A1.3.2 Accessing the DAP

The diagram in Figure A1-1 on page A1-25 shows how a debugger logically accesses the DP and AP registers.

• Although the DP is involved in responding to APACC requests, this involvement is transparent to the debugger at the level of the APACC.

• The debugger can use the DPACC method to access the DP registers, and achieve one of the following:
  — Set the parameters for an imminent APACC. For example, the selection of a particular AP is done by setting the DP register SELECT.
  — Read status information for a previous APACC. For example, the status of the sticky flags resulting from previous resource accesses is available from the DP register CTRL/STAT.

For details about the communication between the debugger and the DAP, see The Debug Port (DP) on page A1-27.

Note

Although this specification defines the ADIv5 in terms of the elements that are shown in Figure A1-1 on page A1-25, it is not mandatory to structure implementations in this way. The elements that are shown in the figure, however, provide a convenient representation for describing the programmers’ model, which is the objective of this specification.
A1.4 The Debug Port (DP)

An ADI implementation includes a single DP that provides the following features:

- An external physical connection to the interface. Which signals make up the physical connection depends on the DP type.
- A method to obtain the identification code of the DAP.
- DP and AP access methods, which depend on the DP type.
- A method to abort a register access that appears to have failed.

The ADIv5 specification supports the following DP types:

**The JTAG Debug Port (JTAG-DP)**

The JTAG-DP is accessed by IEEE 1149.1-compliant DBGTAP scan chains to read and write register information.

- For more information about DBGTAP scan chains, see Chapter B3 The JTAG Debug Port (JTAG-DP).
- IEEE Standard 1149.1 Test Access Port and Boundary Scan Architecture contains detailed information about the requirements for JTAG scan chains.

**The Serial Wire Debug Port (SW-DP)**

The SW-DP is a two-pin serial interface that uses a packet-based protocol to read or write registers. The protocol requires the following steps for communication between the host, which is the debugger, and the target, which is the ADI:

1. A host-to-target packet request, which includes whether the required access is to a DP register (DPACC) or to an AP register (APACC), and a two-bit register address.
2. A target-to-host acknowledge response.
3. A data transfer phase, if necessary. This phase can be target-to-host or host-to-target, depending on the request that is made in the first phase.

For details about the SW-DP protocol, see Chapter B4 The Serial Wire Debug Port (SW-DP).

**The Serial Wire/JTAG Debug Port (SWJ-DP)**

The SWJ-DP interface combines the serial wire debug (SWD) and JTAG Data Link protocols using the following mechanism:

- The pins that carry the signals are shared between the two options.
- The debugger can select which of the protocols it wants to use.

For details about how to implement the SWJ-DP, see Chapter B5 The Serial Wire/JTAG Debug Port (SWJ-DP).
A1.5 Access Ports (APs)

An AP uses a resource-specific transport mechanism to access debug information in the system to be debugged, and passes the information to the DP from where it can be accessed by a debugger using a standardized protocol over a standard physical connection.

The implementation of an AP depends on the resources it accesses. This specification includes programmers’ models for following two types of resources:

- Memory-mapped resources, such as debug peripherals, for which ADIv5 defines a Memory Access Port (MEM-AP) programmers’ model. For a complete description of the MEM-AP programmers’ model, see Guide to the detailed description of a MEM-AP on page A1-30.
- Legacy IEEE 1149.1 JTAG devices, for which ADIv5 defines a JTAG Access Port (JTAG-AP) and associated programmers’ model. For a complete description of the JTAG-AP programmers’ model, see Guide to the detailed description of a JTAG-AP on page A1-31.

Note

- This specification does not specify exact requirements for the transport between the AP and the resource. In particular, it does not require a MEM-AP to use a bus to connect to the system being debugged. For example, ADIv5 might be directly integrated into the resource. In logical terms, however, a MEM-AP always accesses a memory-mapped resource in the system being debugged, which is why this specification describes MEM-AP accesses to the system being debugged as memory accesses.
- In the future, more ARM APs might become available.
- An ADI can include APs that are specified by companies other than ARM.

All Access Ports must follow a base standard for identification, and debuggers must be able to recognize and ignore Access Ports that they do not support. For more information, see Chapter C1 About the AP.

As described in The subdivisions of an ADIv5 implementation on page A1-25:

- The simplest ADI has only one AP. This AP can be either a MEM-AP or a JTAG-AP.
- ADIs can have multiple APs. For example:
  - A mixture of MEM-APs and JTAG-APs.
  - All MEM-APs.
  - All JTAG-APs.
- Debuggers must be able to recognize and ignore unsupported APs.

For more information, see Chapter C1 About the AP.

A1.5.1 Using the Debug Port to access Access Ports

Figure A1-2 on page A1-30 shows the different levels between the physical connection to the debugger and the debug resources of the system being debugged. These levels are designed to enable efficient access to the system being debugged, and several levels provide registers within the DAP. This section describes how these register accesses are implemented.

The DAP supports two types of accesses, Debug Port (DP) accesses and Access Port (AP) accesses. Because debuggers usually have serial interfaces, the methods of making these accesses are kept as short as possible, and all accesses are 32-bits.

The description that is given here is of scan chain access to the registers, from a debugger that is connected to a JTAG Debug Port. However, the process is similar when the access is from a Serial Wire Debug interface connection to an SW-DP. Differences when accessing the registers from a Serial Wire Debug interface connection are described in Chapter B4 The Serial Wire Debug Port (SW-DP).

Every AP or DP access transaction from the debugger includes two address bits, A[3:2]:

- For a DP register access, the address bits A[3:2] and SELECT.DPBANKSEL determine which register is accessed.
For an AP register access, SELECT.APSEL selects an AP to access, and the address bits A[3:2] are combined with SELECT.APBANKSEL to determine which AP register is accessed, as shown in Figure A1-2 on page A1-30. The two address bits A[3:2] are decoded to select one of the four 32-bit words from the register bank that is indicated by SELECT.APBANKSEL in the AP indicated by SELECT.APSEL.

Bits[1:0] of all AP and DP register addresses are 0b00.

For example, to access the register at address 0x14 in the AP that is selected when SELECT.APSEL is 0x00, the debugger must:

- Use a DP register write to set:
  - SELECT.APSEL to 0x00.
  - SELECT.APBANKSEL to 0x1.

- Use an AP register access with A[3:2] = 0b01.

The DAP combines A[3:2] with SELECT.APBANKSEL to generate the AP register address, 0x14. The debugger can access any of the four registers from 0x10 to 0x1C without changing SELECT.

This access model is shown in Figure A1-2 on page A1-30. This figure shows how the contents of the SELECT register are combined with the A[3:2] bits of the APACC scan-chain to form the address of a register in an AP. Other parts of the JTAG-DP are also shown. These parts are explained in greater detail in later sections.

- Figure C2-1 on page C2-149, for a MEM-AP implementation.
- Figure C3-1 on page C3-186, for a JTAG-AP implementation.

These figures give more detail of the connections to the debug or system resources.
A1.5 Guide to the detailed description of a MEM-AP

To understand the operation and use of a MEM-AP, you must understand:

- The MEM-AP itself.
- The MEM-AP registers.
- The standard debug components registers that you access through the MEM-AP.

The MEM-AP is described in the following chapters of this specification:

- Chapter C1 About the AP.
- Chapter C2 The Memory Access Port (MEM-AP).
The MEM-AP provides access to zero, one, or more debug components. Any debug component that complies with the ARM Generic Identification Registers specification implements a set of Component Identification Registers. These registers are described in Chapter D1 Component and Peripheral ID Registers.

If the MEM-AP connects to more than one debug component, the system that is accessed by the MEM-AP must also include at least one ROM Table. ROM Tables are accessed through a MEM-AP, and are described in Chapter D2 About ROM Tables.

--- Note ---
As shown in Design choices and implementation examples on page A1-32, a system with only one functional debug component might also implement a ROM Table.

### A1.5.3 Guide to the detailed description of a JTAG-AP

To understand the operation and use of a JTAG-AP, you must understand:

- The JTAG-AP itself.
- The JTAG-AP registers.

The JTAG-AP is described in the following chapters of this specification:

- Chapter C1 About the AP.
- Chapter C3 The JTAG Access Port (JTAG-AP).

The JTAG-AP provides a standard JTAG connection to one or more legacy components. The connection between the JTAG-AP and the components is described by the IEEE 1149.1-1990 IEEE Standard Test Access Port and Boundary Scan Architecture. Details on how to use this connection are outside the scope of this specification.

### A1.5.4 Using the AP to access debug resources

Accessing the AP gives access to the system being debugged, which is shown as access to Debug resources in Figure A1-2 on page A1-30.

In summary:

- In a MEM-AP, the debug resources are logically memory-mapped. Chapter C2 The Memory Access Port (MEM-AP) section MEM-AP register accesses and memory accesses on page C2-150 describes the method for accessing these resources. The connection between the MEM-AP and a debug resource, however, is outside the scope of this specification.

- In a JTAG-AP, the debug resources are connected through a standard JTAG serial connection, as defined in IEEE 1149.1-1990 IEEE Standard Test Access Port and Boundary Scan Architecture. For more information about accessing the resources, see Chapter C3 The JTAG Access Port (JTAG-AP).
A1.6 Design choices and implementation examples

Figure A1-1 on page A1-25 introduces the components that comprise an ADI.

Before implementing an ADI, you must make some of the design choices that are described in this section, which covers following functional blocks of the interface:

- Choices for the DP.
- Choices for the APs.

Note

This Architecture Specification is written for engineers implementing an ARM Debug Interface, and for engineers using an ARM Debug Interface. If you are reading the Specification to learn more about a particular ARM Debug Interface implementation, you must understand the design choices that have been made in that implementation. Those choices might be implicit in the connections to the debug interface, but if you are uncertain which choices were made, you must contact the implementer of the debug interface for more information.

A1.6.1 Choices for the DP

The DP determines which type of physical connection the ADI presents to the debugger. A DAP has only one DP, so your choice for the DP type decides the physical connection for the entire design. You can choose from the following DP types:

- JTAG Debug Port (JTAG-DP).
- Serial Wire Debug Port (SW-DP).
- Serial Wire/JTAG Debug Port (SWJ-DP).

Note

Note the following with respect to the DP types mentioned in this document:

- In an illustration of an ADI, a component that is labeled DP can represent any of the available options.
- ARM might define more DP types in the future.

A1.6.2 Choices for the APs

An ADI always includes at least one AP, but it might contain multiple APs. The simplest ADIs use a single AP to connect to a single debug component, for example:

- A MEM-AP that connects to a single microprocessor core, as shown in Figure A1-3.
- A JTAG-AP that connects to a single legacy IEEE 1149.1 device, as shown in Figure A1-4 on page A1-33.
As explained in *ROM Tables* on page C2-148, however, a system with only a single debug component often implements a ROM Table, which requires the implementation that is shown in Figure A1-5.

Because a single ADI can include multiple APs, design choices for APs must be made at two levels:

- Choosing the number of APs in the ADI, and whether each AP is a MEM-AP or a JTAG-AP. These decisions are outlined in *Top-level AP planning choices*.
- The choices that have to be made for each implemented AP, as outlined in the following sections:

### Top-level AP planning choices

In a more complex system, there can be multiple APs, and each AP can be connected to multiple components, or multiple address spaces. An AP can be implemented as one of the following three types:

- As a Memory Access Port (MEM-AP) with a memory-mapped debug bus connection. The debug bus connects directly to one or more debug register files.
- As a MEM-AP with a memory-mapped system bus connection. The MEM-AP connection to the system bus provides access to one or more debug register files.
- As a JTAG Access Port (JTAG-AP). A JTAG-AP connects directly to one or more JTAG devices, and enables connection to legacy hardware components.

**Note**

The connection between legacy hardware components and a JTAG-AP is defined by the JTAG standard. For more information, see Chapter C3 *The JTAG Access Port (JTAG-AP)*.

If you are designing or specifying an ADI, you must decide how many APs of which types are required, which depends largely on the debug components of the system to which your ADI connects.
Figure A1-6 shows a more complex ADI, and illustrates the different AP types.

The ADIv5 architecture specification supports the following features:

- A DAP is permitted to contain multiple APs
- A single MEM-AP is permitted to access multiple register files.
- An AP is permitted to access a mixture of system memory and debug register files.

When implementing these features, however, you must observe the following conditions:

- Every AP must follow the basic standard for identification that is described this specification.
- Debuggers must have a way to ignore APs that they do not recognize.

In illustrations such as Figure A1-2 on page A1-30, the DP can be of any DP type that is defined by ADIv5.
Choices for MEM-APs

The following design decisions must be made for a MEM-AP:

**Decisions that depend on the requirements of those debug components**

The main decisions to be made for a MEM-AP concern the connection between the MEM-AP and the memory-mapped debug components that are connected to it. These decisions include:

- Whether a bus is required for this connection.
- The width of the bus, if implemented.
- The memory map of the MEM-AP address space.

**Inclusion of a ROM Table**

If a MEM-AP connects to more than one debug component, the system must include one or more ROM Tables to provide information about the debug system. A system that has only one other component does not require a ROM Table, but a system designer might choose to include one anyway. For more information, see ROM Tables on page C2-148.

**The inclusion of IMPLEMENTATION DEFINED MEM-AP features**

- Certain features must be included if the connection is less than 32-bits wide.
- The debug components can place limitations on the connection, for example a component might require 32-bit access.

For more information about conditional MEM-AP features, see:

- MEM-AP functions on page C2-152.
- MEM-AP implementation requirements on page C2-162.

For detailed information about implementing a MEM-AP, see Chapter C2 The Memory Access Port (MEM-AP).

Choices for JTAG-APs

The following design decisions must be made for a JTAG-AP:

**The number of JTAG scan chains that are connected to the JTAG-AP**

A single JTAG-AP can connect to up to eight JTAG scan chains. These scan chains can be split across multiple devices or components within the system being debugged.

**The number of TAPs in each scan chain**

A single JTAG scan chain can contain multiple TAPs. However, ARM recommends that each scan chain connected to a JTAG-AP contains only one TAP.

For more information, see Chapter C3 The JTAG Access Port (JTAG-AP).
Part B
The Debug Port
Chapter B1
About the DP

This part describes the features that are implemented by the DP.

A DP can be implemented as a JTAG Debug Port (JTAG-DP), a Serial Wire Debug Port (SW-DP), or a combined Serial Wire/JTAG Debug Port (SWJ-DP).

Requirements that apply to all DP types are described in the following sections in this chapter:
- MINDP, Minimal DP extension on page B1-40.
- Sticky flags and DP error responses on page B1-41.
- The transaction counter on page B1-43.
- Pushed-compare and pushed-verify operations on page B1-44.
- Power and reset control on page B1-46.

Reference information for all DP types is described in the following chapter:
- Chapter B2 DP Reference Information.

Specific information for each of the DP types is described in the following chapters:
- Chapter B3 The JTAG Debug Port (JTAG-DP).
- Chapter B4 The Serial Wire Debug Port (SW-DP).
- Chapter B5 The Serial Wire/JTAG Debug Port (SWJ-DP).
B1.1 MINDP, Minimal DP extension

The Minimal Debug Port (MINDP) programmers’ model is a simplified version of the DP that is intended for low gate-count implementations. MINDP implementations must use DPv1 or later.

MINDP implementations must omit the following DP features:

- Pushed-verify operation.
- Pushed-compare operation.
- The transaction counter.

MINDP implementations must observe the following conventions:

- The DPIDR.MIN field is RAO.
- The following fields of the CTRL/STAT register are RES0:
  - TRNCNT.
  - MASKLANE.
  - STICKYCMP.
  - TRNMODE.
  See also CTRL/STAT.
- The ABORT.STKCMPPCLR field is SBZ. Writing 0b1 to this bit is UNPREDICTABLE.
B1.2 Sticky flags and DP error responses

Sticky flags signal transaction errors and are persistent between transactions. When set, a sticky flag remains set until the debugger actively clears it, even if the condition that caused the flag to be set no longer applies.

After performing a series of APACC transactions, a debugger must check the CTRL/STAT register to check if an error occurred. If the debugger finds that a sticky flag is set, it clears the flag, and, if necessary, initiates extra APACC transactions to determine why the sticky flag was set. Because the flags are sticky, the debugger does not have to check the flags after every transaction, and must only check the CTRL/STAT register periodically, which reduces the overhead of checking for errors.

When an error is flagged, the current transaction is completed and subsequent APACC transactions are discarded until the sticky flag is cleared.

The DP response to an error condition and the method to clear the sticky flags depends on the DP type:

- An SW-DP immediately signals an error response.
- A JTAG-DP immediately discards all transaction and marks them as complete.

For details on how to clear the sticky flags for each DP type, see the descriptions of the sticky flag fields in CTRL/STAT, Control/Status register on page B2-55.

If pushed transactions are supported, the sticky flag CTRL/STAT.STICKY_CMP reports the result of pushed operations, see Pushed-compare and pushed-verify operations on page B1-44. CTRL/STAT.STICKY_CMP behaves in the same way as the sticky flags described in this section.

The DP uses the sticky flags in the CTRL/STAT register to signal the following transaction errors:

Read and write errors

A read or write error can occur in the DAP or in the resource being accessed. In either case, when the error is detected, the Sticky Error flag CTRL/STAT.STICKYERR is set to \(0b1\).

For example, a read or write error might occur if the debugger makes an AP transaction request while the debug power domain is powered down. See Power and reset control on page B1-46 for information about power domains.

Overrun detection

DPs support an overrun detection mode, which enables a debugger to send blocks of commands using a connection with high latency and high throughput. These commands must be sent with sufficient in-line delays to make overrun errors unlikely. To implement an overrun detection mode, the DAP can be programmed to set the Sticky Overrun flag, CTRL/STAT.STICKY_ORUN, to \(0b1\) if an overrun error occurs. In overrun detection mode, the debugger must check the Sticky Overrun flag for overrun errors after each sequence of APACC transactions.

Overrun detection mode is enabled by setting the Overrun Detect bit, CTRL/STAT.ORUNDETECT, to \(0b1\).

Due to the differences between the JTAG-DP and the SW-DP, their behavior in overrun detection mode is DATA LINK DEFINED:

**JTAG-DP** If the response to any transaction is not OK/FAULT, the Sticky Overrun flag, CTRL/STAT.STICKY_ORUN, is set to \(0b1\).

The response to a transaction is WAIT until the previous AP transaction is complete. Subsequent responses are OK/FAULT. See Sticky overrun behavior on DPACC and APACC accesses on page B3-99.

**SW-DP** If the response to any transaction is not OK, the Sticky Overrun flag, CTRL/STAT.STICKY_ORUN, is set to \(0b1\).

If a previous AP transaction is incomplete, the first response to a transaction is WAIT. Subsequent responses are FAULT, because the STICKY_ORUN flag is \(0b1\). See Sticky overrun behavior on page B4-115.

The value of the Sticky Error flag, CTRL/STAT.STICKYERR, is not changed.
The method for clearing the STICKYORUN flag depends on whether the DP type is SW-DP or JTAG-DP. See the descriptions of the STICKYORUN field in CTRL/STAT, Control/Status register on page B2-55 for more information.

If a new transaction results in an overrun error while an earlier transaction is incomplete, the earlier transaction completes normally. Other sticky flags, however, might be set to 0b1 during completion of the earlier transaction.

If the debugger clears the ORUNDETECT flag while STICKYORUN is 0b1, the resulting value of STICKYORUN is UNKNOWN.

To leave overrun detection mode, a debugger must perform the following steps:
1. Check the value of the CTRL/STAT.STICKYORUN flag.
2. If the STICKYORUN flag is 0b1, clear it to 0b0.
3. To disable overrun detection mode, clear the ORUNDETECT flag to 0b0.

**Protocol errors (SW-DP only)**

The SW-DP can generate protocol errors, for example in the case of wire-level errors.

Although protocol errors can only occur in the SW-DP, they are described in this chapter because they are part of the sticky flags error-handling mechanism.

The required response is as follows:

- If the SW-DP detects a protocol error in a packet request, the DP does not respond to the message.
- If the SW-DP detects a parity error in the data phase of a write transaction, it sets the Sticky Write Data Error flag, CTRL/STAT.WDATAERR, which is treated in the same way as the other sticky flags described in this section.

For more information, see Parity on page B4-108 and Protocol error response on page B4-114.
B1.3 The transaction counter

Except for MINDP implementations, DPs must include an AP transaction counter, CTRL/STAT.TRNCNT. The transaction counter enables a debugger to generate a sequence of AP transactions with a single AP transaction request. With a MEM-AP access, the transaction counter enables an AP transaction to generate a sequence of accesses to the connected memory system.

--- Note ---

Each AP defines which registers support sequences of transactions. If an AP register does not support sequences of transactions, or SELECT.APSEL selects an AP that is not present, then the result of a sequence of transactions to that register is UNPREDICTABLE. Reserved AP registers and the common AP IDR do not support sequences of transactions.

Examples of the use of the transaction counter are:

Memory fill operations

To facilitate memory fill operations, the transaction counter can repeatedly write a single data value that is supplied in an AP transaction request. The MEM-AP includes a mechanism that initiates a series of AP accesses and auto-increments the access address after each AP access, which results in the supplied data value being written to a sequence of memory addresses under the control of the transaction counter. For more information, see Packed transfers on page C2-158.

Fast searches and memory verification

To perform a fast search, or verify of an area of memory, the transaction counter can be used when reading from the DRW register, with pushed-compare or pushed-verify operations enabled. For examples of this application, see Pushed-compare and pushed-verify operations on page B1-44, and, for more details, Example of using the transaction counter for a pushed-compare operation on a MEM-AP on page C2-165.

Writing a value other than zero to the CTRL/STAT.TRNCNT field generates multiple AP transactions. For example, writing 0x001 to this field generates two AP transactions, and writing 0x002 generates three transactions.

If the transaction counter is not zero, it is decremented after each successful transaction. If one of the following is true, the transaction counter is not decremented and the transaction is not repeated:

- The transaction counter is 0.
- The CTRL/STAT.STICKYERR flag is 0b1.
- The CTRL/STAT.STICKYCMP flag is 0b1.

If a sequence of operations is terminated because the Sticky Error or Sticky Compare flag was set to 0b1, the transaction counter remains at the value from the last successful transaction, which enables the software to recover the location of the error, or determine where the compare or verify operation terminated.

The transaction counter does not auto-reload when it reaches zero.
B1.4 Pushed-compare and pushed-verify operations

The DP supports pushed operations. Pushed operations improve performance where writes might be faster than reads. They are used as part of in-line tests, for example Flash ROM programming and monitor communication.

Pushed operations use the following mechanism:

1. The debugger initiates an AP write transaction. The value to be written is stored in the DP.
2. The DP reads a value from the AP.
3. The DP then compares the two values and updates the Sticky Compare flag, CTRL/STAT.STICKYCMP, based on the result of the comparison. Whenever the STICKYCMP bit is set to 0b1 in this way, any outstanding transaction repeats are canceled.

Pushed operations can affect AP behavior:

- Performing an AP read transaction with pushed-compare or pushed-verify enabled causes UNPREDICTABLE behavior.
- If an SW-DP performs an AP read transaction with pushed-compare or pushed-verify, an UNKNOWN value is returned, and the read has UNPREDICTABLE side effects, even though the wire-level protocol remains coherent.
- Each AP defines which registers support pushed transactions. If an AP register does not support pushed transactions, or SELECT.APSEL selects an AP that is not present, a pushed transaction sets STICKYCMP to an UNKNOWN value. Reserved AP registers and the common AP IDR do not support pushed transactions.

To configure pushed operations, use the CTRL/STAT register:

1. Enable the appropriate transfer mode using the Transfer Mode field, TRNMODE:
   - A value of 0b01 in TRNMODE selects pushed-verify operations: if the values match, the STICKYCMP flag is set to 0b1.
   - A value of 0b10 in TRNMODE selects pushed-compare operations: if the values do not match, the STICKYCMP flag is set to 0b1.
2. Select the byte lanes to be included in the comparison using the byte lane mask field, MASKLANE. A value of 0b1 for bit $n$ of MASKLANE includes byte $n$ of the APACC write value and the current AP value in the comparison. For details about the MASKLANE field, see CTRL/STAT, Control/Status register on page B2-55.

The following are examples of applications of pushed-verify and pushed-compare MEM-AP operations:

- You can use pushed-verify to verify the contents of system memory. A series of expected values are written as AP transactions. With each write, the pushed-verify logic initiates an AP read access, and compares the result of this access with the expected value. If the values do not match, the CTRL/STAT.STICKYCMP flag is set to 0b1. This operation is described in more detail in Example of using a pushed-verify operation on a MEM-AP on page C2-164.
- You can use pushed-compare to search system memory for a given value. However, this feature is most useful when it is performed using the AP transaction counter, which is described in The transaction counter on page B1-43. This operation is described in more detail in Chapter C2 The Memory Access Port (MEM-AP) section Example of using the transaction counter for a pushed-compare operation on a MEM-AP on page C2-165.

---

*Note: Whenever an AP write transaction is performed with pushed-compare or pushed-verify enabled, the AP access that results is a read operation, not a write.*
The following example describes pushed operations on a specific AP, which makes it easier to understand how pushed operations are implemented. Consider an AP write transaction to the Data Read/Write (DRW) register in a MEM-AP with a TRNMODE value of 0b10, and a MASKLANE value of 0b0101. The following actions take place:

1. The DP holds the data value from the AP write transaction in the pushed-compare logic, see Figure A1-2 on page A1-30.

2. The AP reads from the address indicated by the MEM-AP Transfer Address Register (TAR).

3. The value that is returned by this read is compared with the value held in the pushed-compare logic. The comparison is masked using the value of MASKLANE. The example value, 0b0101, includes byte lanes zero and two in the comparison. The result is either a match or a mismatch.

4. In the example, the TRNMODE value of 0b10 selects pushed-compare operations:
   • If the result of the comparison was a mismatch, the CTRL/STAT.STICKYCMP flag is set to 0b1 and any outstanding transactions are canceled.
   • If the result of the comparison was a match, nothing happens.
B1.5 Power and reset control

The DP supports the following power and reset control fields in the CTRL/STAT register:

- Control fields for system and debug power control, CDBGPWRUPREQ, CDBGPRFUPACK, CSYSPWRUPREQ, and CSYSPWRUPACK. For more information, see System and debug power control behavior on page B2-76.
- Control fields for debug reset control, CDBG_RSTREQ and CDBG_RSTACK. For more information, see Debug reset control behavior on page B2-81.

These control bits are programmable by the debugger, and drive signals into the target system.

The DP does not provide any control bits for requesting a system reset. However, it is common for the physical interface to the debugger to include a system reset pin, nSRST, which is intended to provide hints or stimuli into existing power and reset controllers. For details about how to implement a system reset pin, see System reset control behavior on page B2-83.

The ADI does not replace the system power and reset controllers, and the ADI specification does not place any requirements on the operation of system power and reset controllers.
Chapter B2
DP Reference Information

This chapter contains the following reference information for the DP:

- System and debug power control behavior on page B2-76.
- Debug reset control behavior on page B2-81.
- System reset control behavior on page B2-83.
B2.1 DP architecture versions

This section introduces the concept of DP architecture versions and describes the DP registers for the DP architecture versions DPv0, DPv1, and DP2. It contains the following subsections:

- **DP architecture versions summary**.
- **DP architecture version 0 (DPv0) address map** on page B2-49.
- **DP architecture version 1 (DPv1) address map** on page B2-50.
- **DP architecture version 2 (DPv2) address map** on page B2-51.

One of the significant differences between the JTAG-DP and the SW-DP is how the registers are accessed. For this reason, the tables that describe the registers do not include register address information. This information, for each Debug Port type, is included at the start of the detailed description of each register.

Several aspects of the DP architecture are data link defined, and described in the following chapters:

- Chapter B3 The JTAG Debug Port (JTAG-DP).
- Chapter B4 The Serial Wire Debug Port (SW-DP).
- Chapter B5 The Serial Wire/JTAG Debug Port (SWJ-DP).

**B2.1.1 DP architecture versions summary**

Every ADI includes a single DP that is compliant with one of the DP architecture versions. Table B2-1 shows the DP architecture versions.

<table>
<thead>
<tr>
<th>Version number</th>
<th>Description</th>
<th>Debug Port Support</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>DPv0</td>
<td>DP architecture version 0</td>
<td>JTAG-DP</td>
<td>JTAG-DP in ADIv5.0</td>
</tr>
<tr>
<td>DPv1</td>
<td>DP architecture version 1</td>
<td>SW-DP, JTAG-DP</td>
<td>SW-DP in ADIv5.0</td>
</tr>
<tr>
<td>DPv2</td>
<td>DP architecture version 2</td>
<td>SW-DP, JTAG-DP</td>
<td>SW-DP version 2 in ADIv5.1</td>
</tr>
</tbody>
</table>

Although the DP architecture versions are different, their register sets are similar, as summarized in Table B2-2. For details about how the register is implemented in a specific architecture version, and if the implementation is DATA LINK DEFINED, see DP register descriptions.

<table>
<thead>
<tr>
<th>Name</th>
<th>DP architecture version</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>DPv0</td>
</tr>
<tr>
<td>ABORT</td>
<td>Yes</td>
</tr>
<tr>
<td>DPIDR</td>
<td>No</td>
</tr>
<tr>
<td>CTRL/STAT</td>
<td>Yes</td>
</tr>
<tr>
<td>SELECT</td>
<td>Yes</td>
</tr>
<tr>
<td>RDBUFF</td>
<td>Yes</td>
</tr>
<tr>
<td>DLCR</td>
<td>No</td>
</tr>
<tr>
<td>RESEND</td>
<td>No</td>
</tr>
</tbody>
</table>
B2.1.2 DP architecture version 0 (DPv0) address map

DPv0 supports JTAG-DP in ADIv5.

The JTAG-DP register accessed depends on both:
• The Instruction Register (IR) value for the DAP access.
• A[3:2] from the address field of the DAP access.

For more information, see Accessing the JTAG-DP registers.

Table B2-3 shows the DPv0 register map. The A[3:2] field of the DPACC scan chain provides bits[3:2] of the address. Bits[1:0] of the address are always 0b00.

Table B2-3 DPv0 register map

<table>
<thead>
<tr>
<th>Address</th>
<th>Name</th>
<th>Access</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x0</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>0x4</td>
<td>CTRL/STAT</td>
<td>RW</td>
</tr>
<tr>
<td>0x8</td>
<td>SELECT</td>
<td>RW</td>
</tr>
<tr>
<td>0xC</td>
<td>RDBUFF</td>
<td>R</td>
</tr>
<tr>
<td></td>
<td></td>
<td>W³</td>
</tr>
</tbody>
</table>

³ Reserved, UNPREDICTABLE.

The DP must implement the ABORT register. How this register is accessed is DATA LINK DEFINED. In JTAG-DP, the register is implemented through the ABORT instruction.

Accessing the JTAG-DP registers

The JTAG-DP registers are only accessed when the Instruction Register (IR) for the DAP access contains the DPACC or ABORT instruction. The register accesses for each instruction are:

DPACC

The DPACC scan chain accesses the DP CTRL/STAT, SELECT, and RDBUFF registers at addresses 0x0 to 0xC, although register address 0x0 is reserved, and the RDBUFF register at 0xC is always RAZ/WI on a JTAG-DP.

These registers are shown in the illustration of the JTAG-DP in Figure A1-2 on page A1-30.

ABORT

For a write access with address 0x0, the ABORT scan chain accesses the ABORT register.

For a read access with address 0x0, and for any access with address 0x4 to 0xC, the behavior of the ABORT scan chain is UNPREDICTABLE.

For more information about the JTAG-DP scan chains, see Chapter B3 The JTAG Debug Port (JTAG-DP).
### B2.1.3 DP architecture version 1 (DPv1) address map

DPv1 extends DPv0 by adding support for Serial Wire Debug protocol version 1 and defining the following extra registers:

- The Debug Port Identification Register, DPIDR.
- The Data Link Control Register, DLCR.
- More DATA LINK DEFINED registers.

In addition, the definition of some of the DPv0 registers is changed:

- The behavior of writes to bits[4:1] of the ABORT register is defined.
- The behavior on writing to bits[5:4, 1] of the CTRL/STAT register is DATA LINK DEFINED.
- The SELECT register is write only.

For most register addresses, different registers are addressed on read and write accesses. In addition, the SELECT.DPBANKSEL bit determines which register is accessed at address 0x04.

Table B2-4 shows the DPv1 register map.

#### Table B2-4 DPv1 register map

<table>
<thead>
<tr>
<th>Addressa</th>
<th>DPBANKSElb</th>
<th>Name</th>
<th>Access</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x0</td>
<td>x</td>
<td>DPIDR</td>
<td>RO</td>
<td>-</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>-</td>
<td>DATA LINK DEFINED, as either:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>-</td>
<td>• ABORT, see ABORT, Abort register</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>on page B2-53</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>• Reserved, UNPREDICTABLE</td>
</tr>
<tr>
<td>0x4</td>
<td>0x0</td>
<td>CTRL/STAT</td>
<td>RW</td>
<td>-</td>
</tr>
<tr>
<td>0x1</td>
<td></td>
<td>DLCR</td>
<td>RW</td>
<td>-</td>
</tr>
<tr>
<td>0x2 to 0xF</td>
<td></td>
<td></td>
<td>-</td>
<td>UNPREDICTABLE</td>
</tr>
<tr>
<td>0x8</td>
<td>x</td>
<td></td>
<td>RO</td>
<td>DATA LINK DEFINED</td>
</tr>
<tr>
<td></td>
<td></td>
<td>SELECT</td>
<td>WO</td>
<td>-</td>
</tr>
<tr>
<td>0xC</td>
<td>x</td>
<td>RDBUFF</td>
<td>RO</td>
<td>-</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>-</td>
<td>DATA LINK DEFINED</td>
</tr>
</tbody>
</table>

- Bits [1:0] of the address are always 0b00.
- SELECT.DPBANKSEL.

The DP must implement the ABORT register. How this register is accessed is DATA LINK DEFINED, and:

- If defined by the data link, DP register 0 is reserved for this purpose.
- In a JTAG-DP, this register is implemented through the ABORT instruction.
SW-DP DATA LINK DEFINED registers, DPv1

Table B2-5 shows the DATA LINK DEFINED SW-DP registers for a DPv1 implementation. Bits [1:0] of the address are always 0b00.

Table B2-5 SW-DP data link defined registers, DPv1

<table>
<thead>
<tr>
<th>Address</th>
<th>Name</th>
<th>Access</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x0</td>
<td>ABORT</td>
<td>WO</td>
</tr>
<tr>
<td>0x8</td>
<td>RESEND</td>
<td>RO</td>
</tr>
<tr>
<td>0xC</td>
<td>-</td>
<td>WO</td>
</tr>
</tbody>
</table>

a. Reserved, SBZ.

For a DPv1 JTAG-DP, all DATA LINK DEFINED registers are reserved. Accesses to a reserved DATA LINK DEFINED register are UNPREDICTABLE.

B2.1.4 DP architecture version 2 (DPv2) address map

DPv2 extends DPv1 with support for SWD protocol version 2 and definitions for the following registers:

- The Target Identifier register, TARGETID.
- The Data Link Protocol Identification Register, DLPIDR.
- The DATA LINK DEFINED Target Selection register, TARGETSEL.
- The EVENT Status register, EVENTSTAT.

For most register addresses, different registers are addressed on read and write accesses. In addition, an extended SELECT.DPBANKSEL field determines which register is accessed at address 0x04.

Table B2-6 shows the DPv2 register map.

Table B2-6 DPv2 address map

<table>
<thead>
<tr>
<th>Addressa</th>
<th>DPBANKSELb</th>
<th>Name</th>
<th>Access</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x0</td>
<td>x</td>
<td>DPIDR</td>
<td>RO</td>
<td>DATA LINK DEFINED, as either:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>• ABORT, see ABORT, Abort register on page B2-53</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>• Reserved, RES0</td>
</tr>
<tr>
<td>0x4</td>
<td>0x0</td>
<td>CTRL/STAT</td>
<td>RW</td>
<td>-</td>
</tr>
<tr>
<td></td>
<td>0x1</td>
<td>DLCR</td>
<td>RW</td>
<td>-</td>
</tr>
<tr>
<td></td>
<td>0x2</td>
<td>TARGETID</td>
<td>RO</td>
<td>-</td>
</tr>
<tr>
<td></td>
<td>0x3</td>
<td>DLPIDR</td>
<td>RO</td>
<td>-</td>
</tr>
<tr>
<td></td>
<td>0x4</td>
<td>EVENTSTAT</td>
<td>RO</td>
<td>-</td>
</tr>
<tr>
<td></td>
<td>All other values</td>
<td>-</td>
<td>-</td>
<td>Reserved, RES0</td>
</tr>
<tr>
<td>0x8</td>
<td>x</td>
<td>SELECT</td>
<td>RO</td>
<td>DATA LINK DEFINED</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>WO</td>
<td>-</td>
</tr>
</tbody>
</table>
The DP must implement the ABORT register. How this register is accessed is DATA LINK DEFINED, and:

- If defined by the data link, DP register 0 is reserved for this purpose.
- In JTAG-DP, the ABORT register is implemented through the ABORT instruction.

### SW-DP DATA LINK DEFINED registers, DPv2

Table B2-7 shows the DATA LINK DEFINED SW-DP registers for a DPv2 implementation:

<table>
<thead>
<tr>
<th>Address</th>
<th>SWD protocol version</th>
<th>Name</th>
<th>Access</th>
<th>See also:</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x0</td>
<td>x</td>
<td>ABORT</td>
<td>WO</td>
<td>-</td>
</tr>
<tr>
<td>0x8</td>
<td>x</td>
<td>RESEND</td>
<td>RO</td>
<td>-</td>
</tr>
<tr>
<td>0xC</td>
<td>v1</td>
<td></td>
<td>WO</td>
<td>Reserved, SBZ</td>
</tr>
<tr>
<td></td>
<td>v2</td>
<td>TARGETSEL</td>
<td>WO</td>
<td>-</td>
</tr>
</tbody>
</table>

a. Bits [1:0] of the address are always 0b00.
b. SELECT.DPBANKSEL field.

For a DPv2 JTAG-DP, all DATA LINK DEFINED registers are RES0.

### B2.1.5 Register maps, and accesses to reserved addresses

The register memory maps for the DP and the AP within the DAP are shown in:

- Figure A1-2 on page A1-30, for accesses to JTAG-DP registers.
- Figure C2-1 on page C2-149, for accesses to MEM-AP registers.
- Figure C3-1 on page C3-186, for accesses to JTAG-AP registers.

There are several reserved addresses in these register maps. Reserved AP registers are RES0.
B2.2 DP register descriptions

This section gives full descriptions of the DP registers.

The registers are listed alphabetically by name.

B2.2.1 ABORT, Abort register

The ABORT characteristics are:

**Purpose**

ABORT forces an AP transaction abort.

From a software perspective, an abort is a fatal operation. It discards any outstanding and pending transactions, and leaves the AP in an UNPREDICTABLE state. On an SW-DP, however, the sticky error bits are not cleared to 0b0.

Writing 0b1 to the ABORT.DAPABORT register bit generates a DAP abort, causing the current AP transaction to abort. This action also terminates the transaction counter, if it was active. It is IMPLEMENTATION DEFINED whether the AP propagates the abort, for example by aborting a transaction in progress.

After a DAP abort:

- It is IMPLEMENTATION DEFINED which registers, if any, in the AP that was aborted can be accessed. If the register cannot be accessed, the DP returns a WAIT response to an AP access to the register. ARM recommends that any AP register that is not directly related to a stalling transaction is accessible, to allow a debugger to diagnose the cause of the error.
- DP accesses or AP accesses to any other APs, which includes AP accesses to non-existent APs, are accepted by the DP, and defined to behave as RAZ/WI.

**Caution**

Use this function only in extreme cases, when debug host software has observed stalled target hardware for an extended period. Stalled target hardware is indicated by repeated WAIT responses.

**Note**

In DPv1 and DPv2 only, the ABORT register has extra fields that clear error and sticky flag conditions. See the descriptions of the flag fields in **CTRL/STAT, Control/Status register on page B2-55**. In DPv0, these fields are reserved, SBZ.

**Usage Constraints**

ABORT is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>WO</td>
</tr>
</tbody>
</table>

**Configurations**

ABORT is defined and implemented in DPv0, DPv1, and DPv2.

**Attributes**

ABORT is a 32-bit write-only DP architecture register.
**Field descriptions**

The ABORT bit assignments are:

- **Bits[31:1], DPv0**
  - Reserved, SBZ.

- **Bits[31:5], DPv1 or higher**
  - ORUNERRCLR, bit[4]
    - To clear the CTRL/STAT.STICKYORUN overrun error bit to 0b0, write 0b1 to this bit.
  - WDERRCLR, bit[3]
    - To clear the CTRL/STAT.WDATAERR write data error bit to 0b0, write 0b1 to this bit.
  - STKERRCLR, bit[2]
    - To clear the CTRL/STAT.STICKYERR sticky error bit to 0b0, write 0b1 to this bit.
  - STKCMPCLR, bit[1]
    - To clear the CTRL/STAT.STICKYCMP sticky compare bit to 0b0, write 0b1 to this bit. It is IMPLEMENTATION DEFINED whether the CTRL/STAT.STICKYCMP bit is implemented. See MINDP, Minimal DP extension on page B1-40.
  - DAPABORT, bit[0]
    - To generate a DAP abort, which aborts the current AP transaction, write 0b1 to this bit.
    - Do this write only if the debugger has received WAIT responses over an extended period.
    - In DPv0, this bit is SBO.

**Accessing ABORT**

Access to ABORT is DATA LINK DEFINED:

- **JTAG-DP**
  - Access is through its own scan-chain. See the `ABORT, JTAG-DP Abort register` on page B3-96.

- **SW-DP**
  - Accessed by a write to offset 0x0 of the DP register map.

<table>
<thead>
<tr>
<th>DP Offset A&lt;sup&gt;a&lt;/sup&gt;</th>
<th>SELECT.DPBANKSEL</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x0</td>
<td>X</td>
</tr>
</tbody>
</table>

---

<sup>a</sup> Bits[1:0] of the register address are always 0b00.
B2.2.2 CTRL/STAT, Control/Status register

The CTRL/STAT characteristics are:

### Purpose

CTRL/STAT is a DP architecture register that is used to control and obtains status information about the DP.

### Usage Constraints

Access to the register and its value after a powerup reset are defined for each field individually, as shown in the table. Some of fields are RO, meaning they ignore writes. See the field descriptions for detailed information.

<table>
<thead>
<tr>
<th>Field</th>
<th>Access</th>
<th>Value after powerup reset</th>
</tr>
</thead>
<tbody>
<tr>
<td>CDBGWRUPACK</td>
<td>RO</td>
<td></td>
</tr>
<tr>
<td>CDBGWRUPREQ</td>
<td>RW</td>
<td>0b0</td>
</tr>
<tr>
<td>CDBGWRUPACK</td>
<td>RO</td>
<td></td>
</tr>
<tr>
<td>CDBGWRETRY</td>
<td>IMPLEMENTATION DEFINED, RW, or RAZ/WI. See Emulation of debug request.</td>
<td>0b0</td>
</tr>
<tr>
<td>CSYSWRUPACK</td>
<td>RO</td>
<td></td>
</tr>
<tr>
<td>CSYSWRUPREQ</td>
<td>RW</td>
<td>0b0</td>
</tr>
<tr>
<td>MASKLANE&lt;sup&gt;a&lt;/sup&gt;</td>
<td>RW</td>
<td>UNKNOWN</td>
</tr>
<tr>
<td>ORUDETECT</td>
<td>RW</td>
<td>0b0</td>
</tr>
<tr>
<td>READOK&lt;sup&gt;b&lt;/sup&gt;</td>
<td>DATA LINK DEFINED, RES0 or RO/WI. See field description.</td>
<td>0b0</td>
</tr>
<tr>
<td>STICKYCMP&lt;sup&gt;a&lt;/sup&gt;</td>
<td>DATA LINK DEFINED, R/W1C or RO/WI. See field description.</td>
<td>0b0</td>
</tr>
<tr>
<td>STICKYWERR</td>
<td>DATA LINK DEFINED, R/W1C or RO/WI. See field description.</td>
<td>0b0</td>
</tr>
<tr>
<td>STICKYORUN</td>
<td>DATA LINK DEFINED, R/W1C or RO/WI. See field description.</td>
<td>0b0</td>
</tr>
<tr>
<td>TRNCNT&lt;sup&gt;a&lt;/sup&gt;</td>
<td>RW</td>
<td>UNKNOWN</td>
</tr>
<tr>
<td>TRNMODE&lt;sup&gt;a&lt;/sup&gt;</td>
<td>RW</td>
<td>UNKNOWN</td>
</tr>
<tr>
<td>WDATAERR</td>
<td>DATA LINK DEFINED, RES0 or RO/WI. See field description.</td>
<td>0b0</td>
</tr>
</tbody>
</table>

<sup>a</sup> MASKLANE, TRNCNT, and TRNMODE are not supported in MINDP configuration. In MINDP configuration, the effect of writing a value other than zero to either TRNCNT or TRNMODE is UNPREDICTABLE.

<sup>b</sup> DPv1 or higher.

### Configurations

Included in all implementations.

### Attributes

CTRL/STAT is a 32-bit read/write register.
Field descriptions

The CTRL/STAT bit assignments are:

```
31 30 29 28 27 26 25 24 23 12 11 8 7 6 5 4 3 2 1 0
<table>
<thead>
<tr>
<th>TRNCNT</th>
<th>MASKLANE</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>WDATAERR</td>
</tr>
<tr>
<td></td>
<td>READOK</td>
</tr>
<tr>
<td>CDBGMRSTREQ</td>
<td>STICKYERR</td>
</tr>
<tr>
<td>CDBGMRSTACK</td>
<td>STICKYCMP</td>
</tr>
<tr>
<td>CDBGMPWRUPREQ</td>
<td>TRNMODE</td>
</tr>
<tr>
<td>CDBGMPWRUPACK</td>
<td>STICKYORUN</td>
</tr>
<tr>
<td>CSYSPWRUPREQ</td>
<td>ORUNDETECT</td>
</tr>
<tr>
<td>CSYSPWRUPACK</td>
<td></td>
</tr>
</tbody>
</table>

CSYSPWRUPACK, bit[31]
System powerup acknowledge. Indicates the status of the CSYSPWRUPACK signal. See Power control requirements and operation on page B2-78.
This bit is RO, meaning it ignores writes.

CSYSPWRUPREQ, bit[30]
System powerup request. This bit controls the CSYSPWRUPREQ signal. See Power control requirements and operation on page B2-78.
After a powerup reset, this bit is 0b0.

CDBGMPWRUPACK, bit[29]
Debug powerup acknowledge. Indicates the status of the CDBGMPWRUPACK signal. See Power control requirements and operation on page B2-78.
This bit is RO, meaning it ignores writes.

CDBGMPWRUPREQ, bit[28]
Debug powerup request. This bit controls the CDBGMPWRUPREQ signal. See Power control requirements and operation on page B2-78.
After a powerup reset, this bit is 0b0.

CDBGMRSTACK, bit[27]
Debug reset acknowledge. Indicates the status of the CDBGMRSTACK signal. See Debug reset control behavior on page B2-81.
This bit is RO, meaning it ignores writes.

CDBGMRSTREQ, bit[26]
Debug reset request. This bit controls the CDBGMRSTREQ signal. See Debug reset control behavior on page B2-81.
It is IMPLEMENTATION DEFINED whether this bit is RW or RAZ/WI. See Emulation of debug reset request on page B2-82.
After a powerup reset, this bit is 0b0.

Bits[25:24] Reserved, RES0.

TRNCNT, bits[23:12]
Transaction counter. See The transaction counter on page B1-43.
After a powerup reset, the value of this field is UNKNOWN.
Note

It is IMPLEMENTATION DEFINED whether this field is implemented.

TRNCNT is not supported in MINDP configuration. In MINDP configuration, the effect of writing a value other than zero to TRNCNT or TRNMODE is UNPREDICTABLE. See also MINDP, Minimal DP extension on page B1-40.

MASKLANE, bits[11:8]

For pushed operations, the DP performs a byte-by-byte comparison of the word that is supplied in an AP write transaction with the current word at the target AP address. The MASKLANE field is used to select the bytes to be included in this comparison. For more information about pushed operations, see Pushed-compare and pushed-verify operations on page B1-44.

Each of the four bits of the MASKLANE field corresponds to one of the four bytes of the words to be compared. Therefore, each bit is said to control one byte lane of the compare operation.

Table B2-8 shows how the bits of MASKLANE control the comparison masking.

Table B2-8 Control of pushed operation comparisons by MASKLANE

<table>
<thead>
<tr>
<th>MASKLANE</th>
<th>Effect</th>
<th>Bits included in comparisons</th>
</tr>
</thead>
<tbody>
<tr>
<td>0b1xxx</td>
<td>Include byte lane 3 in comparisons.</td>
<td>Bits[31:24].</td>
</tr>
<tr>
<td>0bx1xx</td>
<td>Include byte lane 2 in comparisons.</td>
<td>Bits[23:16].</td>
</tr>
<tr>
<td>0bxx1x</td>
<td>Include byte lane 1 in comparisons.</td>
<td>Bits[15:8].</td>
</tr>
<tr>
<td>0bxxx1</td>
<td>Include byte lane 0 in comparisons.</td>
<td>Bits[7:0].</td>
</tr>
</tbody>
</table>

Note

• The MASKLANE field is only relevant if the Transfer Mode field TRNMODE is 0b01, for pushed-verify operations, or 0b10, for pushed-compare operations. See the description of the TRNMODE field and Pushed-compare and pushed-verify operations on page B1-44.

• It is IMPLEMENTATION DEFINED whether this field is implemented. See MINDP, Minimal DP extension on page B1-40.

• After a powerup reset, the value of this field is UNKNOWN.

WDATAERR, bit[7]

This bit is set to 0b1 if one of the following Write Data Error occurs:

• A parity or framing error on the data phase of a write.
• A write that has been accepted by the DP is then discarded without being submitted to the AP.

For more information, see Sticky flags and DP error responses on page B1-41.

Access to and how to clear this field are DATA LINK DEFINED:

JTAG-DP, all implementations

• Access is reserved, RES0.

SW-DP, all implementations, and JTAG-DP, DPv1 and higher

• Access is RO/WI.
• To clear WDATAERR to 0b0, write 0b1 to the ABORT.WDERRCLR field in the ABORT register. A single write of the ABORT register can be used to clear multiple flags if necessary.

After clearing the WDATAERR flag, you must typically resend the corrupted data.

After a powerup reset, WDATAERR is 0b0.

READOK, bit[6]

This bit is DATA LINK DEFINED
• On JTAG-DP, the bit is reserved, RES0.
• On SW-DP, access is RO/WI.

If the response to the previous AP read or RDBUFF read was OK, the bit is set to 0b1. If the response was not OK, it is cleared to 0b0.

This flag always indicates the response to the last AP read access. See Protocol error response on page B4-114.

After a powerup reset, this bit is 0b0.

Note
This field is defined for DPv1 and higher only.

STICKYERR, bit[5]

This bit is set to 0b1 if an error is returned by an AP transaction. See Sticky flags and DP error responses on page B1-41.

Access to and how to clear this field are DATA LINK DEFINED:

JTAG-DP, all implementations
• Access is R/W1C.
• To clear STICKYERR to 0b0, write 0b1 to it, which signals the DP to clear the flag and set it to 0b0. A single write of the CTRL/STAT register can be used to clear multiple flags if necessary.

STICKYERR can also be cleared using the ABORT.STKERRCLR field.

SW-DP, all implementations, and JTAG-DP, DPv1 and higher
• Access is RO/WI.
• To clear STICKYERR to 0b0, write 0b1 to the ABORT.STKERRCLR field in the ABORT register. A single write of the ABORT register can be used to clear multiple flags if necessary.

After clearing CTRL/STAT.STICKYERR, you must find the location where the error that caused the flag to be set occurred.

After a powerup reset, this bit is 0b0.

STICKYCMP, bit[4]

This bit is set to 0b1 when a mismatch occurs during a pushed-compare operation or a match occurs during a pushed-verify operation. See Pushed-compare and pushed-verify operations on page B1-44.

It is IMPLEMENTATION DEFINED whether this field is implemented. See MINDP, Minimal DP extension on page B1-40.

Access to and how to clear this field are DATA LINK DEFINED:

JTAG-DP, all implementations
• Access is R/W1C.
• To clear STICKYCMP to 0b0, write 0b1 to it, which signals the DP to clear the flag and set it to 0b0. A single write of the CTRL/STAT register can be used to clear multiple flags if necessary.

STICKYCMP can also be cleared using the ABORT.STKERRCLR field.
SW-DP, all implementations, and JTAG-DP, DPv1 and higher

- Access is RO/W1.
- To clear STICKYCMP to 0b0, write 0b1 to the ABORT.STKCMPCLR field in the ABORT register. A single write of the ABORT register can be used to clear multiple flags if necessary.

After clearing STICKYCMP, you must retrieve the value of the transaction counter to find the location where the error that caused the flag to be set occurred.

After a powerup reset, this bit is 0b0.

TRNMODE, bits[3:2]

This field sets the transfer mode for AP operations.
In normal operation, AP transactions are passed to the AP for processing, as described in Using the AP to access debug resources on page A1-31.
In pushed-verify and pushed-compare operations, the DP compares the value that is supplied in an AP write transaction with the value held in the target AP address. The AP write transaction generates a read access to the debug memory system as described in Pushed-compare and pushed-verify operations on page B1-44.
TRNMODE can have one of the following values:
0b00 Normal operation.
0b01 Pushed-verify mode.
0b10 Pushed-compare mode.
0b11 Reserved.

After a powerup reset, the value of this field is UNKNOWN.

--- Note ---

It is IMPLEMENTATION DEFINED whether this field is implemented.
TRNMODE is not supported in MINDP configuration. In MINDP configuration, the effect of writing a value other than zero to TRNCNT or TRNMODE is UNPREDICTABLE. See also MINDP, Minimal DP extension on page B1-40.

STICKYORUN, bit[1]

If overrun detection is enabled, this bit is set to 0b1 when an overrun occurs. See bit[0] of this register for details of enabling overrun detection.

Access to and how to clear this field are DATA LINK DEFINED:

JTAG-DP, all implementations

- Access is R/W1C.
- To clear STICKYORUN to 0b0, write 0b1 to it, which signals the DP to clear the flag and set it to 0b0. A single write of the CTRL/STAT register can be used to clear multiple flags if necessary.

STICKYORUN can also be cleared using the ABORT.STKERRCLR field.

SW-DP, all implementations, and JTAG-DP, DPv1 and higher

- Access is RO/W1.
- To clear STICKYORUN to 0b0, write 0b1 to the ABORT.ORUNERRCLR field in the ABORT register. A single write of the ABORT register can be used to clear multiple flags if necessary.

After clearing STICKYORUN, you must find out which DP or AP transaction initiated the overrun that caused the flag to be set, and repeat the transactions for that DP or AP from the transaction pointed to by the transaction counter.

After a powerup reset, this bit is 0b0.
ORUNDETECT, bit[0]

This bit can have one of the following values:

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0b0</td>
<td>Overrun detection is disabled.</td>
</tr>
<tr>
<td>0b1</td>
<td>Overrun detection is enabled.</td>
</tr>
</tbody>
</table>

For more information about overrun detection, see *Sticky flags and DP error responses* on page B1-41.

After a powerup reset, this bit is 0b0.

### Accessing CTRL/STAT

CTRL/STAT can be accessed at the following address:

<table>
<thead>
<tr>
<th>DP Offset A&lt;sup&gt;a&lt;/sup&gt;</th>
<th>SELECT.DPBANKSEL</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x4</td>
<td>0x0</td>
</tr>
</tbody>
</table>

a. Bits[1:0] of the register address are always 0b00.
B2.2.3 DLCR, Data Link Control register

The DLCR characteristics are:

**Purpose**

DLCR controls the operating mode of the Data Link.

**Usage Constraints**

DLCR is DATA LINK DEFINED:

- For a JTAG DP, the DLCR register is RES0.
- For an SW-DP, the DLCR register has the fields that are described in Field descriptions on page B2-63.

DLCR is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th>RW</th>
</tr>
</thead>
</table>

**Configurations**

DLCR is implemented in DPv1 and DPv2.

**Attributes**

DLCR is a 32-bit DATA LINK DEFINED DP architecture register.

**Field descriptions**

The DLCR bit assignments for an SW-DP are:

![DLCR diagram]

- **Bits[31:10]**
  - Reserved, RES0.

- **TURNROUND, bits[9:8]**
  - For an SW-DP, this field defines the turnaround tristate period. For details about line turnaround, see Line turnaround on page B4-107. Table B2-9 shows the permitted values of this field, and their meanings.

<table>
<thead>
<tr>
<th>DLCR.TURNROUND</th>
<th>Turnaround tristate period</th>
</tr>
</thead>
<tbody>
<tr>
<td>0b00</td>
<td>1 data period(^a).</td>
</tr>
<tr>
<td>0b01</td>
<td>2 data periods(^a).</td>
</tr>
<tr>
<td>0b10</td>
<td>3 data periods(^a).</td>
</tr>
<tr>
<td>0b11</td>
<td>4 data periods(^a).</td>
</tr>
</tbody>
</table>

\(^a\). A data period is the period of a single data bit on the SWD interface.
After a powerup or line reset, this field is 0b00.

Note

Support for varying the turnaround tristate period is IMPLEMENTATION DEFINED. An implementation that does not support variable turnaround must treat writing a value other than 0b00 to the TURNROUND field as an immediate protocol error.

Bit[7] Reserved, RES0.
Bits[5:0] Reserved, RES0.

Accessing DLCR

DLCR can be accessed at the following address:

<table>
<thead>
<tr>
<th>DP Offset A(^a)</th>
<th>SELECT.DPBANKSEL</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x4</td>
<td>0x1</td>
</tr>
</tbody>
</table>

\(^a\) Bits[1:0] of the register address are always 0b00.

---

**B2.2.4 DLPIDR, Data Link Protocol Identification register**

The DLPIDR characteristics are:

**Purpose**

DLPIDR provides protocol version information.

**Configurations**

DLPIDR is implemented in DPv2.

Note

An SWD Port that implements DPv2, must implement at least SWD protocol version 2.

**Usage Constraints**

For a JTAG-DP, DLPIDR is reserved and any result from accessing the register is UNPREDICTABLE. DLPIDR is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
</tr>
</tbody>
</table>

**Attributes**

DLPIDR is a 32-bit DATA LINK DEFINED register.
Field descriptions

For an SW-DP, the DLPIDR bit assignments are:

<table>
<thead>
<tr>
<th>31</th>
<th>28</th>
<th>27</th>
<th>4</th>
<th>3</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>PROTVSN</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

TINSTANCE, bits[31:28]

IMPLEMENTATION DEFINED. Defines an instance number for this device. This value must be unique for all devices with identical TARGETID.TPARTNO and TARGETID.TDESIGNER fields that are connected together in a multi-drop system.

Bits[27:4]: RES0.

PROTVSN, bits[3:0]

Defines the SWD protocol version that is implemented. Valid values for this field are:

- 0x1: SWD protocol version 2. Adds support for multidrop extensions. See Chapter B4 The Serial Wire Debug Port (SW-DP).

All other values of this field are reserved.

Accessing DLPIDR

DLPIDR can be accessed at the following address:

<table>
<thead>
<tr>
<th>DP Offset A&lt;sup&gt;a&lt;/sup&gt;</th>
<th>SELECT.DPBANKSEL</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x4</td>
<td>0x3</td>
</tr>
</tbody>
</table>

a. Bits[1:0] of the register address are always 0b00.
B2.2.5 DPIDR, Debug Port Identification register

The DPIDR characteristics are:

**Purpose**
DPIDR provides information about the Debug Port.

**Usage Constraints**
DPIDR is accessible as follows:

| Default | RO |

**Configurations**
DPIDR is defined and implemented only in DPv1 and DPv2.

---
**Note**
- In DPv0, the DPIDR is reserved and accesses are UNPREDICTABLE.
- In all DP architecture versions, a JTAG-DP implementation must implement the IDCODE instruction and IDCODE scan-chain. The architecture does not require that the TAP IDCODE register value and the DPIDR value are the same.

**Attributes**
A 32-bit DP architecture register.

Access to the DPIDR is not affected by the value of SELECT.DPBANKSEL.

**Field descriptions**
The DPIDR bit assignments are:

<table>
<thead>
<tr>
<th>31</th>
<th>28</th>
<th>27</th>
<th>20</th>
<th>19</th>
<th>17</th>
<th>16</th>
<th>15</th>
<th>12</th>
<th>11</th>
<th>2</th>
<th>1</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>REVISION</td>
<td>PARTNO</td>
<td>RES0</td>
<td>VERSION</td>
<td>DESIGNER</td>
<td>MIN</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>RAO</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- **REVISION, bits[31:28]**
  Revision code. The meaning of this field is IMPLEMENTATION DEFINED.

- **PARTNO, bits[27:20]**
  Part Number for the Debug Port. This value is provided by the designer of the Debug Port and must not be changed.

- **Bits[19:17]**
  Reserved, RES0.

- **MIN, bit[16]**
  *Minimal Debug Port (MINDP) functions implemented:*
  - 0b0 Transaction counter, Pushed-verify, and Pushed-find operations are implemented.
  - 0b1 Transaction counter, Pushed-verify, and Pushed-find operations are not implemented.

- **VERSION, bits[15:12]**
  Version of the Debug Port architecture implemented. Permitted values are:
  - 0x0 Reserved. Implementations of DPv0 do not implement DPIDR.
  - 0x1 DPv1 is implemented.
  - 0x2 DPv2 is implemented.
  - All remaining values are reserved.
DESIGNER, bits[11:1]

Code that identifies the designer of the DP.

This field indicates the designer of the DP and not the implementer, except where the two are the same. To obtain a number, or to see the assignment of these codes, contact JEDEC http://www.jedec.org.

A JEDEC code takes the following form:

- A sequence of zero or more numbers, all having the value 0x7F.
- A following 8-bit number, that is not 0x7F, and where bit[7] is an odd parity bit. For example, ARM Limited is assigned the code 0x7F 0x7F 0x7F 0x7F 0x3B.

The encoding that is used in the DPIDR is as follows:

- The JEP106 continuation code, DPIDR bits[11:8], is the number of times that 0x7F appears before the final number. For example, for ARM Limited this field is 0x4.
- The JEP106 identification code, IDR bits[7:1], equals bits[6:0] of the final number of the JEDEC code. For example, for ARM Limited this field is 0x3B.

Bit[0] RAO.

Accessing DPIDR

DLPIDR can be accessed at the following address:

<table>
<thead>
<tr>
<th>DP Offset A⁰</th>
<th>SELECT.DPBANKSEL</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x0</td>
<td>x</td>
</tr>
</tbody>
</table>

a. Bits[1:0] of the register address are always 0b00.
B2.2.6 EVENTSTAT, Event Status register

The EVENTSTAT characteristics are:

**Purpose**

EVENTSTAT is used by the system to signal an event to the external debugger. The nature of the event is IMPLEMENTATION DEFINED.

ARM recommends connecting EVENTSTAT to one of the following:

- An output trigger of a CoreSight Cross-Trigger Interface (CTI) with software acknowledge.
- An output from a uniprocessor system that indicates whether the processor is halted:
  - For ARMv6-M, ARMv7-M, and ARMv8-M processors, the recommended HALTED signal.
  - For all other ARM architecture processors, the recommended DBGACK signal.

**Usage Constraints**

EVENTSTAT is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th>RO</th>
</tr>
</thead>
</table>

**Configurations**

EVENTSTAT is implemented in DPv2.

**Attributes**

A 32-bit RO register.

**Field descriptions**

The EVENTSTAT bit assignments are:

| Bits[31:1] | Reserved, RES0. |
| EA, bit[0] | If an event is implemented, this field is the event status flag. Valid values for the flag are: |
| 1b0 | An event requires attention. |
| 1b1 | There is no event requiring attention. |

If no event is implemented, this field is RAZ.

**Note**

The status of the event is inverted in the register, and when debugging an implementation that does not implement an event, debuggers must not interpret a value of zero as an event requiring attention, but poll other registers to detect the status of the system.

**Accessing EVENTSTAT**

EVENTSTAT can be accessed at the following address:

<table>
<thead>
<tr>
<th>DP Offset A³</th>
<th>SELECT.DPBANKSEL</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x4</td>
<td>0x4</td>
</tr>
</tbody>
</table>

a. Bits[1:0] of the register address are always 0b00.
B2.2.7   **RDBUFF, Read Buffer register**

The RDBUFF characteristics are:

**Purpose**

The purpose and behavior of RDBUFF is **DATA LINK DEFINED**:

**JTAG-DP**  The Read Buffer is architecturally defined to provide a DP read operation that does not have any side effects. This definition allows a debugger to insert a DP read of RDBUFF at the end of a sequence of operations, to return the final AP Read Result and ACK values.

**SW-DP**  On an SW-DP, the Read Buffer presents data that was captured during the previous AP read, enabling repeatedly returning the value without generating a new AP access.

---

**Note**

After reading the DP Read Buffer, its contents are no longer valid. The result of a second read of the DP Read Buffer is **UNKNOWN**.

---

If you require the value from an AP register read, that read must be followed by one of:
- A second AP register access, with the appropriate AP selected as the current AP.
- A read of the DP Read Buffer.

The second access to either the AP or the DP stalls until the result of the original AP read is available.

**Usage Constraints**

RDBUFF is accessible as follows:

**Configurations**

RDBUFF is implemented in DPv0, DPv1, and DPv2.

**Attributes**

A 32-bit read-only buffer.

The RDBUFF bit assignments are:

<table>
<thead>
<tr>
<th>Bit Position</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>31-0</td>
<td>DATA LINK DEFINED</td>
</tr>
</tbody>
</table>

**Accessing RDBUFF**

RDBUFF can be accessed at the following address:

<table>
<thead>
<tr>
<th>DP Offset*</th>
<th>SELECT.DPBANKSEL</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xC</td>
<td></td>
</tr>
</tbody>
</table>

a. Bits[1:0] of the register address are always #00.
B2.2.8 RESEND, Read Resend register

The RESEND register characteristics are:

Purpose
Performing a read to RESEND does not capture new data from the AP, but returns the value that was returned by the last AP read or DP RDBUFF read.
RESEND enables the debugger to recover read data from a corrupted SW-DP transfer without having to re-issue the original read request, or generate a new access to the connected debug memory system.
RESEND can be accessed multiple times, and always returns the same value until a new access is made to an AP register or the DP RDBUFF register.

Usage Constraints
ARM recommends that debuggers only access RESEND when a failed read has been indicated by the SW-DP, and at no other time. The reason for this is that, if an implementation cannot resend the information, it is permitted to treat reads RESEND as a protocol error.
RESEND is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
</tr>
</tbody>
</table>

Configurations
RESEND is implemented in DPv1 and DPv2.
For these versions, RESEND is included in all implementations.

Attributes
A 32-bit read-only DP architecture register.
RESEND is:
• A read-only register.
• Accessed by a read of offset 0x8 in the DP register map.

DATA LINK DEFINED:

JTAG-DP The register is reserved, any access is UNPREDICTABLE.
SW-DP The value that was returned by the last AP read or DP RDBUFF read.

Field descriptions
The RESEND bit assignments are:

```
   31 0
   DATA LINK DEFINED
```

<table>
<thead>
<tr>
<th>Bits[31:0]</th>
<th>DATA LINK DEFINED:</th>
</tr>
</thead>
<tbody>
<tr>
<td>JTAG-DP</td>
<td>The register is reserved, any access is UNPREDICTABLE.</td>
</tr>
<tr>
<td>SW-DP</td>
<td>Data for previous AP read.</td>
</tr>
</tbody>
</table>
Accessing RESEND

RESEND can be accessed at the following address:

<table>
<thead>
<tr>
<th>DP Offset A&lt;sup&gt;a&lt;/sup&gt;</th>
<th>SELECT.DPBANKSEL</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x8</td>
<td>x</td>
</tr>
</tbody>
</table>

a. Bits[1:0] of the register address are always 0b00.
B2.2.9 SELECT, AP Select register

The SELECT characteristics are:

**Purpose**

SELECT:
- Selects an Access Port (AP) and the active register banks within that AP.
- Selects the DP address bank.

**Usage Constraints**

SELECT is accessible as follows:

<table>
<thead>
<tr>
<th></th>
<th>DPv0</th>
<th>DPv1</th>
<th>DPv2</th>
</tr>
</thead>
<tbody>
<tr>
<td>Access</td>
<td>RW</td>
<td>WO</td>
<td>WO</td>
</tr>
</tbody>
</table>

**Configurations**

A DP architecture register. SELECT is implemented in DPv0, DPv1, and DPv2.

**Note**

This specification deprecates reading SELECT in a DPv0 implementation.

**Attributes**

SELECT is a 32-bit DP architecture register.

**Field descriptions**

The SELECT bit assignments are:

<table>
<thead>
<tr>
<th>31</th>
<th>24 23</th>
<th>8 7</th>
<th>4 3</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>APSEL</td>
<td>Reserved</td>
<td>RES0</td>
<td>APBANKSEL</td>
<td>DPBANKSEL</td>
</tr>
</tbody>
</table>

**APSEL, bits[31:24]**

Selects the AP with the ID number APSEL. If there is no AP with the ID APSEL, all AP transactions return zero on reads and are ignored on writes. See *Register maps, and accesses to reserved addresses on page B2-52.*

After a powerup reset, the value of this field is UNKNOWN.

**Note**

Every ARM Debug Interface implementation must include at least one AP.

**Bits[23:8]**

Reserved, RES0.

**APBANKSEL, bits[7:4]**

Selects the active four-word register bank on the current AP. See *Using the AP to access debug resources on page A1-31.*

After a powerup reset, the value of this field is UNKNOWN.
DPBANKSEL, bit[3:0]

Debug Port address bank select.

The behavior of SELECT.DPBANKSEL depends on the DP version, as follows:

**DPv0**  
In DPv0 the SELECT.DPBANKSEL field must be written as zero, otherwise accesses to DP register 0x4 are UNPREDICTABLE.

**DPv1**  
In DPv1 the SELECT.DPBANKSEL field controls which DP register is selected at address 0x4, and Table B2-10 shows the permitted values of this field.

<table>
<thead>
<tr>
<th>DPBANKSEL</th>
<th>DP register at address 0x4</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x0</td>
<td>CTRL/STAT</td>
</tr>
<tr>
<td>0x1</td>
<td>DLCR</td>
</tr>
</tbody>
</table>

All other values of SELECT.DPBANKSEL are reserved. If the field is set to a reserved value, accesses to DP register 0x4 are UNPREDICTABLE.

**DPv2**  
In DPv2 the SELECT.DPBANKSEL field controls which DP register is selected at address 0x4, and Table B2-11 shows the permitted values of this field.

<table>
<thead>
<tr>
<th>DPBANKSEL</th>
<th>DP register at address 0x4</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x0</td>
<td>CTRL/STAT</td>
</tr>
<tr>
<td>0x1</td>
<td>DLCR</td>
</tr>
<tr>
<td>0x2</td>
<td>TARGETID</td>
</tr>
<tr>
<td>0x3</td>
<td>DLPIDR</td>
</tr>
<tr>
<td>0x4</td>
<td>EVENTSTAT</td>
</tr>
</tbody>
</table>

All other values of SELECT.DPBANKSEL are reserved. If the field is set to a reserved value, accesses to DP register 0x4 are RES0.

After a powerup reset, this field is 0b0.

**Note**  
Some previous ADI revisions have described DPBANKSEL as a single-bit field called CTRSEL, defined only for SW-DP. From issue B of this document, DPBANKSEL is redefined. The new definition is backwards-compatible.

### Accessing SELECT

SELECT can be accessed at the following address:

<table>
<thead>
<tr>
<th>DP Offset A&lt;sup&gt;a&lt;/sup&gt;</th>
<th>SELECT.DPBANKSEL</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x8</td>
<td>Not applicable</td>
</tr>
</tbody>
</table>

---

<sup>a</sup> Bits[1:0] of the register address are always 0b00.
B2.2.10 TARGETID, Target Identification register

The TARGETID characteristics are:

**Purpose**

TARGETID provides information about the target when the host is connected to a single device.

**Usage Constraints**

TARGETID is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
</tr>
</tbody>
</table>

**Configurations**

TARGETID is implemented in DPv2.

**Attributes**

TARGETID is a 32-bit read-only register.

**Field descriptions**

The TARGETID bit assignments are:

<table>
<thead>
<tr>
<th>31</th>
<th>28</th>
<th>27</th>
<th>12</th>
<th>11</th>
<th>10</th>
</tr>
</thead>
<tbody>
<tr>
<td>TREV</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>TPAR</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>TDES</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>1</td>
</tr>
</tbody>
</table>

**TREVISION, bits[31:28]**

Target revision.

**TPARTNO, bits[27:12]**

IMPLEMENTATION DEFINED. The value is assigned by the designer of the part. The value must be unique to the part.

**TDESIGNER, bits[11:1]**

IMPLEMENTATION DEFINED.

This field indicates the designer of the part and not the implementer, except where the two are the same.

Designers must insert their JEDEC-assigned code here.

**Note**

The ARM JEP106 value is not shown for the TDESIGNER field. ARM might design a DP containing the TARGETID register, but typically, the designer of the part, referenced in the TPARTNO field, is another designer who creates a part around the licensed ARM IP. If the designer of the part is ARM, then the value of this field is 0x23B.

To obtain a number, or to see the assignment of these codes, contact JEDEC at http://www.jedec.org.

A JEP106 code takes the following form:

- A sequence of zero or more numbers, all having the value 0x7F.
- A following 8-bit number, that is not 0x7F, and where bit[7] is an odd parity bit. For example, ARM Limited is assigned the code 0x7F 0x7F 0x7F 0x7F 0x7F 0x7F 0x38.
The encoding that is used in TARGETID is as follows:

- The JEP106 continuation code, TARGETID bits[11:8], is the number of times that 0x7F appears before the final number. For example, for ARM Limited this field is 0x4.
- The JEP106 identification code, TARGETID bits[7:1], equals bits[6:0] of the final number of the JEDEC code.

**Bit[0]**

RAO.

**Accessing TARGETID**

TARGETID can be accessed at the following address:

<table>
<thead>
<tr>
<th>DP Offset A³</th>
<th>SELECT.DPBANKSEL</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x4</td>
<td>0x2</td>
</tr>
</tbody>
</table>

a. Bits[1:0] of the register address are always 0b00.
B2.2.11  TARGETSEL, Target Selection register

The TARGETSEL characteristics are:

**Purpose**

TARGETSEL selects the target device in an SWD multi-drop system. On a write to TARGETSEL immediately following a line reset sequence, the target is selected if both the following conditions are met:

- Bits[31:28] match bits[31:28] in the DLPIDR.

Writing any other value deselects the target. Debug tools must write 0xFFFFFFFF to deselect all targets. 0xFFFFFFFF is an invalid TARGETID value. All other invalid TARGETID values are reserved.

During the response phase of a write to the TARGETSEL register, the target does not drive the line. See **Sticky flags and DP error responses** on page B1-41 for more information.

**Usage Constraints**

The register is DATA LINK DEFINED:

- **JTAG-DP**  The register is reserved, any access is UNPREDICTABLE.
- **SW-DP**  If SWD protocol version 2 is implemented, the register is implemented.

The register is accessible as follows:

<table>
<thead>
<tr>
<th></th>
<th>SW-DP</th>
<th>JTAG-DP</th>
</tr>
</thead>
<tbody>
<tr>
<td>WO</td>
<td>UNPREDICTABLE</td>
<td></td>
</tr>
</tbody>
</table>

**Configurations**

TARGETSEL is implemented in DPv2.

**Note**

In issue A of this document, this register was called ROUTESEL, and was a reserved write-only register.

**Attributes**

TARGETSEL is a 32-bit DP architecture register.

**Field descriptions**

For an SW-DP, the TARGETSEL bit assignments are:

<table>
<thead>
<tr>
<th>31</th>
<th>28</th>
<th>27</th>
<th>12</th>
<th>11</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td>TINSTANCE</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>TPARTNO</td>
<td>TDESIGNER</td>
<td></td>
</tr>
</tbody>
</table>

**TINSTANCE**, bits[31:28]

IMPLEMENTATION DEFINED. The instance number for this device. See DLPIDR.

**TPARTNO**, bits[27:12]

IMPLEMENTATION DEFINED. The value that is assigned by the designer of the part. See TARGETID.
TDESIGNER, bits[11:1]

IMPLEMENTATION DEFINED. The 11-bit code that is formed from the JEDEC JEP106 continuation code and identity code. See TARGETID.

Bit[0] SBO.

Accessing TARGETSEL

TARGETSEL can be accessed at the following address:

<table>
<thead>
<tr>
<th>DP Offset A&lt;sup&gt;a&lt;/sup&gt;</th>
<th>SELECT.DPBANKSEL</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xC</td>
<td>x</td>
</tr>
</tbody>
</table>

a. Bits[1:0] of the register address are always 0b00.
B2.3 System and debug power control behavior

This section gives detailed information about system and debug power.

B2.3.1 The DAP power domains model

The DAP model supports multiple power domains, which provide support for debug components that can be powered down.

Three power domains are modeled:

**Always-on power domain**

Power domain that must be powered up for the debugger to connect to the device.

**System power domain**

Power domains that include system components.

**Debug power domain**

Power domain that includes the entire debug subsystem.

The system and debug power domains can be subdivided if necessary. However, to define a simple debug interface, the device must be partitioned into system and debug power domains at the top level. Any finer-grained control is outside the scope of this model.

In most situations, debuggers power up the complete SoC. However, if a debugger is investigating an energy management issue, it might want to power up only the debug domain. To achieve this goal, SoC designers might want to map the power controller into a bus segment that the DAP can access when only the debug power domain is powered up.

When using an ARM Debug Interface, for the debug process to work correctly, systems must not remove power from the DP during a debug session. If power is removed, the DAP controller state is lost. However, the DAP is designed to permit the rest of the DAP and the system to be powered down and debugged while maintaining power to the DP.

The DP registers reside in the always-on power domain, on the external interface side of the DP. Therefore, they can always be driven, enabling powerup requests to be made to a system power controller. The power and reset control bits are part of the DP CTRL/STAT register. See Debug reset control behavior on page B2-81 for more information about the reset control bits in this register.

ADIv5 defines two pairs of power control signals:

- **CDBGPRRUPREQ** and **CDBGPRRUPACK**.
- **CSYSPWRUPREQ** and **CSYSPWRUPACK**.

Table B2-12 summarizes the programmers' model for the power control signal pairs.

<table>
<thead>
<tr>
<th>Signal</th>
<th>Programmers’ model</th>
</tr>
</thead>
<tbody>
<tr>
<td>CDBGPRRUPREQ</td>
<td>Bit[28] of the CTRL/STAT register</td>
</tr>
<tr>
<td>CDBGPRRUPACK</td>
<td>Bit[29] of the CTRL/STAT register</td>
</tr>
<tr>
<td>CSYSPWRUPREQ</td>
<td>Bit[30] of the CTRL/STAT register</td>
</tr>
<tr>
<td>CSYSPWRUPACK</td>
<td>Bit[31] of the CTRL/STAT register</td>
</tr>
</tbody>
</table>

These signals are expected to provide hints to the system power and clock controller. The following sections describe these signal pairs.
**CDBGPWRUPREQ and CDBGPWRUPACK**

*CDBGPWRUPREQ* is the signal from the debug interface to the power controller. This signal requests the system power controller to fully power up and enable clocks in the debug power domain. *CDBGPWRUPACK* is the signal from the power controller to the debug interface. When *CDBGPWRUPREQ* is asserted, the power controller powers up the debug power domain and then asserts *CDBGPWRUPACK* to acknowledge that it has responded to the request.

Which components are in the debug power domain that is controlled by *CDBGPWRUPREQ* is IMPLEMENTATION DEFINED. This domain might include all debug components in the system, or it might, for example, be limited to exclude components that have extra levels of power control. The *CDBGPWRUPREQ* signal indicates that the debugger requires the debug resources of these components to be communicative. Communicative means that the debugger can access at least enough registers of the debug resource for it to determine the state of the resource.

Whether the resource is active is IMPLEMENTATION DEFINED. The power and clock controller must power up and run the clocks of as many domains as necessary to comply with this request from the debugger for the resources to be communicative.

The power and clock controller must honor *CDBGPWRUPREQ* for as long as it is asserted. For example, if a component in a debug power domain requests to have its clocks stopped, the request must be emulated for non-debug logic within that power domain, including all components with a single shared domain.

If some debug resources of a component are not in the debug power domain, then at least the minimal debug interface of the component must be powered up. If the following requirements are met, power can be removed from the remainder of the component:

- There is some means to save and restore the state of the debug resources.
- The debugger can communicate with the debug resources when the remainder of the component is not powered.

The means to save and restore the values that are held in these resources might include software solutions. If the debug resources do lose their value when power is removed from the remainder of the component, then the debug interface must include means for the debugger to discover that the programmed values have been lost.

*CDBGPWRUPACK* is the acknowledge signal for the *CDBGPWRUPREQ* request signal. *CDBGPWRUPACK* must be asserted for as long as *CDBGPWRUPREQ* is asserted. See *Powerup request and acknowledgement timing* on page B2-79.

**CSYSPWRUPREQ and CSYSPWRUPACK**

*CSYSPWRUPREQ* is the signal from the debug interface to the power controller. This signal requests the system power controller to fully power up and enable clocks in the system power domain. *CSYSPWRUPACK* is the signal from the power controller to the debug interface. When *CSYSPWRUPREQ* is asserted, the power controller powers up the system power domain and then asserts *CSYSPWRUPACK* to acknowledge that it has responded to the request.

Which components are in the system power domain that is controlled by *CSYSPWRUPREQ* is IMPLEMENTATION DEFINED. This domain might include all debug components in the system, or might be limited, for example to exclude components that have extra levels of power control, such as processors that implement independent Core Powerup Request controls.

The *CSYSPWRUPREQ* signal indicates that the debugger requires all debug resources of these components to be active. Active means that the debug resource can perform its debug function. An active resource is also communicative.

The power and clock controller must honor *CSYSPWRUPREQ* for as long as it is asserted.

*CSYSPWRUPREQ* has no effect on debug components that are controlled by *CDBGPWRUPREQ*, because those components have no debug logic in the system power domain. However, for components where some debug resources are in the system power domain that is controlled by *CSYSPWRUPREQ*, the request must be emulated for non-debug logic within that power domain.

*CSYSPWRUPACK* is the acknowledge signal for the *CSYSPWRUPREQ* request signal. *CSYSPWRUPACK* must be asserted for as long as *CSYSPWRUPREQ* is asserted. See *Powerup request and acknowledgement timing* on page B2-79.
When CSYSPWRUPREQ is asserted by the debugger, CDBGWRUPREQ must also be asserted.

## B2.3.2 Power control requirements and operation

This section applies to both the system and the debug domain, and uses the following notation:

- **CxxxPWRUPREQ** refers to either CSYSPWRUPREQ or CDBGWRUPREQ.
- **CxxxPWRUPACK** refers to either CSYSPWRUPACK or CDBGWRUPACK.

All signals that are described in this section are active-high, so assert denotes taking the signal HIGH, and deassert denotes taking the signal LOW.

The rules for the operation of powerup requests and acknowledgements are:

- The debugger must not set CTRL/STAT.CSYSPWRUPREQ to 0b1 and CTRL/STAT.CDBGWRUPREQ to 0b0 at the same time. The response to this combination of requests is UNPREDICTABLE.
- To initiate powerup, the DP must assert CxxxPWRUPREQ.
  - If the corresponding power domain is powered down or in a low-power retention state, the power controller must power up and restore clocks to the domain when it detects that CxxxPWRUPREQ is asserted. After the domain is powered up, the controller must assert CxxxPWRUPACK.
  - If the corresponding power domain is already powered up and clocked when the power controller detects that CxxxPWRUPREQ is asserted, the controller must still respond by asserting CxxxPWRUPACK, even though it does not affect the power domain.
- ARM strongly recommends that tools only initiate an AP transfer when CDBGWRUPREQ and CDBGWRUPACK are asserted. If CDBGWRUPREQ or CDBGWRUPACK is LOW, any AP transfer might generate a fault response.
- The DP requests removal of power to a domain by deasserting CxxxPWRUPREQ.
  The power controller deasserts CxxxPWRUPACK when it has accepted the request to power down the domain.

**Note**

The power controller deasserting CxxxPWRUPACK, does not indicate that the domain has been powered down, it only indicates that the power controller has recognized and accepted the request to remove power.

- **CxxxPWRUPACK** must default to the LOW state, and only go HIGH on receipt of a CxxxPWRUPREQ request.
- After detecting the deassertion of CxxxPWRUPREQ, the power controller must gracefully power down the domain, unless removal of power from the domain would affect system operation. For example, the power controller might maintain power to the domain if it has other requests to maintain power.
- After powerdown has been requested through the deassertion of CxxxPWRUPREQ, tools must wait until CxxxPWRUPACK is LOW before making a new request for powerup.

This requirement ensures that the power control handshaking mechanism is not violated.

Figure B2-1 on page B2-79 shows the timing of the power control signals.

**Note**

ARM strongly recommends that all AP transactions are initiated between times T2 and T3 for CDBGWRUPREQ and CDBGWRUPACK, as shown in Figure B2-1 on page B2-79.
B2.3 System and debug power control behavior

B2.3.3 Emulation of powerdown

If the DAP asserts \texttt{CxxxPRWUPREQ} for a domain, and the power controller receives a conflicting request for the domain from another source, it must emulate the powerdown request for the domain by completing the handshake process as expected, without actually removing power from the domain. This requirement enables debugging a system with power domains that power up and down dynamically.

The following requests cause a conflict when issued by another source after the DAP has asserted \texttt{CxxxPRWUPREQ}:

- A powerdown request.
- A request to enter a low-power retention mode, with clocks disabled.

Emulation of powerdown is relevant to application debugging, when the application developer does not care whether the core domain actually powers up and down because this aspect is controlled at the OS level.

B2.3.4 Emulation of power control

If the system to which a DAP is connected does not support the ADIv5 power control model, the required signals must be emulated or generated from other signals:

**System power controllers that do not support the ADIv5 power control scheme**

To ensure that the DAP receives an immediate acknowledgement after initiating or removing a powerup request, connect \texttt{CxxxPRWUPACK} to \texttt{CxxxPRWUPREQ}, as shown in Figure B2-2.

**System power controllers that do not support separate power domains**

If the debug power domain is part of the system power domain, \texttt{CSYSPWRUPREQ} and \texttt{CDBGPRUPREQ} can independently request powerup. To correctly emulate power control:

- To ensure that the DAP receives an immediate acknowledgement of after initiating or removing a system powerup request, connect \texttt{CSYSPWRUPACK} to \texttt{CSYSPWRUPREQ}.
- Generate appropriate \texttt{CxxxPRWUPACK} signals that ensure that the DAP sees the correct response when it asserts \texttt{CxxxPRWUPREQ}.
Note

The CxxxPWRUPACK signals must be emulated as described. Setting
CTRL/STAT.CSYSPWRUPREQ to 0b1 and CTRL/STAT.CDBGPWRUPREQ to 0b0 in the
CTRL/STAT register leads to UNPREDICTABLE system behavior.

The connections are shown in Figure B2-3.

![Diagram](image-url)
B2.4 Debug reset control behavior

The DP register CTRL/STAT provides two fields for reset control of the debug domain:

- CTRL/STAT.CDBGRSTREQ, Debug reset request.
- CTRL/STAT.CDBGRSTACK, Debug reset acknowledge.

The associated signals, CDBGRSTREQ and CDBGRSTACK, provide a connection to a system reset controller. The debug domain that is controlled by these signals covers the internal DAP and the connection between the DAP and the debug components, for example the debug bus.

The DP registers are in the always-on power domain on the external interface side of the DP. Therefore, the registers can be driven at any time, to generate a reset request to the system reset controller.

Figure B2-4 shows the reset request and acknowledge timing.

![Figure B2-4 Reset request and acknowledge timing](image)

Note

The use of AMBA APB signal names in the examples does not indicate a requirement that a debug bus must be implemented using an AMBA APB.

In Figure B2-4:

1. At time T1, the debugger writes 0b1 to CTRL/STAT.CDBGRSTREQ, which initiates the reset request. The debug domain is reset between times T1a and T1b, and the reset is complete by time T2. This operation resets the AP registers and other AP state.

   Note
   
   There is no reset of the DP registers and DP state. These registers are only reset by a powerup reset.

2. At time T2, the system reset controller acknowledges that the reset of the debug domain has completed. The CDBGRSTACK signal sets the CTRL/STAT.CDBGRSTACK bit to 0b1.

3. At time T3, the debugger checks the DP CTRL/STAT register and finds that the reset has completed. Therefore, it writes 0b0 to CTRL/STAT.CDBGRSTREQ, which removes the reset request signal.

4. At time T4, the system reset controller recognizes that CDBGRSTREQ is no longer asserted, and deasserts CDBGRSTACK.

Caution

If CDBGRSTREQ is removed before the reset controller asserts CDBGRSTACK, the behavior is UNPREDICTABLE.

The AP debug components are also reset on powerup of the debug power domain.

A debug reset request has no effect on devices that are powered down when the request is issued.
B2.4 Debug reset control behavior

B2.4.1  Emulation of debug reset request

If the debug reset control is not supported then:

• It is IMPLEMENTATION DEFINED whether CTRL/STAT.CDBGRSTREQ is read/write or RAZ/WI.

• CTRL/STAT.CDBGRSTACK is RAZ.

——— Note ————
ARM recommends tying CDBGRSTACK LOW so that the debugger can use a timeout mechanism to detect whether debug reset is implemented.

B2.4.2  Limitations of CDBGRSTREQ and CDBGRSTACK

Debug reset control behavior on page B2-81 shows how these bits can drive the debug reset signal, PRESETDBGn. In an actual system, there might be other reset signals that are associated with other debug buses. For example, in an ARM CoreSight system, ATRESETn resets all registers in the AMBA Trace Bus domain.

——— Note ————
It is IMPLEMENTATION DEFINED which components are reset by CDBGRSTREQ. Figure B2-4 on page B2-81 is an example only. Not only components that use PRESETDBGn are reset.

Because debug logic might be accessible by the system, an implementation might have corner cases if CDBGRSTREQ is set at the same time as the system is using the debug logic. For example, the reset might occur during a transaction, causing a system or software malfunction.

It is IMPLEMENTATION DEFINED whether CDBGRSTREQ can be used when debug power is off.

If the Device Enable signal to the AP is LOW, ARM recommends that CDBGRSTREQ from an AP is ignored by the reset controller DEVICEEN.

——— Caution ————
System-level use of debug components must be handled with caution. ARM recommends that such system-level usage is not combined with a reset system that permits those debug components to be reset without the knowledge of the system. ARM recommends that debuggers do not use debug reset requests unless necessary.
B2.5 System reset control behavior

The DP does not provide control bits for requesting a system reset. However, it is common for the physical interface to the debugger to include a system reset pin, nSRST. This section describes the recommended behavior of the system when a system reset is requested on the nSRST pin.

nSRST is an active LOW pin that can be asserted and deasserted at any point in time, regardless of the current state of the target system, to return the target system to a known state for booting and for starting a debug session.

While nSRST is asserted:
- The target system must be held in the known state.
- The debugger must be able to access the debug domain of the target system.

B2.5.1 Limitations of system reset control

The debugger must ensure that the DAP is not accessing the system when asserting nSRST. When nSRST is asserted, the debugger can access the debug domain.

The effect of nSRST on the debug domain is IMPLEMENTATION DEFINED.

For example, to safely return the target system to a known state, the debug domain might also require to be reset. When nSRST is asserted, the entire system must be reset, including the debug domain. However, the debug domain must be released from reset to allow the debugger access. Only the non-debug domain is held in reset while nSRST is asserted.

ARM recommends that debuggers set CTRL/STAT.CDBGWRUPREQ to 0b1 while nSRST is initially asserted.

![Example system reset timing diagram](image)

1. At time T1, the debugger writes 0b0 to CTRL/STAT.CDBGWRUPREQ.
2. At time T2, the system power controller acknowledges the request and CTRL/STAT.CDBGWRUPACK is set to 0b0.
3. At time T3, the debugger asserts nSRST. The debug domain and non-debug domain are reset at time T3a. The debug domain reset is complete by time T4a.
4. At time T4, the debugger writes 0b1 to CTRL/STAT.CDBGWRUPREQ.
5. At time T5, the system power controller acknowledges this request and signals the debug domain reset is complete by setting CTRL/STAT.CDBGWRUPACK to 0b1. The debugger can now program the debug domain.
6. At time T6, the debugger releases nSRST. The non-debug domain reset completes at time T6a.
Chapter B3
The JTAG Debug Port (JTAG-DP)

This chapter describes the implementation of the JTAG Debug Port (JTAG-DP), and in particular, the Debug Test Access Port (DBGTAP), the Debug Test Access Port State Machine (DBGTAPSM), and scan chains.

It is only relevant to ARM Debug Interface implementations that use a JTAG Debug Port. In this case, the JTAG-DP provides the external connection to the DAP, and all interface accesses are made using the scan chains, which are driven by the DBGTAPSM.

This chapter contains the following sections:

• The scan chain interface on page B3-87.
• IR scan chain and IR instructions on page B3-91.
• DR scan chain and DR instructions on page B3-95.
B3.1 About the JTAG-DP

The JTAG-DP is based on the IEEE 1149.1 Standard for Test Access Port (TAP) and Boundary Scan Architecture, widely referred to as JTAG. To emphasize that the JTAG-DP is intended for accessing debug components, the naming convention that is used in this document differs from the IEEE 1149.1 naming convention by adding the prefix DBG, as shown in Table B3-1:

<table>
<thead>
<tr>
<th>IEEE 1149.1 name</th>
<th>JTAG-DP name</th>
<th>JTAG-DP description</th>
</tr>
</thead>
<tbody>
<tr>
<td>TAP</td>
<td>DBGTAP</td>
<td>Debug Test Access Port.</td>
</tr>
<tr>
<td>TAPSM</td>
<td>DBGTAPSM</td>
<td>Debug Test Access Port State Machine.</td>
</tr>
</tbody>
</table>

The signal naming conventions of IEEE 1149.1 are modified in a similar way, for example the IEEE 1149.1 TDI signal is named DBGTDI on a JTAG Debug Port. See Physical connection to the JTAG-DP on page B3-88 for the complete list of the JTAG-DP signal names.
B3.2 The scan chain interface

When a Debug Access Port (DAP) is implemented with a JTAG-DP, the wire-level interface accesses the APACC scan chain to access debug resources in the system being debugged, or the DPACC scan chain to access information internal to the DAP.

B3.2.1 DAP elements

The DAP requires the following elements to support JTAG scan chains:

- A Debug TAP State Machine (DBGTAPSM).
- An Instruction Register (IR), which selects and controls the available scan chains.
- Various Data Registers (DRs), which hold the information that is exposed through the available scan chains, and interface to:
  - The DP registers in the DAP itself.
  - The debug registers in the device or debug component being accessed through the DAP.

Figure B3-1 shows how the scan chains provide access to the different levels of the DAP architecture. For more details, see Figure A1-2 on page A1-30.

**Physical connection perspective**

![Physical connection perspective diagram]

**Scan chains perspective**

![Scan chains perspective diagram]

Figure B3-1 JTAG-DP scan chain access to the different levels of the ADI
### B3.2.2 Physical connection to the JTAG-DP

The physical connection to the JTAG-DP closely follows the JTAG model. Table B3-2 lists the recommended signals for the JTAG-DP physical connection alongside their equivalent JTAG signal names.

#### Table B3-2 JTAG-DP signal connections

<table>
<thead>
<tr>
<th>JTAG-DP signal name</th>
<th>JTAG equivalent signal name</th>
<th>Direction</th>
<th>Required?</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>DBGTDI</td>
<td>TDI</td>
<td>Input</td>
<td>Yes</td>
<td>Debug Data In</td>
</tr>
<tr>
<td>DBGTDO</td>
<td>TDO</td>
<td>Output</td>
<td>Yes</td>
<td>Debug Data Out</td>
</tr>
<tr>
<td>TCK</td>
<td>TCK</td>
<td>Input</td>
<td>Yes</td>
<td>Debug Clock</td>
</tr>
<tr>
<td>DBGTMS</td>
<td>TMS</td>
<td>Input</td>
<td>Yes</td>
<td>Debug Mode Select</td>
</tr>
<tr>
<td>DBGTRSTn</td>
<td>TRST</td>
<td>Input</td>
<td>Optional</td>
<td>Debug TAP Reset</td>
</tr>
</tbody>
</table>

An implementation might include a return clock signal, RTCK. However, ARM recommends not to use RTCK in ADI implementations.

### B3.2.3 The Debug TAP State Machine (DBGTAPSM)

The Debug TAP State Machine (DBGTAPSM) controls the operation of a JTAG-DP. In particular, it controls the scan chain interface that provides the external physical interface to the DAP through the JTAG-DP. It is based closely on the JTAG TAP State Machine, see IEEE 1149.1-1990 IEEE Standard Test Access Port and Boundary Scan Architecture.

Figure B3-2 on page B3-89 shows the state diagram for the DBGTAPSM.
The DBGTAPSM uses the following process:

- The **DBGTDI** signal input is the start of the scan chain, and the **DBGTD0** signal output is the end of the scan chain.

- When the DBGTAPSM goes through the Capture-IR state:
  - When using a 4-bit IR, 0b0001 is transferred to the IR scan chain.
  - When using an 8-bit IR, 0b00000001 is transferred to the IR scan chain.
  - The IR scan chain is connected between **DBGTDI** and **DBGTD0**.

- While the DBGTAPSM is in the Shift-IR state, the IR scan chain advances one bit for each rising edge of **TCK**. On the first tick:
  - The LSB of the IR scan chain is output on **DBGTD0**.
  - Bit[1] of the IR scan chain is transferred to bit[0].
  - Bit[2] of the IR scan chain is transferred to bit[1].
  - Similarly, for every other bit \( n \) of the IR scan chain, bit[\( n \)] of the scan chain is transferred to bit[\( n-1 \)].
  - The value on **DBGTDI** is transferred to the MSB of the IR scan chain.
• When the DBGTAPSM goes through the Update-IR state, the value that is scanned into the IR scan chain is transferred into the Instruction Register.

• The value that is held in the Instruction Register selects a Data Register, and an associated DR scan chain. When the DBGTAPSM goes through the Capture-DR state, the value of the selected Data Register (DR) is transferred to the selected DR scan chain, which is connected between DBGTDI and DBGTDO. This data is then shifted while the DBGTAPSM is in the Shift-DR state, in the same manner as the IR shift in the Shift-IR state.

• When the DBGTAPSM goes through the Update-DR state, the value that is scanned into the DR scan chain is transferred into the selected Data Register.

• When the DBGTAPSM is in the Run-Test/Idle state, no special actions occur. Debuggers can use this state as a true resting state.

Note
This behavior is different from the behavior of previous versions of the ADI that were based on the IEEE JTAG standard. From ARM Debug Interface v5, there is no requirement for debuggers to gate TCK to obtain a true rest state.

The behavior of the IR and DR scan chains is described in more detail in IR scan chain and IR instructions on page B3-91 and DR scan chain and DR instructions on page B3-95.

The DBGTRSTn signal only resets the DBGTAP state machine and Instruction Register. DBGTRSTn asynchronously takes the DBGTAPSM to the Test-Logic-Reset state. As shown in Figure B3-2 on page B3-89, the Test-Logic-Reset state can also be entered synchronously from any state by a sequence of five TCK cycles with DBGTMS HIGH. However, depending on the initial state of the DBGTAPSM, this transition might take the state machine through one of the Update states, with the resulting side effects.

The reset behavior of the registers is as follows:

• The DP registers are only reset on a powerup reset.

• The AP registers are reset on a powerup reset, and also by the Debug Reset Control described in Debug reset control behavior on page B2-81.
B3.3 IR scan chain and IR instructions

This section describes the JTAG-DP Instruction Register (IR), accessed through the IR scan chain.
B3.3.1 Required IR instructions

As described in The Debug TAP State Machine (DBGTAPSM) on page B3-88, the JTAG-DP transfers an instruction into the IR. This instruction determines the Data Register that the JTAG-DP Data Register maps onto, as described in DR scan chain and DR instructions on page B3-95.

The width of the IR is IMPLEMENTATION DEFINED, and can be four or eight bits.

The standard IR instructions, which are required for all JTAG-DP implementations, are listed in Table B3-3, and recommended IMPLEMENTATION DEFINED extensions to this instruction set are described in IMPLEMENTATION DEFINED extensions to the IR instruction set on page B3-93.

Unused IR instruction values are reserved and select the BYPASS register.

Table B3-3 Standard IR instructions

<table>
<thead>
<tr>
<th>4-bit IR instruction value</th>
<th>8-bit IR instruction value</th>
<th>Data register</th>
<th>DR scan length</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>0b0xxx</td>
<td>0b0xxxxxxx</td>
<td>-</td>
<td>-</td>
<td>IMPLEMENTATION DEFINED extensions to the IR instruction set on page B3-93.</td>
</tr>
<tr>
<td>-</td>
<td>0b10000000-0b11110111</td>
<td>-</td>
<td>-</td>
<td>Reserved.</td>
</tr>
<tr>
<td>0b1000</td>
<td>0b11111000</td>
<td>ABORT</td>
<td>35</td>
<td>-</td>
</tr>
<tr>
<td>0b1001</td>
<td>0b11111001</td>
<td>-</td>
<td>-</td>
<td>Reserved.</td>
</tr>
<tr>
<td>0b1010</td>
<td>0b11111010</td>
<td>DPACC</td>
<td>35</td>
<td>See DPACC and APACC, JTAG-DP DP and AP Access registers on page B3-97.</td>
</tr>
<tr>
<td>0b1011</td>
<td>0b11111011</td>
<td>APACC</td>
<td>35</td>
<td></td>
</tr>
<tr>
<td>0b110x</td>
<td>0b1111110x</td>
<td>-</td>
<td>-</td>
<td>Reserved.</td>
</tr>
<tr>
<td>0b1110</td>
<td>0b11111110</td>
<td>IDCODE</td>
<td>32</td>
<td>-</td>
</tr>
<tr>
<td>0b1111</td>
<td>0b11111111</td>
<td>BYPASS</td>
<td>1</td>
<td>Required by JTAG specification.</td>
</tr>
</tbody>
</table>
B3.3.2 IMPLEMENTATION DEFINED extensions to the IR instruction set

The 4-bit IR instructions 0b0000 to 0b0111 and the 8-bit instructions 0b00000000 to 0b01111111 are reserved for IMPLEMENTATION DEFINED extensions to the DAP.

These instructions can be used for accessing a boundary scan register, for IEEE 1149.1 compliance, as shown in Table B3-4. All these instructions select the boundary scan data register.

--- Note ---
This extension describes only boundary scan instructions that are described by IEEE 1149.1-2001. Later editions of IEEE 1149.1 define additional instructions.

ARM recommends that:
- Separate JTAG TAPs are used for boundary scan and debug.
- The instructions that are listed in Table B3-4 are not implemented.

If the IR register is set to an IR instruction value that is not implemented, or reserved, then the BYPASS register is selected.

### Table B3-4 Recommended IMPLEMENTATION DEFINED IR instructions for IEEE 1149.1-compliance

<table>
<thead>
<tr>
<th>4-bit IR instruction value</th>
<th>8-bit IR instruction value</th>
<th>Instruction</th>
<th>Required by IEEE 1149.1?</th>
</tr>
</thead>
<tbody>
<tr>
<td>0b0000</td>
<td>0b00000000</td>
<td>EXTEST</td>
<td>See note in main text.</td>
</tr>
<tr>
<td>0b0001</td>
<td>0b00000001</td>
<td>SAMPLE</td>
<td>Yes</td>
</tr>
<tr>
<td>0b0010</td>
<td>0b00000010</td>
<td>PRELOAD</td>
<td>Yes</td>
</tr>
<tr>
<td>0b0100</td>
<td>0b00000100</td>
<td>INTEST</td>
<td>No</td>
</tr>
<tr>
<td>0b0101</td>
<td>0b00000101</td>
<td>CLAMP</td>
<td>No</td>
</tr>
<tr>
<td>0b0110</td>
<td>0b00000110</td>
<td>HIGHZ</td>
<td>No</td>
</tr>
</tbody>
</table>

If you require a boundary scan implementation, you must implement the instructions that are required by IEEE 1149.1. The other IR instruction values that are listed in Table B3-4 are reserved encodings that must be used if that function is implemented in the boundary scan. If implemented, these instructions must behave as required by the IEEE 1149.1 specification. If not implemented, they select the BYPASS register.

--- Note ---
**EXTEST instruction** The original revision of the IEEE 1149.1 specification, 1149.1-1990, requires that instruction {000..0} is EXTEST. However, in more recent editions this requirement is removed and the specification recommends that instruction {000..0} is reserved. See the IEEE specification for more details.

The IEEE 1149.1 specification also defines the IDCODE and BYPASS instructions, which are included in Table B3-3 on page B3-92.

B3.3.3 IR, JTAG-DP Instruction Register

**Purpose**
Holds the current DAP Controller instruction.

**Configurations**
This register is mandatory in the IEEE 1149.1 standard.
Attributes

IMPLEMENTATION DEFINED, a 4-bit or 8-bit register.

Operation

The operation of the IR register is shown in the following figure:

![Diagram showing IR register operation for 4-bit and 8-bit lengths]

When in Shift-IR state, the shift section of the IR is selected as the serial path between DBGTDI and DBGTDO. At the Capture-IR state, the binary value 0b0001 for 4-bit instructions, or 0b00000001 for 8-bit instructions, is loaded into this shift section. This value is shifted out, least significant bit first, during Shift-IR, while a new instruction is shifted in, least significant bit first:

- At the Update-IR state, the value in the shift section is loaded into the IR and becomes the current instruction.
- In the Test-Logic-Reset state, IDCODE becomes the current instruction.
B3.4 DR scan chain and DR instructions

The DR scan chain is associated with the DR registers:

- The BYPASS and IDCODE registers, as defined by the IEEE 1149.1 standard.
- The DPACC and APACC Access registers, xPACC.
- An ABORT register, to abort a transaction.

This section describes each of these registers.

The instruction in the IR register determines which of these scan chains is connected to the DBGTDI and DBGTDO signals, see IR scan chain and IR instructions on page B3-91.
**B3.4.1 ABORT, JTAG-DP Abort register**

**Purpose**

Access the Abort register in the DP, to force an AP abort.

This implementation is the JTAG-DP implementation of the ABORT register.

**Attributes**

A 35-bit register.

**Operation**

The operation of the ABORT register is shown in the following figure:

When the ABORT instruction is the current instruction in the IR, the serial path between DBGTDI and DBGTDO is connected to a 35-bit scan chain that accesses the ABORT register.

In DPv0, the effect of writing a value other than 0x00000001 to the ABORT register is UNPREDICTABLE, which means that, in DPv0, the debugger must scan the value 0x00000008 into this scan chain. For more information, see **ABORT, Abort register** on page B2-53.

**B3.4.2 BYPASS, JTAG-DP Bypass register**

**Purpose**

Bypasses the device, by providing a direct path between DBGTDI and DBGTDO.

**Configurations**

This register is mandatory in the IEEE 1149.1 standard.

**Attributes**

A 1-bit register.

**Operation**

The operation of the BYPASS register is shown in the following figure:

When the BYPASS instruction is the current instruction in the IR:

- In the Shift-DR state, data is transferred from DBGTDI to DBGTDO with a delay of one TCK cycle.
- In the Capture-DR state, a logic 0 is loaded into this register.
- In the Update-DR state, nothing happens. The shifted-in data is ignored.
B3.4.3 DPACC and APACC, JTAG-DP DP and AP Access registers

The DPACC and APACC scan chains have the same format.

**Purpose**

DPACC and APACC are used to read from and write to DP or AP registers. The DPACC scan chain uses A[3:2], SELECT, DPBANKSEL and RnW to determine the address of the DP register to be accessed, as summarized in Table B3-5. For detailed information about addressing JTAG-DP registers, see *DP architecture versions* on page B2-48.

**Note**

The DP register ABORT is accessed through the ABORT instruction.

**Table B3-5 JTAG-DP Register access summary.**

<table>
<thead>
<tr>
<th>Register</th>
<th>Access</th>
<th>Address (A&lt;sup&gt;a&lt;/sup&gt;, SELECT, DPBANKSEL)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>DPv0</td>
</tr>
<tr>
<td>CTRL/STAT</td>
<td>RW</td>
<td>0x4, -</td>
</tr>
<tr>
<td>DLCR</td>
<td>RW</td>
<td>-</td>
</tr>
<tr>
<td>DLPIDR</td>
<td>RO</td>
<td>-</td>
</tr>
<tr>
<td>DPIDR</td>
<td>RO</td>
<td>-</td>
</tr>
<tr>
<td>EVENTSTAT</td>
<td>RO</td>
<td>-</td>
</tr>
<tr>
<td>RDBUFF</td>
<td>RO</td>
<td>0xC, -</td>
</tr>
<tr>
<td>SELECT</td>
<td>WO&lt;sup&gt;b&lt;/sup&gt;</td>
<td>0x8, -</td>
</tr>
<tr>
<td>TARGETID</td>
<td>RO</td>
<td>-</td>
</tr>
</tbody>
</table>

<sup>a</sup> Bits [1:0] of the address are always 0b00.
<sup>b</sup> RW for DPv0

- *MEM-AP Programmers' Model* on page C2-166 for details of accessing MEM-AP registers.
- *JTAG-AP register summary* on page C3-200 for details of accessing JTAG-AP registers.

**Attributes**

DPACC and APACC are 35-bit registers.

**Operation**

The operation of the DPACC and APACC registers is shown in the following figure:
When the DPACC or APACC instruction is the current instruction in the IR, the shift section of the DP Access register or AP Access register is selected as the serial path between \texttt{DBGTDI} and \texttt{DBGTDO}:

- In the Capture-DR state, the result of the previous transaction, if any, is returned, together with a 3-bit ACK response. The ACK responses that are implemented are summarized in Table B3-6.

<table>
<thead>
<tr>
<th>Response</th>
<th>ACK[2:0] encoding</th>
<th>See:</th>
</tr>
</thead>
<tbody>
<tr>
<td>OK/FAULT</td>
<td>0b010</td>
<td>OK/FAULT response to a DPACC or APACC access</td>
</tr>
<tr>
<td>WAIT</td>
<td>0b001</td>
<td>WAIT response to a DPACC or APACC access on page B3-99</td>
</tr>
</tbody>
</table>

All other ACK encodings are reserved.

- In the Shift-DR state, this data is shifted out, least significant bit first. The first three bits of data that are shifted out are ACK[2:0].

As the returned data is shifted out to \texttt{DBGTDO}, new data is shifted in from \texttt{DBGTDI}, as described in \texttt{OK/FAULT} response to a DPACC or APACC access.

- Operation in the Update-DR depends on whether the ACK[2:0] response was OK/FAULT or WAIT. The two cases are described in:
  - \texttt{OK/FAULT} response to a DPACC or APACC access.
  - \texttt{WAIT} response to a DPACC or APACC access on page B3-99.

### OK/FAULT response to a DPACC or APACC access

If the response indicated by ACK[2:0] is OK/FAULT, the previous transaction has completed. The response code does not show whether the transaction completed successfully or failed. You must read the CTRL/STAT register to find whether the transaction was successful:

- If the previous instruction in the IR was not one of DPACC, APACC or BYPASS, the captured ReadResult[31:0] is UNKNOWN, and if Data[34:3] is shifted out it must be discarded.

- If the previous transaction was a read that completed successfully, the captured ReadResult[31:0] is the requested register value. This result is shifted out as Data[34:3].

- If the previous transaction was a write, or a read that did not complete successfully, the captured ReadResult[31:0] is UNKNOWN, and if Data[34:3] is shifted out it must be discarded.

An OK/FAULT response is followed by an Update-DR operation to fulfill the read or write request that is formed by the values that were shifted into the scan chain:

- \texttt{DBGTDI} and \texttt{DBGTDO} connect to the scan chain corresponding to the current IR instruction, and the specified address is used to select a register.

- For write requests, corresponding to RnW having a value of 0b0, the value in DATAIN[31:0] is written to the selected register.

- For read requests, corresponding to RnW having a value of 0b1, the value in DATAIN[31:0] is IGNORED. Another scan is required to obtain the read data.

Register accesses can be pipelined, because a single DPACC or APACC scan can return the result of the previous read operation at the same time as shifting in a request for another register access. At the end of a sequence of pipelined register reads, you can read the DP \texttt{RDBUFF} register to shift out the result of the final register read.

Reading the DP \texttt{RDBUFF} register has no effect on the operation of the \texttt{DBGTAPSM}. For details about returning the result from a previous DPACC or APACC scan, see section Target response summary on page B3-100.
If the current IR instruction is APACC, an AP access is requested:

- If any sticky flag in the DP CTRL/STAT register is 0b1, the transaction is discarded. The next scan returns an OK/FAULT response. For more information, see Sticky flags and DP error responses on page B1-41.

- If pushed-compare or pushed-verify operations are enabled, the scanned-in value of RnW must be 0b0, otherwise behavior is UNPREDICTABLE. On Update-DR, a read request is issued, and the returned value is compared against DATAIN[31:0]. The CTRL/STAT.STICKYCMP flag is updated based on this comparison. For more information, see Pushed-compare and pushed-verify operations on page B1-44.

Pushed operations are enabled using the CTRL/STAT.TRNMODE field.

- The AP access does not complete until the AP signals it as completed. For example, if you access a Memory Access Port (MEM-AP), the AP access might cause an access to a memory system connected to the MEM-AP. In this case, the AP access does not complete until the memory system signals to the MEM-AP that the memory access has completed.

### WAIT response to a DPACC or APACC access

A WAIT response indicates that the previous transaction has not completed. Normally, after receiving a WAIT response the host retries the DPACC or APACC access.

---

**Note**

The previous transaction might be either a DP or an AP access. DP accesses are stalled, by returning WAIT, until any previous AP transaction has completed.

---

Normally, if software detects a WAIT response, it retries the same transfer, which enables the protocol to process data as quickly as possible. However, if the software has retried a transfer several times, and has waited long enough for a slow interconnect and memory system to respond, it might write to the ABORT register to cancel the operation. This action signals to the active AP that it must terminate the transfer that it is attempting, to permit access to other parts of the debug system. An AP might not be able to terminate a transfer on its SoC interface. However, on receiving an ABORT, the AP must free its interface to the DP.

No request is generated at the Update-DR state, and the shifted-in data is discarded. The captured value of ReadResult[31:0] is UNKNOWN.

### Sticky overrun behavior on DPACC and APACC accesses

At the Capture-DR state, if the previous transaction has not completed, a WAIT response is generated. In this case, if the Overrun Detect flag, CTRL/STAT.ORUNDETECT is 0b1, the Sticky Overrun flag, CTRL/STAT.STICKYORUN, is set to 0b1.

As long as the previous transaction is not completed, subsequent scans also receive a WAIT response.

When the previous transaction has completed, any additional APACC transactions are abandoned and scans respond with an OK/FAULT response. However, DP registers can be accessed. In particular, the CTRL/STAT register can be accessed, to confirm that the Sticky Overrun flag is 0b1, and to clear the flag to 0b0 after gathering any required information about the overrun condition. See Sticky flags and DP error responses on page B1-41 for more information.

### Minimum response times

As explained in OK/FAULT response to a DPACC or APACC access on page B3-98, a DP or AP register access is initiated at the Update-DR state of one DPACC or APACC access, and the result of the access is returned at the Capture-DR state of the following DPACC or APACC access. If the requested register access has not completed, however, the second access generates a WAIT response.

The timing between the Update-DR state and the Capture-DR state is defined in terms of TCK cycles. Referring to Figure B3-2 on page B3-89, there are two paths from the Update-DR state, where the register access is initiated, to the Capture-DR state, where the response is captured:

- A direct path through Select-DR-Scan.
• A path through Run-Test/Idle and Select-DR-Scan.

If the second path is followed, the state machine can spend a variable number of TCK cycles in the Run-Test/Idle state, which in turn varies the number of TCK cycles between the Update-DR and Capture-DR states.

A JTAG-DP implementation might impose an IMPLEMENTATION DEFINED lower limit on the number of TCK cycles between the Update-DR and Capture-DR states, and always generate an immediate WAIT response if Capture-DR is entered before this limit has expired. Although any debugger must be able to recover successfully from any WAIT response, ARM recommends that debuggers must be able to adapt to any IMPLEMENTATION DEFINED limit.

Note

Accessing AP registers or debug resources in connected device through an AP can be subjected to other variable response delays in the system. A debugger that can adapt to these delays and avoid wasting WAIT scans operates more efficiently and provides higher maximum data throughput.

Target response summary

As described in OK/FAULT response to a DPACC or APACC access on page B3-98, a DP or AP register access is initiated at the Update-DR state of one DPACC or APACC access, and the result of the access is returned at the Capture-DR state of the following DPACC or APACC access. The target responses, at the Capture-DR state, for every possible DPACC and APACC access in the previous scan, are summarized in:

• Table B3-7, for cases where the previous scan was a DPACC access.
• Table B3-8 on page B3-101, for cases where the previous scan was an APACC access.

Note

The target responses that are shown in Table B3-7 are independent of the operation being performed in the current DPACC or APACC scan. In this table, Read result is the data that is shifted out as Data[34:3], and ACK is decoded from the data that is shifted out as Data[2:0].

Table B3-7 JTAG-DP target response summary, when previous scan was a DPACC access

<table>
<thead>
<tr>
<th>Previous scana, at Update-DR state</th>
<th>Current scan, at Capture-DR state</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>Access</td>
<td>A/b</td>
<td>AP stated</td>
</tr>
<tr>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>X</td>
<td>X</td>
<td>Not Busy</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>R</td>
<td>0b00</td>
<td>X</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>0b01</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>0b10</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>0b11</td>
<td></td>
</tr>
</tbody>
</table>

Note

The return value depends on the DP version:

• DPv1, DPv2 Returns the value of DPIDR.
• DPv0 Returns UNKNOWN value.

Returns CTRL/STAT value.

Returns SELECT value.

Returns RDBUFF value, always zero.
### Table B3-7 JTAG-DP target response summary, when previous scan was an DPACC access (continued)

<table>
<thead>
<tr>
<th>Previous scan, at Update-DR state</th>
<th>Current scan, at Capture-DR state</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>Access A&lt;sup&gt;b&lt;/sup&gt; Sticky?&lt;sup&gt;c&lt;/sup&gt; AP state&lt;sup&gt;d&lt;/sup&gt; Read result</td>
<td></td>
<td></td>
</tr>
<tr>
<td>W 0b00 X</td>
<td>Not Busy UNKNOWN OK/ FAULT</td>
<td>The result depends on the DP version: DPv2 Write is ignored, returns RES0. DPv0, DPv1 Behavior is UNPREDICTABLE.</td>
</tr>
<tr>
<td>0b01</td>
<td>Value has been written to CTRL/STAT.</td>
<td></td>
</tr>
<tr>
<td>0b10</td>
<td>Value has been written to SELECT.</td>
<td></td>
</tr>
<tr>
<td>0b11</td>
<td>Writes to RDBUFF always ignored.</td>
<td></td>
</tr>
</tbody>
</table>

a. The previous scan is the most recent scan for which the ACK response at the Capture-DR state was OK/FAULT. Updates that are made following a WAIT response are discarded.
c. The Sticky? column indicates whether any Sticky flag was 0b1 in the DP CTRL/STAT register.
d. The state of the AP when the current scan reaches the Capture-DR state, or the response from the AP at that time.

### Table B3-8 JTAG-DP target response summary, when previous scan was an APACC access

<table>
<thead>
<tr>
<th>Previous scan, at Update-DR state</th>
<th>Current scan, at Capture-DR state</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>Access A&lt;sup&gt;b&lt;/sup&gt; Sticky?&lt;sup&gt;c&lt;/sup&gt; AP state&lt;sup&gt;d&lt;/sup&gt; Read result</td>
<td></td>
<td></td>
</tr>
<tr>
<td>X X X</td>
<td>Busy UNKNOWN WAIT</td>
<td>If the Overrun Detect flag is 0b1, this access and response sequence causes the Sticky Overrun flag to be set to 0b1. See CTRL/STAT, Control/Status register on page B2-55.</td>
</tr>
<tr>
<td>R X No Ready See Notes</td>
<td>OK/ FAULT</td>
<td>If pushed-verify or pushed-compare is implemented and enabled, the behavior is UNPREDICTABLE.</td>
</tr>
<tr>
<td></td>
<td>Error UNKNOWN</td>
<td>Sticky Error flag is set to 0b1.</td>
</tr>
<tr>
<td>W X No Ready UNKOWN</td>
<td>OK/ FAULT</td>
<td>The data that was captured at the previous scan has been written to the requested AP register. If pushed-verify or pushed-compare is implemented and enabled, the previous pushed transaction might have set the Sticky Compare flag to 0b1, see Pushed-compare and pushed-verify operations on page B1-44.</td>
</tr>
<tr>
<td></td>
<td>Error UNKNOWN</td>
<td>Sticky Error flag is set to 0b1.</td>
</tr>
<tr>
<td>X X Yes Not busy UNKNOWN OK/ FAULT</td>
<td>Previous transaction was discarded.</td>
<td></td>
</tr>
</tbody>
</table>

a. The previous scan is the most recent scan for which the ACK response at the Capture-DR state was OK/FAULT. Updates that are made following a WAIT response are discarded.
c. The Sticky? column indicates whether any Sticky flag was 0b1 in the DP CTRL/STAT register.
d. The state of the AP when the current scan reaches the Capture-DR state, or the response from the AP at that time.
Host response summary

The ACK column, for the Current scan, at Capture-DR state section of Table B3-7 on page B3-100 and Table B3-8 on page B3-101, shows the responses that the host might receive after initiating a DPACC or APACC access. Table B3-9 indicates the normal action of a host in response to each of these ACKs.

**Table B3-9 Summary of JTAG-DP host responses**

<table>
<thead>
<tr>
<th>Access type</th>
<th>ACK from target</th>
<th>Suggested host action in response to ACK</th>
</tr>
</thead>
<tbody>
<tr>
<td>Read</td>
<td>OK/FAULT</td>
<td>Capture read data.</td>
</tr>
<tr>
<td>Write</td>
<td>OK/FAULT</td>
<td>No action required.</td>
</tr>
<tr>
<td>Read or Write</td>
<td>WAIT</td>
<td>Repeat the same access until either an OK/FAULT ACK is received or the wait timeout is reached. If necessary, use the Abort register to enable access to the AP.</td>
</tr>
<tr>
<td>Read or Write</td>
<td>Invalid ACK</td>
<td>Assume that a target or line error has occurred and treat as a fatal error.</td>
</tr>
</tbody>
</table>
### B3.4.4 IDCODE, the JTAG TAP ID register

#### Purpose

JTAG-DP TAP identification. The IDCODE value enables a debugger to identify the Debug Port to which it is connected. JTAG-DP implementations have different IDCODE values, so that a debugger can distinguish between them.

When the IDCODE instruction is the current instruction in the IR, the shift section of the Device ID Code register is selected as the serial path between DBGTDI and DBGTDO:

- In the Capture-DR state, the 32-bit device ID code is loaded into this shift section.
- In the Shift-DR state, this data is shifted out, least significant bit first.
- Nothing happens at the Update-DR state. The shifted-in data is ignored.

#### Attributes

A 32-bit register.

#### Field descriptions

The IDCODE bit assignments and operating mode are:

![IDCODE Bit Assignments](image)

- **VERSION**, bits[31:28]
  - Version code. The meaning of this field is IMPLEMENTATION DEFINED.
- **PARTNO**, bits[27:12]
  - Part Number for the DP TAP. This value is provided by the designer of the Debug Port TAP and must not be changed.
- **DESIGNER**, bits[11:1]
  - The Designer ID is an 11-bit JEDEC code that identifies the designer of the JTAG-DP TAP. It is formed from the JEDEC JEP106 continuation code and identity code as shown in Table B3-10.

JEDEC codes are assigned by the JEDEC Solid State Technology Association, see [JEDEC](https://www.jedec.org) Standard Manufacturer’s Identification Code.

Normally, this field identifies the designer of the ADIv5 implementation, rather than the system architect or the device manufacturer. If the DAP is used for boundary scan, however, the field must conform to the JEDEC Manufacturer ID assigned to the manufacturer of the device.

The ARM default value for this field is $0x23B$. Other designers must use their own JEDEC assigned code.

- **Bit[0]**
  - RAO.

#### Table B3-10 JEDEC JEP106 manufacturer ID code, with ARM values

<table>
<thead>
<tr>
<th>JEP106 field</th>
<th>Width (bits)</th>
<th>Bits in IDCODE</th>
<th>ARM registered value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Continuation code</td>
<td>4</td>
<td>Bits[11:8]</td>
<td>$0b100 (0x4)</td>
</tr>
<tr>
<td>Identity code</td>
<td>7</td>
<td>Bits[7:1]</td>
<td>$0b111011 (0x38)</td>
</tr>
</tbody>
</table>
The JTAG Debug Port (JTAG-DP)

B3.4 DR scan chain and DR instructions
Chapter B4
The Serial Wire Debug Port (SW-DP)

This chapter describes the implementation of the Serial Wire Debug Port (SW-DP), including the SWD interface. It is only relevant if your ARM Debug Interface implementation uses an SW-DP. In this case, the SW-DP provides the external connection to the debug interface, and all interface accesses are made using the SWD protocol summarized in this chapter.

Note
The ARM SWD interface is a synchronous serial interface. This chapter does not describe the physical characteristics of the SWD interface, such as signal timings.

Contact ARM if you require more detailed information about the implementation of the ARM SWD interface.

This chapter contains the following sections:
- About the SWD protocol on page B4-106.
- SWD protocol operation on page B4-110.
- SWD interface on page B4-122.
B4.1 About the SWD protocol

This section provides general information about the ARM SWD protocol. It contains the following sections:

- Basic operation.
- SWD protocol versions.
- Line turnaround.
- Idle cycles.
- Bit order.
- Parity.
- Limitations of multi-drop.

B4.1.1 Basic operation

The ARM SWD interface uses a single bidirectional data connection and a separate clock to transfer data synchronously. An operation on the wire consists of two or three phases:

Packet request
The external host debugger issues a request to the DP. The DP is the target of the request.

Acknowledge response
The target sends an acknowledge response to the host.

Data transfer phase
This phase is only present when either:

- A data read or data write request is followed by a valid (OK) acknowledge response.
- The CTRL/STAT.ORUNDETECT flag is 0b1.

The data transfer is one of:

- Target to host, following a read request (RDATA).
- Host to target, following a write request (WDATA).

Note
If the CTRL/STAT.ORUNDETECT bit is 0b1, a data transfer phase is required on all responses, including WAIT and FAULT. For more information, see Sticky overrun behavior on page B4-115.

When the SW-DP receives a packet request from the debug host, it must respond immediately by entering the acknowledge phase. There is a turnaround period between these phases, as they are in different directions. If a data phase is required, it follows immediately after the acknowledge phase.

For a write request, there is a turnaround period between the acknowledge phase and the WDATA data transfer phase. Following the WDATA data transfer phase the host continues to drive the wire. There is no additional turnaround period.

For a read request, there is no turnaround period between the acknowledge phase and the data transfer phase. There is a turnaround period following the RDATA data transfer phase, following which the host drives the wire.

To ensure that the transfer can be clocked through the SW-DP, after the data transfer phase the host must do one of the following:

- Immediately start a new SWD operation with the start bit of a new packet request.
- Continue to drive the SWD interface with idle cycles until the host starts a new SWD operation.
- If the host is driving the SWD clock, continue to clock the SWD interface with at least eight idle cycles. After completing this sequence, the host can stop the clock.
B4.1.2 SWD protocol versions

SWD protocol version 1 is a point-to-point architecture, supporting connection between a single host and a single device. It permits connection to multiple devices by providing extra connections from the host, which has several disadvantages:

• It complicates the physical connection standard, by having variants with different numbers of connections.
• It increases the number of pins that are required for the connector on the device PCB, which is unacceptable where size is a limiting factor.
• It increases the number of pins that are required on a package with multiple dies inside.
• It makes it difficult to integrate multiple platforms that are accessed by the SWD protocol into the same chip.

Techniques to solve this require connections that are shared between multiple Serial Wire devices. These connections are detrimental to the maximum speed of operation, but in many situations they provide an acceptable trade-off.

SWD protocol version 2 is a multi-drop architecture that:

• Enables a two-wire host connection to communicate simultaneously with multiple devices.
• Permits an effectively unlimited number of devices to be connected simultaneously, subject to electrical constraints.
• Is largely backwards-compatible, because provision for multi-drop support in a device does not break point-to-point compatibility with existing host equipment that does not support the multi-drop extensions. For more information, see SWD protocol versions.
• Permits a device to power down completely, while the device is not selected.
• Prevents multiple devices from driving the wire simultaneously, and continues to support the wire being actively driven both HIGH and LOW, maintaining a high maximum clock speed.
• Permits multi-drop connections incorporating devices that do not implement the SWD protocol.

--- Note ---

SWD protocol version 2 requires the implementation of dormant state, which can limit its compatibility with SWD version 1:

• For an SWJ-DP implementation, JTAG is selected on a powerup reset. Selecting SWD bypasses the dormant state, and subsequent operation is compatible with SWD protocol version 1.
• For an SW-DP implementation of SWD protocol version 2, the dormant state is selected on a powerup reset, meaning the start-up state differs from a start-up with SWD protocol version 1. After SWD operation is selected, operation is compatible with SWD protocol version 1.

--- B4.1.3 Line turnaround ---

To prevent contention, a turnaround period is required when the device driving the wire changes. For the turnaround period, neither the host nor the target drives the wire, and the state of the wire is undefined. See also Line pull-up on page B4-122.

--- Note ---

The line turnaround period can provide for pad delays when using a high sample clock frequency.

The length of the turnaround period is controlled by DLCR.TURNROUND. The default setting is a turnaround period of one clock cycle.
B4.1.4  Idle cycles

After completing a transaction, the host must either insert idle cycles or continue immediately with the start bit of
a new transaction.

The host clocks the SWD interface with the line LOW to insert idle cycles.

B4.1.5  Bit order

All data values in SWD operations are transferred LSB first.

For example, the OK response of 0b001 appears on the wire as 1, followed by 0, followed by 0, as shown in
Figure B4-1 on page B4-111 and Figure B4-2 on page B4-112.

B4.1.6  Parity

A simple parity check is applied to all packet request and data transfer phases. Even parity is used:

Packet requests

- If the number of bits with a value of 0b1 is odd, the parity bit is set to 0b1.
- If the number of bits with a value of 0b1 is even, the parity bit is set to 0b0.

Data transfers (WDATA and RDATA)

The parity check is made over the 32 data bits WDATA[0:31] or RDATA[0:31]:

- If the number of bits with a value of 0b1 is odd, the parity bit is set to 0b1.
- If the number of bits with a value of 0b1 is even, the parity bit is set to 0b0.

The packet request parity bit is shown in each of the diagrams in this section, from Figure B4-1 on page B4-111 to
Figure B4-7 on page B4-116. It appears on the wire immediately after the A[2:3] bits. A parity error in the packet
request is detected by the SW-DP, which responds with a protocol error. See Protocol error response on
page B4-114.

The WDATA parity bit is shown in Figure B4-1 on page B4-111 and in Figure B4-7 on page B4-116. It appears on
the wire immediately after the WDATA[31] bit. A parity error in the WDATA data transfer phase is detected by
the SW-DP and, other than writes to TARGETSEL, recorded in CTRL/STAT.WDATAERR. If overrun detection is
enabled, CTRL/STAT.STICKYORUN is set to 0b1. A parity error in a write to TARGETSEL deselects the target.

The RDATA parity bit is shown in Figure B4-2 on page B4-112. It appears on the wire immediately after the
RDATA[31] bit. The debugger must check for parity errors in the RDATA data transfer phase and retry the read if
necessary.

Note

The ACK[0:2] bits are never included in the parity calculation. Debuggers must remember this principle when
parity checking the data from a read operation, when the debugger receives a continuous stream of 36 bits, as shown
in Figure B4-2 on page B4-112:

- Bits 0-2 are ACK[0:2].
- Bits 3-34 are RDATA[0:31].
- Bit 35 is the parity bit.

The parity check must be applied to bits 3-34 of this block of data, and the result must be compared with bit 35, the
parity bit.


**B4.1.7 Limitations of multi-drop**

This section describes the configuration and auto-detection limitations of a multi-drop SWD system.

**System configuration**

Each device must be configured with a unique target ID, which includes a 4-bit instance ID, to differentiate between otherwise identical targets. The 4-bit ID places a limit of 16 such targets in any system, and means that identical devices must be configured before they are connected together to ensure that their instance IDs do not conflict.

**Auto-detection of the target**

It is not possible to interrogate a multi-drop SWD system that includes multiple devices to establish which devices are connected. For a target with multiple devices, because all devices are selected on coming out of a line reset, no communication with a device is possible without prior selection of that target using its target ID. Therefore, connection to a multi-drop SWD system that includes multiple devices requires that either:

- The host has prior knowledge of the devices in the system and is configured before target connection.
- The host attempts auto-detection by issuing a target select command for each of the devices it has been configured to support. While auto-detection is likely to involve many target select commands, it must be possible to iterate through all the supported devices in a reasonable time from the viewpoint of a user of the debug tools.

For this reason, debug tools cannot connect seamlessly to targets in a multi-drop SWD system that they have never seen before. If the debug tools can be provided with the target ID of such targets, however, the contents of the target can be auto-detected as normal.

To protect against multiple selected devices all driving the line simultaneously, the SWD protocol version 2 requires:

- For multi-drop SWJ-DP, the JTAG connection is selected out of powerup reset. JTAG does not drive the line. See Chapter B5 The Serial Wire/JTAG Debug Port (SWJ-DP).
- For multi-drop SW-DP, the DP is in the dormant state out of powerup reset. See Dormant operation on page B5-131.
SWD protocol operation

This section gives an overview of the bidirectional operation of the protocol. It illustrates each of the possible sequences of operations on the SWD interface data connection.

--- Note ---

The diagrams in this section are included to show the operation of the SWD protocol. They are not timing diagrams for the protocol. Contact ARM if you require timing information for the serial connection to the SW-DP.

- Successful write operation (OK response) on page B4-111.
- Successful read operation (OK response) on page B4-112.
- WAIT response to read or write operation request on page B4-112.
- FAULT response to read or write operation request on page B4-113.
- Protocol error response on page B4-114.
- Sticky overrun behavior on page B4-115.
- SW-DP write buffering on page B4-116.

The illustrations of the different possible operations use the following terms:

- **Start**
  A single start bit, with value 0b1.

- **APnDP**
  A single bit, indicating whether the Debug Port or the Access Port Access register is to be accessed. This bit is 0b0 for a DPACC access, or 0b1 for an APACC access.

- **RnW**
  A single bit, indicating whether the access is a read or a write. This bit is 0b0 for a write access, or 0b1 for a read access.

- **A[2:3]**
  Two bits, giving the A[3:2] address field for the DP or AP register Address:
  - For a DPACC access, the register being addressed depends on the A[3:2] value and, if A[3:2]==0b01, the value that is held in SELECT.DPBANKSEL. For details, see:
    - DP architecture version 1 (DPv1) address map on page B2-50
    - DP architecture version 2 (DPv2) address map on page B2-51.
  - For an APACC access, the register being addressed depends on the A[3:2] value and the value that is held in SELECT.APSEL,APBANKSEL. For details about addressing, see:
    - MEM-AP Programmers’ Model on page C2-166 for accesses to a MEM-AP register
    - JTAG-AP register summary on page C3-200 for accesses to a JTAG-AP register.

--- Note ---

- **Parity**
  A single parity bit for the preceding packet. See Parity on page B4-108.

- **Stop**
  A single stop bit. In the synchronous SWD protocol, this bit is always 0b0.

- **Park**
  A single bit. The host must drive the Park bit HIGH to park the line before tristating it for the turnaround period, to ensure that the line is read as HIGH by the target, which is required because the pull-up on the SWD interface is weak. The target reads this bit as 0b1.

- **Trn**
  Turnaround. See Line turnaround on page B4-107.

--- Note ---
All the examples that are given in this chapter show the default turnaround period of one cycle.

- **ACK[0:2]**
  A three-bit target-to-host response.
The ACK value is transmitted LSB-first on the wire, which is why it appears as ACK[0:2] on the diagrams.

**Note**

WDATA[0:31]

32 bits of write data, from host to target.

**Note**

The WDATA value is transmitted LSB-first on the wire, which is why it appears as WDATA[0:31] on the diagrams.

RDATA[0:31]

32 bits of read data, from target to host.

**Note**

The RDATA value is transmitted LSB-first on the wire, which is why it appears as RDATA[0:31] on the diagrams.

### B4.2.1 Successful write operation (OK response)

On receiving a write packet request, if the SW-DP is ready for the WDATA data transfer phase, and there is no error condition, it issues an OK response. This response is indicated by a response value of 0b001.

This response does not apply to writes to TARGETSEL. See *Connection and line reset sequence* on page B4-122.

Therefore, a successful write operation consists of three phases:

1. An eight-bit write packet request, from the host to the target.
2. A three-bit OK acknowledge response, from the target to the host.
3. A 33-bit WDATA data transfer phase, from the host to the target.

By default, there are single-cycle turnaround periods between each of these phases. See *Line turnaround* on page B4-107 for more information.

A successful write operation is shown in Figure B4-1.

![Figure B4-1 SWD successful write operation](image-url)

The host must start transferring the write data immediately after receiving the OK acknowledge response from the target. This behavior is the same for writing to the DP or to an AP. The OK response that is shown in Figure B4-1 indicates that the DP is ready to accept the write data. The DP writes this data after the write phase has completed, and therefore the response to the DP write itself is given on the next operation. However, the SW-DP can buffer AP writes, as described in *SW-DP write buffering* on page B4-116.

There is no turnaround phase after the data phase. The host is driving the line, and can start the next operation immediately.
B4.2.2 Successful read operation (OK response)

On receiving a read packet request, if the SW-DP is ready for the RDATA data transfer phase, and there is no error condition, it issues an OK response. This response is indicated by a response value of 0b001.

Therefore, a successful read operation consists of three phases:
1. An eight-bit read packet request, from the host to the target.
2. A three-bit OK acknowledge response, from the target to the host.
3. A 33-bit RDATA data transfer phase, where data is transferred from the target to the host.

By default, there are single-cycle turnaround periods between the first and second of these phases, and after the third phase. See Line turnaround on page B4-107 for more information. However, there is no turnaround period between the second and third phases, because the line is driven by the target in both of these phases.

Figure B4-2 shows a successful read operation.

If the host requested a read access to the DP, the SW-DP sends the read data immediately after the acknowledgement response.

Read accesses to the AP are posted, which means that the result of the access is returned on the next transfer. This result can be another AP register read, or a DP register read of RDBUFF.

To make a series of AP reads, a debugger only has to insert one read of the RDBUFF register:

- On the first AP read access, the read data that is returned is unknown. The debugger must discard this result.
- The next AP read access, if successful, returns the result of the previous AP read.
- This response can be repeated for any number of AP reads. Issuing the last AP read packet request returns the last-but-one AP read result.
- The debugger can then read the DP RDBUFF register to obtain the last AP read result.

So that a debugger can recover from line errors, the next transaction after an AP register read can be any DP register read. If the next transaction is a DP register read other than a read of RDBUFF, then a following AP register read or read of RDBUFF returns the result of the first AP register read.

If the next transaction following an AP register read is an AP register write or a DP register write, the result of the first AP register read is lost because any following AP register read or read of RDBUFF returns an UNKNOWN value.

B4.2.3 WAIT response to read or write operation request

If the SW-DP is not able to process the request from the debugger immediately, it must issue a WAIT response. A WAIT response to a read or write packet request consists of two phases:
1. An eight-bit read or write packet request, from the host to the target.
2. A three-bit WAIT acknowledge response, from the target to the host.

By default, there are single-cycle turnaround periods between these two phases, and after the second phase. See Line turnaround on page B4-107 for more information.

A WAIT response to a read or write packet request is shown in Figure B4-3 on page B4-113.
If overrun detection is enabled, CTRL/STAT.STICKYORUN is set to 0b1 and a data phase is required on a WAIT response. For more information, see Sticky overrun behavior on page B4-115.

A WAIT response must not be issued in response to the following requests, which must always be processed immediately:

- Reads of the DPIDR register.
- Reads of the CTRL/STAT register.
- Writes to the ABORT register.

In response to any other request, the DP issues a WAIT response if it cannot process the request, which happens if:

- A previous AP or DP access is outstanding.
- The new request is an AP read request and the result of the previous AP read is not yet available.

Normally, when a debugger receives a WAIT response it retries the same operation, to process data as quickly as possible. However, if several retries have been attempted, with a wait that is long enough for a slow interconnection and memory system to respond, the debugger might write to ABORT.DAPABORT, if appropriate. This value signals to the active AP that it must terminate the transfer that it is attempting. An AP implementation might be unable to terminate a transfer on its SoC interface, but on receiving a DAP abort request the AP must free up the interface to the Debug Port.

Writing to the ABORT register after receiving a WAIT response enables the debugger to access other parts of the debug system.

**B4.2.4 FAULT response to read or write operation request**

An SW-DP must not issue a FAULT response in response to:

- Reads of the DPIDR register, which is a read-only register.
- Reads of the CTRL/STAT register, which is a read/write register.
- Writes to the ABORT register, which is a write-only register.

For any other access, the SW-DP issues a FAULT response if any sticky flag is set to 0b1 in the CTRL/STAT register.

A FAULT response to a read or write packet request consists of two phases:

1. An eight-bit read or write packet request, from the host to the target.
2. A three-bit FAULT acknowledge response, from the target to the host.

By default, there are single-cycle turnaround periods between these two phases, and after the second phase. See Line turnaround on page B4-107 for more information.

A FAULT response to a read or write packet request is shown in Figure B4-4 on page B4-114.
If overrun detection is enabled, CTRL/STAT.STICKYORUN is set to $0b1$ and a data phase is required on a FAULT response. For more information, see Sticky overrun behavior on page B4-115.

Use of the FAULT response enables the protocol to remain synchronized. A debugger might stream a block of data and then check the CTRL/STAT register at the end of the block.

In an SW-DP, the sticky error flags are cleared to $0b0$ by writing bits in the ABORT register.

**B4.2.5 Protocol error response**

If any of the following occurs, a protocol error occurs:

- The Parity bit does not match the parity of the packet request. For more information about the parity checks in the SWD protocol, see Parity on page B4-108.
- The Stop bit is not $0b0$.
- The Park bit is not $0b1$.
- DLCR.TURNROUND indicates an unsupported turnaround period.

**Note**

A mismatch between the Parity bit in the WDATA transfer phase and the parity of the data does not cause a protocol error response, because the SW-DP has already given its response to the header. For more information, see Sticky flags and DP error responses on page B1-41.

**Target response to protocol errors**

On detecting a protocol error, the target enters the protocol error state.

If overrun detection is enabled, CTRL/STAT.STICKYORUN is set to $0b1$ and the target must wait until the data phase of the transaction has completed before entering the protocol error state. Otherwise, it enters the protocol error state immediately.

When a protocol error is detected by the SW-DP, the SW-DP does not reply to the packet request and does not drive the line. This situation is illustrated in Figure B4-5 on page B4-115.

**Note**

If SWD protocol version 2 is implemented, the SW-DP does also not reply to a TARGETSEL register write packet request.
In the protocol error state, the target behaves as follows:

- If the target detects a valid read of the DP DPIIDR register, it is IMPLEMENTATION DEFINED whether the target leaves the protocol error state, and gives an OK response.
- If the target detects a valid packet header other than the read of the DP DPIIDR register, or the target detects an IMPLEMENTATION DEFINED number of additional protocol errors, it enters the lockout state.
  
  ARM recommends that the target enters the lockout state after one more protocol error is detected while in the protocol error state.

If the target cannot leave the protocol error state on a read of the DPIIDR register, the protocol error and lockout states are equivalent.

The target must leave the protocol error state on a line reset.

The target only leaves the lockout state on a line reset.

If the SW-DP implements SWD protocol version 2, it must enter the lockout state after a single protocol error immediately after a line reset. However, if the first packet request detected by the target following line reset is valid it can then revert to entering the lockout state after an IMPLEMENTATION DEFINED number of protocol errors.

Host response to protocol errors

If the host does not receive an expected response from the target, it must not drive the line for at least the length of any potential data phase and then attempt a line reset. For more information, see Connection and line reset sequence on page B4-122.

The host can attempt reads of the DP DPIIDR register before attempting a line reset, as the target might respond and leave the protocol error state, but ARM does not recommend this solution.

If the transfer that resulted in the original protocol error response was a write, it can be assumed that no write occurred. If the original transfer was a read, it is possible that the read was issued to an AP. Although this scenario is unlikely, the possibility must be considered because reads are pipelined.

 Stam overrun behavior

If an SW-DP receives a transaction request when the previous transaction has not completed, it returns a WAIT response. If overrun detection is enabled in the CTRL/STAT register, the CTRL/STAT.STICKYORUN flag is set to 0b1. Subsequent transactions generate FAULT responses, because a sticky flag is 0b1. If overrun detection is enabled, CTRL/STAT.STICKYORUN is also set if there is a FAULT response, protocol error, or line reset.

When overrun detection is enabled, WAIT and FAULT responses require a data phase:

- If the transaction is a read, the data in the data phase is UNKNOWN. The target does not drive the line, and the host must not check the parity bit.
- If the transaction is a write, the data phase is ignored.

Figure B4-6 on page B4-116 shows the WAIT or FAULT response to a read operation when overrun detection is enabled, and Figure B4-7 on page B4-116 shows the response to a write operation when overrun detection is enabled.
B4.2.7 SW-DP write buffering

The SW-DP can implement a write buffer, enabling it to accept write operations even when other transactions are outstanding. If a DP implements a write buffer, it issues an OK response to a write request if it can accept the write into its write buffer. This response means that an OK response to a write request, other than a write to the ABORT register in the DP, indicates only that the write has been accepted by the DP. It does not indicate that all previous transactions have completed.

The maximum number of outstanding transactions, and the types of transactions that might be outstanding, when a write is accepted, are IMPLEMENTATION DEFINED. However, the DP must be implemented so that all accesses occur in order. For example, if a DP only buffers writes to AP registers and it has any buffered writes, it must stall on a DP register write access to ensure that the writes are performed in order.

If a write is accepted into the write buffer but later abandoned, the CTRL/STAT.WDATAERR flag is set to 0b1. A buffered write is abandoned if:

- A sticky flag is set to 0b1 by a previous transaction.
- A DP read of the DPIDR or CTRL/STAT register is made. Because the DP must not stall reads of these registers, it must:
  - Perform the DPIDR or CTRL/STAT register access immediately.
  - Discard any buffered writes, because otherwise they would be performed out-of-order.
  - Set the WDATAERR flag to 0b1.
- A DP write of the ABORT register is made. The DP must not stall an ABORT register access.

The flag being set means that if software makes a series of AP write transactions, it might not be possible to determine which transaction failed from examining the ACK responses, but it might be possible to use other inquiries to find which write failed. For example, if when using the auto-address increment (AddrInc) feature of a Memory Access Port, software can read the TAR to find the address of the last successful write transaction.

The write buffer must be emptied before the following operations can be performed:

- Any AP read operation.
- Any DP operation other than a read of the DPIDR or CTRL/STAT register, or a write of the ABORT register.

If the write buffer is not empty, attempting these operations causes a WAIT response from the DP.
If pushed-verify or pushed-compare is enabled, AP write transactions are converted into AP reads. These transactions are then treated in the same way as other AP read operations. See Pushed-compare and pushed-verify operations on page B1-44 for details of these operations.

If a DP read of the DPIDR or CTRL/STAT register, or a DP write to the ABORT register, is required immediately after a sequence of AP writes, the software must first perform an access that the DP is able to stall, to ensure that the write buffer is emptied before the DP register access is performed. If this access is not done, WDATAERR might be set to 0b1, causing the buffered writes to be lost.

There is no requirement to insert an extra instruction to terminate the sequence of AP writes if the sequence of writes is followed by one of:

- An AP read operation.
- A write operation that can be stalled, such as a write to the SELECT register.

Often the requirement for an extra instruction can be avoided.

### B4.2.8 Summary of target responses

The following subsections show the target SW-DP responses for different transaction requests:

- Target SW-DP responses to DP transaction requests.
- Target SW-DP responses to AP transaction requests on page B4-119.

#### Target SW-DP responses to DP transaction requests

For DP transaction requests, the register that is accessed is determined by:

- In DPv1 or later, when A[3:2] is 0b01, the value of SELECT.DPBANKSEL.

The behavior of some read transaction requests depends on the register that is accessed, as Table B4-1 shows.

Table B4-1 shows the target SW-DP response to all possible debugger DP read operation requests.

Table B4-2 on page B4-118 shows the target SW-DP response to all possible debugger DP write operation requests, assuming the WDATA parity check is good.

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Sticky flag</td>
<td></td>
<td></td>
<td>ACK</td>
</tr>
<tr>
<td>x</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0b0</td>
<td>x</td>
<td>x</td>
<td>x</td>
<td>OK</td>
</tr>
<tr>
<td>0b1</td>
<td>0x0</td>
<td>x</td>
<td>x</td>
<td>OK</td>
</tr>
<tr>
<td>Not 0x0</td>
<td>No</td>
<td>Yes</td>
<td>OK</td>
<td>Respond with register value.</td>
</tr>
<tr>
<td>No</td>
<td>No</td>
<td>WAIT</td>
<td>No data phase, unless overrun detection is enabled.</td>
<td></td>
</tr>
<tr>
<td>Yes</td>
<td>x</td>
<td>FAULT</td>
<td>No data phase, unless overrun detection is enabled.</td>
<td></td>
</tr>
</tbody>
</table>
Table B4-1 Target response summary for DP read transaction requests (continued)

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>0b10</td>
<td>x</td>
<td>No</td>
<td>Yes</td>
<td>OK</td>
<td></td>
<td>OK</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Respond by resending the last read value that is sent to the host. This value is the result of one of:</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>• The most recent AP read</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>• The most recent DP RDBUFF read.</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>No</td>
<td>No</td>
<td>WAIT</td>
<td></td>
<td>No data phase, unless overrun detection is enabled.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Yes</td>
<td>x</td>
<td>FAULT</td>
<td></td>
<td>No data phase, unless overrun detection is enabled.</td>
</tr>
<tr>
<td>0b11</td>
<td>x</td>
<td>No</td>
<td>Yes</td>
<td>OK</td>
<td></td>
<td>OK</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Respond with the value from the previous AP read, and set CTRL/STAT.READOK bit to 0b1.</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>No</td>
<td>No</td>
<td>WAIT</td>
<td></td>
<td>No data phase, unless overrun detection is enabled. Set CTRL/STAT.READOK bit to 0b0.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Yes</td>
<td>x</td>
<td>FAULT</td>
<td></td>
<td>No data phase, unless overrun detection is enabled. Set CTRL/STAT.READOK bit to 0b0.</td>
</tr>
</tbody>
</table>

a. The SW-DP must always give an OK response to a read of the DPIDR or CTRL/STAT register.
b. See Sticky overrun behavior on page B4-115 for details about the data phase when overrun detection is enabled.

Table B4-2 Target response summary for DP write transaction requests

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>0b00</td>
<td>x</td>
<td>x</td>
<td>x</td>
<td>OK</td>
<td></td>
<td>OK</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Write WDATA value to ABORT register.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0b01 or 0b10</td>
<td>x</td>
<td>No</td>
<td>Yes^4</td>
<td>OK</td>
<td></td>
<td>OK</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Write WDATA value to the selected DP register.</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>No</td>
<td></td>
<td>WAIT</td>
<td></td>
<td>No data phase, unless overrun detection is enabled.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Yes</td>
<td></td>
<td>FAULT</td>
<td></td>
<td>No data phase, unless overrun detection is enabled.</td>
</tr>
</tbody>
</table>

^4 A sticky flag must be set to 0b1 before the AP is ready, and a write to the AP is allowed.
Fault conditions that are not shown in these tables are described in Fault conditions not included in the target response tables on page B4-120.

Target SW-DP responses to AP transaction requests

For AP transaction requests, the register that is accessed is determined by the value of A[3:2] combined with the values of SELECT.{APSEL,APBANKSEL}. For more information, see Using the AP to access debug resources on page A1-31.

Table B4-3 summarizes the target SW-DP response to all possible debugger AP read operation requests.

Table B4-4 on page B4-120 summarizes the target SW-DP response to all possible debugger AP write operation requests, assuming the WDATA parity check is good.

Fault conditions that are not shown in these tables are described in Fault conditions not included in the target response tables on page B4-120.

Target SW-DP responses to AP transaction requests

For AP transaction requests, the register that is accessed is determined by the value of A[3:2] combined with the values of SELECT.{APSEL,APBANKSEL}. For more information, see Using the AP to access debug resources on page A1-31.

Table B4-3 summarizes the target SW-DP response to all possible debugger AP read operation requests.

Table B4-4 on page B4-120 summarizes the target SW-DP response to all possible debugger AP write operation requests, assuming the WDATA parity check is good.

Fault conditions that are not shown in these tables are described in Fault conditions not included in the target response tables on page B4-120.
Fault conditions that are not shown in these tables are described in *Fault conditions not included in the target response tables*.

### Fault conditions not included in the target response tables

There are two fault conditions that are not included in possible operation requests listed in Table B4-1 on page B4-117 to Table B4-4:

**Protocol error**

If there is a protocol error, the target does not respond to the request at all, which means that when the host expects an ACK response, it finds that the line is not driven. See *Protocol error response* on page B4-114.

**WDATA fails parity check (write operations only)**

The ACK response of the DP is sent before the parity check is performed, and is shown in Table B4-2 on page B4-118. When the parity check is performed and fails, the CTRL/STAT.WDATAERR flag is set to 0b1.

### Summary of host responses

Every access by a debugger to an SW-DP starts with an operation request. *Summary of target responses on page B4-117* listed all possible requests from a debugger, and summarized how the SW-DP responds to each request.

Whenever a debugger issues an operation request to an SW-DP, it expects to receive a 3-bit acknowledgement, as listed in the ACK columns of Table B4-1 on page B4-117 to Table B4-4. Table B4-5 on page B4-121 summarizes how the debugger must respond to this acknowledgement, for all possible cases.

#### Note

For SWD protocol version 2, this table does not apply to writes to TARGETSEL. See *Connection and line reset sequence*.  

---

**Table B4-4 Target response summary for AP write transaction requests**

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>0bxx</td>
<td>No</td>
<td>Yes&lt;sup&gt;a&lt;/sup&gt;</td>
<td>OK</td>
<td>Normally&lt;sup&gt;b&lt;/sup&gt;, write WDATA value to the indicated AP register.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>No</td>
<td>WAIT</td>
<td>No data phase, unless overrun detection is enabled&lt;sup&gt;c&lt;/sup&gt;.</td>
</tr>
<tr>
<td></td>
<td>Yes&lt;sup&gt;x&lt;/sup&gt;</td>
<td>FAULT</td>
<td></td>
<td>No data phase, unless overrun detection is enabled&lt;sup&gt;c&lt;/sup&gt;.</td>
</tr>
</tbody>
</table>

<sup>a</sup> Writes might be accepted when other transactions are still outstanding. These writes might be abandoned later. See *SW-DP write buffering on page B4-116* for more information.

<sup>b</sup> If pushed-verify or pushed-compare is enabled, the write is converted to a read of the addressed AP register, and the value that is returned by this read is compared with the supplied WDATA value, see *Pushed-compare and pushed-verify operations on page B1-44* for more information.

<sup>c</sup> See *Sticky overrun behavior on page B4-115* for details of data phase when overrun detection is enabled.
### Table B4-5 Summary of host (debugger) responses to the SW-DP acknowledge

<table>
<thead>
<tr>
<th>Operation requested</th>
<th>ACK received</th>
<th>Host response</th>
<th>Data phase</th>
<th>Additional action</th>
</tr>
</thead>
<tbody>
<tr>
<td>R</td>
<td>OK</td>
<td>Capture RDATA from target and check for valid parity(^a) and protocol.</td>
<td>If a parity or protocol fault occurs and it is not possible to flag the data as invalid, the host might have to repeat the original read request or use the RESEND register(^b).</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Invalid ACK</td>
<td>Back off because of possible data phase.</td>
<td>The host can check CTRL/STAT register to see if the response sent was OK.</td>
<td></td>
</tr>
<tr>
<td>W</td>
<td>OK</td>
<td>Send WDATA.</td>
<td>Validity of this transfer is confirmed on next access.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Invalid ACK</td>
<td>Back off to ensure that target does not capture next header as WDATA.</td>
<td>Repeat the write access. A FAULT response is possible if the first response was sent as OK but not recognized as valid by the debugger. The subsequent write is not affected by the first, misread, response.</td>
<td></td>
</tr>
<tr>
<td>x</td>
<td>WAIT</td>
<td>No data phase, unless overrun detection is enabled(^c).</td>
<td>Normally, repeat the original operation request. See WAIT response to read or write operation request on page B4-112 for more information.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>FAULT</td>
<td>No data phase, unless overrun detection is enabled(^c).</td>
<td>Can send new headers, but only an access to DP register addresses 0b0X gives a valid response.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>No ACK</td>
<td>Back off because of possible data phase.</td>
<td>Can attempt IDCODE register read. Otherwise reset connection and retrain. See Protocol error response on page B4-114.</td>
<td></td>
</tr>
</tbody>
</table>

---

\(^a\) See Parity on page B4-108 for details of the parity checking.

\(^b\) The host debugger might support corrupted reads, or it might have to retry the transfer.

\(^c\) If overrun detection is enabled, a data phase is required. See Sticky overrun behavior on page B4-115 for a description of the behavior on read and write operations.
B4.3 SWD interface

The SWD protocol uses a synchronous serial interface, which comprises a single bidirectional data signal, and a clock signal.

This section gives an overview of the physical SWD interface.

B4.3.1 Line interface

The SWD interface uses a single bidirectional data pin, SWDIO. The same signal is used for both host and target sourced signals.

The SWD interface is synchronous, and requires a clock pin, SWCLK.

When the target samples SWDIO, sampling is performed on the rising edge of SWCLK. When the target drives SWDIO, or stops driving it, signal changes are performed on the rising edge of SWCLK.

The clock can be sourced from the target and exported, or provided by the host. This clock is then used by the host as a reference for generation and sampling of data so that the target is not required to perform any over-sampling.

Both the target and host can drive the bus HIGH and LOW or tristate it. The ports must be able to tolerate short periods of contention that might occur because of a loss of synchronization.

The clock can be asynchronous to any system clock, including the debug logic clock. The SWD interface clock can be stopped when the debug port is idle, see About the SWD protocol on page B4-106.

B4.3.2 Line pull-up

To make sure that the line is in a known state when neither host nor target is driving the line, a 100KΩ pull-up is required at the target. This pull-up can only be relied on to maintain the state of the wire. If the wire is driven LOW and released, the pull-up resistor eventually returns the line to the HIGH state, but this process takes many clock periods.

The pull-up is intended to prevent false detection of signals when no host is connected, and must be of a suitably high value to reduce current consumption from the target when the host actively pulls down the line.

--- Note ---

A small current drains from the target whenever the line is driven LOW. If the interface is left connected for extended periods when the target has to use a low-power mode, the line must be held HIGH, or reset, by the host until the interface is activated.

B4.3.3 Connection and line reset sequence

A debugger must use a line reset sequence to ensure that hot-plugging the serial connection does not result in unintentional transfers. The line reset sequence ensures that the SW-DP is synchronized correctly to the header that signals a connection.

The SWD interface does not include a reset signal. A line reset is achieved by holding the data signal HIGH for at least 50 clock cycles, followed by at least two idle cycles. Figure B4-8 on page B4-123 shows the interface timing for a line reset followed by a DP DPIDR register read.
A line reset is required when first connecting to the target. A line reset might be required following a protocol error. See Protocol error response on page B4-114.

A line reset resets DLCR.

--- Note ---

Other SW-DP registers are reset only by a powerup reset.

---

When waiting for a packet header, if the target detects a sequence of 50 clock cycles with the data signal held HIGH, followed by at least two idle cycles, it must enter the reset state. It is IMPLEMENTATION DEFINED whether a sequence of 50 clock cycles with the data signal held HIGH that is detected at any other time causes the interface to enter the reset state.

The only valid transactions in reset state are:

- A read of the DPIDR register. This transaction takes the connection out of reset state.
- One of the switching sequences defined by Switching between SWD and JTAG on page B5-128, if implemented.
- A write to the TARGETSEL register, if SWD protocol version 2 is implemented. If this transaction selects the target, the interface remains in reset state.

--- Note ---

Only writes to TARGETSEL immediately after entry to the reset state can select or deselect the target. See Target selection protocol, SWD protocol version 2.

---

Any of these sequences can be aborted by a second line reset. The behavior of the target is UNPREDICTABLE if any other transaction is made in reset state.

If the host does not see an expected response when reading the DPIDR register, it must retry the reset sequence, because the target might have been in a state where, for example, it treated the initial line reset as a data phase of a transaction and therefore did not detect it as a valid line reset. If so, the target detects the line reset as a protocol error and requires a second line reset to respond correctly.

If overrun detection is enabled, then the line reset sets CTRL/STAT.STICKYORUN to 0b1.

---

**B4.3.4 Target selection protocol, SWD protocol version 2**

1. Perform a line reset. See Figure B4-9 on page B4-124.
2. Write to DP register 0xC, TARGETSEL, where the data indicates the selected target. The target response must be ignored. See Figure B4-9 on page B4-124.
3. Read from the DP register 0x0, DPIDR, to verify that the target has been successfully selected.
A write to the TARGETSEL register must always be followed by a read of the DPIDR register or a line reset. If the response to the DPIDR read is incorrect, or there is no response, the host must start the sequence again.

The target is selected on receiving a line reset sequence.

After receiving a line reset sequence, if the target receives a write request to TARGETSEL that does not select the same target, the target is deselected.

When deselected, the target ignores all accesses and must not drive the line. To select or deselect the target, a write to TARGETSEL must immediately follow a line reset sequence. Writes to TARGETSEL at any other time are UNPREDICTABLE.

If the target encounters a protocol error, it becomes deselected. Specifically, it does not respond to a read of the DPIDR register.

For more information, including the required behavior of the target during the response phase of the write to the TARGETSEL register, see Sticky flags and DP error responses on page B1-41.

A parity error in the data phase of a write to the TARGETSEL register does not set the CTRL/STAT.WDATAERR bit to 0b1. A parity error in the data phase of a write to the TARGETSEL register is treated as a protocol error.

Accesses to the TARGETSEL register are not affected by the state of the CTRL/STAT.{WDATAERR, STICKYERR, STICKYCMP, STICKYORUN} bits.

Implementations of SWD protocol version 2 must also support dormant operation. See Dormant operation on page B5-131.
Chapter B5
The Serial Wire/JTAG Debug Port (SWJ-DP)

This chapter describes multiple protocol interoperability as implemented in the Serial Wire/JTAG Debug Port (SWJ-DP) CoreSight component. It contains the following sections:
- About the SWJ-DP on page B5-126.
- Switching between SWD and JTAG on page B5-128.
- Dormant operation on page B5-131.
- Restrictions on switching between operating modes on page B5-138.
B5.1 About the SWJ-DP

The SWJ-DP interface provides a mechanism to select between SWD and JTAG Data Link protocols, which enables the DP to provide JTAG and SWD connections while making efficient use of package pins through sharing, or overlaying, pins.

Implementing an SWJ-DP enables a SoC to connect to legacy JTAG equipment without the need to change to the DP design. If an SWD tool is available, the JTAG interface is not needed, and only two pins are required, instead of the four or five used for JTAG, which frees up some pins for alternative use. See also Limitations when reusing pins.

B5.1.1 SWJ-DP structure

The SWJ-DP comprises both an SW-DP and a JTAG-DP. It selects either the SW-DP or the JTAG-DP as the interface to the DAP, and switches between the SWD and JTAG Data Link protocols. Switching is achieved by routing the shared pins as shown in Table B5-1.

The mechanism for switching between SWD and JTAG is described in Switching from JTAG to SWD operation on page B5-129.

Note

- While the DP is in SWD mode, the JTAG pins TDI, TDO, and nTRST are expected to be reused.
- An SWJ-DP can be implemented in a package where the JTAG pins TDI, TDO, and nTRST are not connected because an SWJ-DP does not need these JTAG pins to switch the DP to SWD mode.

The following rules apply to SWJ-DP implementations:

- There is no requirement to implement separate SW-DP and JTAG-DP blocks within the SWJ-DP.
- The number, type and location of APs accessed by the SWJ-DP must not depend on whether the SW-DP or the JTAG-DP is selected, and each DP type must access the same debug resources. There is no requirement to implement these APs as shared APs.
  
  For this reason, tools must not rely on the state of a DP or any AP it accesses to persist when the other DP is selected. After switching DPs, the debugger must re-initialize the DAP, which includes setting the CTRL/STAT.(CDBGWRUPREQ, CSYSPWRUPREQ) bits correctly.
- The JTAG-DP and SW-DP programmers’ models do not have to implement the same DP architecture version. See Chapter B1 About the DP.
- If the JTAG protocol is never used, a pull-down on TDI at the target is required.

B5.1.2 Limitations when reusing pins

If the JTAG pins on the SWJ-DP interface are not used, they can be reused. There is, however, a trade-off between the number of pins that are used and compatibility with existing hardware and test equipment.

In the following situations the use of a JTAG debug interface must be maintained:

- The DP is included in an existing scan chain, which is often true for on-chip TAPs used for testing or other purposes.
• The device must be enabled to be cascaded with legacy devices which use JTAG for debug, although this requirement can also be supported using a JTAG Access Port (JTAG-AP).

• There is a requirement to use existing debug hardware with the corresponding test TAPs, for example, in Automatic Test Equipment (ATE).

The following must be observed:

• When reusing pins, there must be no conflict with their use in JTAG operation.

• To support use of SWJ-DP in a scan chain with other JTAG devices, the default behavior after a DP reset must be to transition any reused pins from their alternative function to their JTAG function, if the direction of the alternative function is compatible with being driven by a JTAG debug device. The transition of the JTAG TAP to the Shift-DR or Shift-IR state can be used for this transition.

• The alternate function of reused pins cannot be used while the SoC is being used in JTAG operation.

• The switching scheme must enable a JTAG debugger to connect by sending a specific sequence, provided there is no conflict on the TDI and TDO pins.

• The connection sequence that is used for SWD must be safe when applied to the JTAG interface, even when hot-plugged, to enable the debugger to continually retry its access sequence.

• A sequence with TMS HIGH must ensure that all parts of the SWJ-DP are in a known reset state.

• The pattern that selects SWD must have no effect on JTAG devices.

• An SWJ-DP implementation must be compatible with a free-running TCK, or a gated clock, that is supplied by the external tools.
B5.2 Switching between SWD and JTAG

SWJ-DP enables either an SWD or JTAG protocol to be used on the debug port. This section describes in detail how the switching mechanism is implemented, and how to switch between the two interfaces.

--- Note ---

On devices where the dormant state of operation is implemented, ARM deprecates the mechanism that is described in The Switching Mechanism, and recommends using a transition through dormant state instead. For more information about dormant state, see Dormant operation on page B5-131.

B5.2.1 The Switching Mechanism

The implementation uses a watcher circuit that detects a specific 16-bit select sequence on SWDIOTMS:

- A 16-bit sequence to switch from JTAG to SWD operation.
- A 16-bit sequence to switch from SWD to JTAG.

--- Note ---

ARM deprecates use of these sequences on devices where the dormant state of operation is implemented, and recommends using a transition through dormant state instead. For more information, see Dormant operation on page B5-131.

SWJ-DP defaults to JTAG operation on powerup reset and therefore the JTAG protocol can be used from reset without sending a select sequence.

Switching from one protocol to the other can only occur when the selected interface is in its reset state. The JTAG TAP state machine must be in its Test-Logic-Reset (TLR) state and the SWD interface must be in line-reset. The powerup reset state for a JTAG TAP state machine is the Test-Logic-Reset state.

Having detected a switching sequence, SWJ-DP does not detect more sequences until after a reset condition. If JTAG is selected, the JTAG TAP state machine being in the Test-Logic-Reset state is the reset condition. If SWD is selected, a line reset is the reset condition.

Figure B5-1 on page B5-129 is a simplified state diagram that shows how SWJ-DP transitions between selected, detecting, and selection states.
### B5.2 Switching between SWD and JTAG

#### B5.2.1 Switching from JTAG to SWD operation

To switch SWJ-DP from JTAG to SWD operation:

1. Send at least 50 SWCLKTCK cycles with SWDIOTMS HIGH. This sequence ensures that the current interface is in its reset state. The JTAG interface only detects the 16-bit JTAG-to-SWD sequence starting from the Test-Logic-Reset state.

2. Send the 16-bit JTAG-to-SWD select sequence on SWDIOTMS.

3. Send at least 50 SWCLKTCK cycles with SWDIOTMS HIGH. This sequence ensures that if SWJ-DP was already in SWD operation before sending the select sequence, the SWD interface enters line reset state.

The recommended sequences end with a reset sequence for the selected state, to ensure that the target is in the relevant reset state.

---

#### B5.2.2 Switching from JTAG to SWD operation

To switch SWJ-DP from JTAG to SWD operation:

1. Send at least 50 SWCLKTCK cycles with SWDIOTMS HIGH. This sequence ensures that the current interface is in its reset state. The JTAG interface only detects the 16-bit JTAG-to-SWD sequence starting from the Test-Logic-Reset state.

2. Send the 16-bit JTAG-to-SWD select sequence on SWDIOTMS.

3. Send at least 50 SWCLKTCK cycles with SWDIOTMS HIGH. This sequence ensures that if SWJ-DP was already in SWD operation before sending the select sequence, the SWD interface enters line reset state.

The 16-bit JTAG-to-SWD select sequence is 0b0111 1001 1110 0111, most-significant-bit (MSB) first. This sequence can be represented as one of the following:

- 0x79E7, transmitted MSB first.
- 0xE79E, transmitted least-significant-bit (LSB) first.

---

Figure B5-2 on page B5-130 shows the interface timing. The sequence that is shown in the figure has been chosen to ensure that the SWJ-DP switches to SWD, independent of whether it was previously expecting JTAG or SWD. As long as the 50 cycles with SWDIOTMS HIGH sequence are sent first, the JTAG-to-SWD select sequence does not affect SW-DP or the SWD and JTAG protocols that are used in the SWJ-DP, or any other TAP Controllers that might be connected to SWDIOTMS.

On selecting SWD operation, the SWD interface returns to its reset state. See Connection and line reset sequence on page B4-122.
B5.2.3 Switching from SWD to JTAG operation

To switch SWJ-DP from SWD to JTAG operation:

1. Send at least 50 \( \text{SWCLKTCK} \) cycles with \( \text{SWDIOTMS} \) HIGH. This sequence ensures that the current interface is in its reset state. The SWD interface only detects the 16-bit SWD-to-JTAG sequence when it is in the reset state.

2. Send the 16-bit SWD-to-JTAG select sequence on \( \text{SWDIOTMS} \).

3. Send at least five \( \text{SWCLKTCK} \) cycles with \( \text{SWDIOTMS} \) HIGH. This sequence ensures that if SWJ-DP was already in JTAG operation before sending the select sequence, the JTAG TAP enters the Test-Logic-Reset state.

The 16-bit SWD-to-JTAG select sequence is 0b0011 1100 1110 0111, MSB first. This sequence can be represented as either of the following:
- 0x3CE7, transmitted MSB first
- 0xE73C, transmitted LSB first.

Figure B5-3 shows the SWD-to-JTAG sequence timing. The sequence that is shown in the figure has been chosen to ensure that the SWJ-DP switches to JTAG, independent of whether it was previously expecting JTAG or SWD. If the \( \text{SWDIOTMS} \) HIGH sequence is sent first, the SWD-to-JTAG select sequence does not affect SW-DP or the SWD and JTAG protocols that are used in the SWJ-DP, or any other TAP Controllers that might be connected to \( \text{SWDIOTMS} \).

Figure B5-3 shows that the SWD-to-JTAG sequence begins with two \( \text{SWDIOTMS} \) LOW cycles after the line reset. No additional \( \text{SWDIOTMS} \) LOW cycles are allowed.
B5.3 Dormant operation

An alternative to the selection mechanism for switching between JTAG and SWD operation that is described in Switching between SWD and JTAG on page B5-128 is the dormant state of operation.

To switch between JTAG and SWD operation, a debugger must first place the target into dormant state, and then transition to the required operating state.

Using dormant state allows the target to be placed into a quiescent mode, allowing devices to inter-operate with other devices implementing other protocols. Those other protocols must also implement a quiescent state, with a mechanism for entering and leaving that state that is compatible, but not necessarily compliant, with the SWJ-DP and SW-DP protocols.

Dormant operation is required by SWJ-DP and SW-DP implementations that implement SWD protocol version 2. SWD protocol version 2 is described in Chapter B4 The Serial Wire Debug Port (SW-DP). Otherwise, support for dormant state is IMPLEMENTATION DEFINED. In the dormant state, the target must ignore any stimulus, with any timing, other than a defined Selection Alert sequence.

The Selection Alert sequence must be followed by a protocol-specific Activation code.

Selection of dormant state is possible when either JTAG or SWD operation is selected. Figure B5-4 extends the state diagram of Figure B5-1 on page B5-129 to include selection of dormant state, for an SWJ-DP implementation.

![Figure B5-4 SWJ-DP selection of JTAG, SWD, and dormant states](image.png)

**Note**

Following the DS-to-JTAG activation code, the JTAG TAP is in either the Test-Logic-Reset state or Run-Test/Idle state, and therefore this state machine is in either the JTAG-Sel TLR state or the JTAG-Sel selected state. Normally, the TAP state that the state machine returns to is the TAP state it left from, but it is also possible to reset the JTAG TAP state machine when JTAG is not the selected protocol. To ensure that the TAP is in the Run-Test/Idle state, ARM recommends that the DS-to-JTAG sequence is followed by a single clock with SWDIOTMS LOW.

The DS-to-SWD sequence is shown terminating in the SW-Sel reset state. The recommended sequence ends with a line reset to ensure that the target is in the reset state.
B5.3 Dormant operation

B5.3.1 Using the dormant state outside of SWJ-DP

An SWD device that does not implement JTAG can nevertheless implement dormant state, and inter-operate with SWJ-DP and other JTAG devices that also implement dormant state. In this case:

- The operating mode selection state machine is simplified.
- The initial state, entered on a powerup reset, is the dormant state.

Figure B5-5 shows the state diagram for an SW-DP that implements protocol version 2, meaning it supports dormant operation.

The dormant state enables multi-drop SWJ-DP, SW-DP, and JTAG TAPs to share a physical connection to a host, as shown in Figure B5-6. These different devices can be in different physical packages, or on different dies in a single package, or on a single die.

Figure B5-6 Multiple JTAG, SW, SWJ (multi-drop), and other protocol devices on shared connection
B5 The Serial Wire/JTAG Debug Port (SWJ-DP)
B5.3 Dormant operation

### B5.3.2 Switching from JTAG to dormant state

To switch from JTAG to dormant state, a debugger must:

1. Send at least five **SWCLKTCK** cycles with **SWDIOTMS** HIGH. This sequence places the JTAG TAP state machine into the Test-Logic-Reset state, and selects the IDCODE instruction.

2. Send the recommended 31-bit JTAG-to-DS select sequence on **SWDIOTMS**.

The recommended 31-bit JTAG-to-DS select sequence is 0b010111011101110111011100110, MSB first. This sequence can be represented as either:

- 0x2EEEEE6 transmitted MSB first, that is, starting from bit 30.
- 0x33BBBBBA transmitted LSB first.

![Figure B5-7 Recommended JTAG-to-DS sequence timing](image)

#### Requirements for implementations

The JTAG-to-DS sequence is the shortest sequence that switches from JTAG-to-DS. For compatibility with other standards, all JTAG devices that implement dormant state must recognize other sequences as valid JTAG-to-DS select sequences.

The full sequence is defined around the concept of a zero-bit-DR-scan (ZBS or ZBS scan) which is in turn defined by transitions of the JTAG TAP state machine. A ZBS is defined as any JTAG TAP state machine sequence that starts at Capture-DR and ends in Update-DR without passing through Shift-DR.

Examples of a ZBS are:

- Capture-DR → Exit1-DR → Update-DR
- Capture-DR → Exit1-DR → Pause-DR → … → Pause-DR → Exit2-DR → Update-DR

The sequence also uses the ZBS count, which is defined as follows:

- If the TAP state machine enters either the Select-IR-Scan or Test-Logic-Reset state, the ZBS count is unlocked and reset to zero, which includes asynchronously entering Test-Logic-Reset following assertion of nTRST. At reset, the ZBS count is unlocked and reset to zero.
- On entering Update-DR at the end of a ZBS scan, if the ZBS count is unlocked and less than seven, it is incremented by one.
- The counter does not increment past seven. On entering Update-DR at the end of a ZBS scan, if the ZBS count is unlocked and equal to seven, it is not incremented. The count does not wrap to zero.
- The ZBS count is locked if the TAP state machine enters the Shift-DR state and the ZBS count is not zero.

The JTAG-to-DS sequence is defined as any sequence of TAP state machine transitions that terminates in the Run-Test/Idle state with a locked ZBS count of six. On entering Run-Test/Idle, the target is placed into dormant state (DS).

The behavior of the target on entering Run-Test/Idle with other locked ZBS counts is IMPLEMENTATION DEFINED.
Although the recommended JTAG-to-DS sequence starts by placing the JTAG TAP state machine in the Test-Logic-Reset state, this transition is not required for recognizing the JTAG-to-DS sequence. Tools must, however, ensure that the Instruction Register (IR) is loaded with either the BYPASS or IDCODE instruction before placing the target into the dormant state. If the IR is not loaded with either of these instructions when the target is put into dormant state, the behavior is unpredictable.

The pseudocode function `EnterDormantState` describes the function of the JTAG-to-DS sequence detector. It is notionally called on every TAP state machine transition. The function takes the state being entered as an argument, and returns a Boolean that indicates whether dormant state must be entered.

For details of the pseudocode language, see Appendix E3 Pseudocode Definition.

```c
enumeration TAPState {
    TestLogicReset, RunTestIdle,
    SelectDRScan, CaptureDR, ShiftDR, Exit1DR, PauseDR, Exit2DR, UpdateDR,
    SelectIRScan, CaptureIR, ShiftIR, Exit1IR, PauseIR, Exit2IR, UpdateIR};

    boolean shiftDRflag = FALSE;
    integer ZBScount = 0;
    boolean ZBSlocked = FALSE;

    // EnterDormantState()
    // ===============

    boolean EnterDormantState(TAPState state)
    case state of
        when CaptureDR
            shiftDRflag = FALSE;
        when ShiftDR
            shiftDRflag = TRUE;
        if ZBScount != 0 then ZBSlocked = TRUE;
        when UpdateDR
            if !ZBSlocked && !shiftDRflag && ZBScount < 7 then
                ZBScount = ZBScount + 1;
            when SelectIRScan, TestLogicReset
                ZBScount = 0; ZBSlocked = FALSE;
        return state == RunTestIdle && ZBSlocked && ZBScount == 6;
```

**Note**
If the JTAG-to-DS sequence is terminated by entering the Test-Logic-Reset state, an SWJ-DP can immediately detect a JTAG-to-SWD sequence.

### B5.3.3 Switching from SWD to dormant state

To switch from SWD to dormant state:

1. Send at least 50 `SWCLKTCK` cycles with `SWDIOTMS` HIGH. This sequence ensures that the SWD interface is in the reset state. The target only detects the SWD-to-DS sequence when it is in the reset state.

2. Send the 16-bit SWD-to-DS select sequence on `SWDIOTMS`.

The 16-bit SWD-to-DS select sequence is 0b0011_1101_1100_0111, MSB first. This sequence can be represented as either:

- 0x3DC7 transmitted MSB first.
- 0xE3BC transmitted LSB first.
B5.3.4 Leaving dormant state

To ensure that the probability for any protocol being used to accidentally signal the DP to leave the dormant state is low, the sequence for leaving the dormant state is considerably longer than the sequence for entering it.

To signal the DP to leave the dormant state:

1. Send at least eight \texttt{SWCLKTCK} cycles with \texttt{SWDIOTMS} HIGH. This sequence ensures that the target is not in the middle of detecting a Selection Alert sequence. The target is permitted to detect the Selection Alert sequence even if this 8-cycle sequence is not present.

2. Send the 128-bit Selection Alert sequence on \texttt{SWDIOTMS}.

3. Send four \texttt{SWCLKTCK} cycles with \texttt{SWDIOTMS} LOW. The target must ignore the value on \texttt{SWDIOTMS} during these cycles.

4. Send the required activation code sequence on \texttt{SWDIOTMS}
   - If selecting JTAG, the target is in either the Run/Test Idle or Test-Logic-Reset states, see the Note that follows Figure B5-4 on page B5-131 for more information. ARM recommends that the debugger sends one \texttt{SWCLKTCK} cycle with \texttt{SWDIOTMS} LOW, to ensure that the TAP state machine is in the Run-Test/Idle state. Alternatively, send at least five \texttt{SWCLKTCK} cycles with \texttt{SWDIOTMS} HIGH to ensure that the TAP state machine is in the Test-Logic/Reset state.
   - If selecting SWD, the target is in the protocol error state. The debugger must send at least 50 \texttt{SWCLKTCK} cycles with \texttt{SWDIOTMS} HIGH. This sequence ensures that the SWD interface is in the line reset state.

\begin{center}
\textbf{Note}
\end{center}

The Activation code selects a protocol, not a target. In a multidrop SWD system with multiple SW-DPs, a target must then be selected. For more information, see Target selection protocol, SWD protocol version 2 on page B4-123.

The Selection Alert sequence, in binary, is

\begin{verbatim}
0100_1001_1100_1111_1001_0000_0100_0110_1010_1001_1011_0100_1010_0001_0110_0001_
1001_0111_1111_0101_1011_1011_1100_0111_0100_0101_0111_0000_0011_1101_1001_1000
\end{verbatim}

This sequence is sent MSB first. This sequence can be represented as either:

- 0x49CF9846 A984A161 97F58BC7 45703D98 transmitted MSB first.
- 0x198C0EA2 E3D0AFF9 86852D95 6209F392 transmitted LSB first.

\begin{center}
Figure B5-8 SWD-to-DS sequence timing
\end{center}

Figure B5-8 shows that the SWD-to-DS sequence begins with two SWDIOTMS LOW cycles after the line reset. No additional SWDIOTMS LOW cycles are allowed.
The Selection Alert sequence can be generated by implementing a Linear Feedback Shift Register (LFSR) implementing feedback on bits 6, 5, 3 and 0, starting in the state 0b1001001 and shifting out one bit from bit 0 each cycle. The sequence starts with a zero start bit and continues with the output of the LFSR.

The value of the activation code depends on whether SWD or JTAG operation is to be requested. Table B5-2 defines the activation codes a debugger must use for JTAG devices, SW-DP devices, and SWJ-DP devices. These sequences are sent MSB first.

<table>
<thead>
<tr>
<th>Activation code</th>
<th>Value, MSB first</th>
<th>Other JTAG</th>
<th>ADIv5 Debug Ports</th>
<th>Protocol selected</th>
</tr>
</thead>
<tbody>
<tr>
<td>JTAG-Serial</td>
<td>0b0000_0000_0000</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>ARM CoreSight SW-DP</td>
<td>0b0101_1000</td>
<td>No</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td>ARM CoreSight JTAG-DP</td>
<td>0b0101_0000</td>
<td>No</td>
<td>Yes</td>
<td>No</td>
</tr>
</tbody>
</table>

**JTAG online activation codes**

For compatibility with other standards, all JTAG devices that implement dormant state using the ADIv5 defined selection alert sequence, must recognize other sequences as valid JTAG-Serial activation codes.

Figure B5-11 on page B5-137 shows, as a state diagram, the sequence that a JTAG device must recognize.
Each of the bit-strings that are shown in Figure B5-11 are received MSB first. The transition out of state G2 requires a reset of the JTAG TAP, but otherwise returns to dormant state. For more information on this sequence, contact ARM.

Note

ADIV5 does not define any other activation codes, but also does not prohibit an implementation from recognizing other activation codes for compatibility with other standards. Implementations can also use alternative selection alert mechanisms. Debuggers can generate multiple selection alert sequences to alert multiple devices, and then use the common activation codes to select which devices to activate.
B5.4 Restrictions on switching between operating modes

A debugger must not mix JTAG-DP and SW-DP reads and writes of DAP registers in a single debug session. A single debug session is defined as from when a debugger connection is made with the system in a reset state through to the debugger connection being broken. At the start of a debug session, the state of the target is UNKNOWN.

Attempting to mix JTAG-DP and SW-DP reads and writes of DAP registers while any component of the DAP is active can have unpredictable results.

A powerup reset cycle might be required to reset the DAP before a change in active Data Link protocol. However, this cycle is not required when switching between the active protocol and dormant state.
Part C
The Access Port
Chapter C1
About the AP

A DAP can include multiple APs.

This chapter gives an overview of APs, and describes the features that must be implemented by every AP. It contains the following sections:

• AP requirements on page C1-142.
• Selecting and accessing an AP on page C1-143.
• AP Programmers’ Model on page C1-144.

The following chapters provide two AP definitions:

• Chapter C2 The Memory Access Port (MEM-AP).
• Chapter C3 The JTAG Access Port (JTAG-AP).

Designers can use the ADI architecture specification to implement other APs.


### C1.1 AP requirements

A DAP can implement multiple APs, and use a mixture of AP types.

--- **Note** ---

This Architecture Specification permits a DAP to include AP types that are not defined in the specification, even if such an AP is the only AP in the DAP. A debugger must be able to detect any AP, and must ignore any AP that it does not recognize.

All APs must observe the following requirements:

- Every AP must implement an Identification Register as described in *AP Programmers’ Model on page C1-144*. This identification model is required for implementations of the MEM-AP and JTAG-AP implementations that are defined by ARM, by any future ARM AP implementations, and by any APs that might be implemented by any third party.

- Any AP must support accesses by the implemented DP, as described in *Using the AP to access debug resources on page A1-31*. A summary of how to access an AP is given in *Selecting and accessing an AP on page C1-143*.

- For all APs, reserved registers must be RES0. This requirement applies to all APs, including any implemented by companies other than ARM.

There are no other requirements for APs in the ADIv5 specifications. All features that are provided by an AP can be IMPLEMENTATION DEFINED.
**C1.2 Selecting and accessing an AP**

Any APACC request to a MEM-AP, a JTAG-AP, or an AP not defined by this specification must be answered by the DP according to the following addressing scheme:

- The value of the **SELECT.APSEL** field must be used to select which AP is accessed.
- The value of the **SELECT.APBANKSEL** field must be used to select the four-register bank of AP registers is accessed. This information is passed as the A[7:4] field of the AP access.
- The A[3:2] field that is passed in the APACC access must be used to select the AP register within the selected four-register bank.
- The RnW field for the APACC access must be used to determine whether the AP register access is a read access or a write access.

For detailed information about DP support for APACC accesses, see Chapter B3 *The JTAG Debug Port (JTAG-DP)* and Chapter B4 *The Serial Wire Debug Port (SW-DP)*.

Examples of implementations of APACC accesses are shown in Figure C2-1 on page C2-149 for a MEM-AP, and Figure C3-1 on page C3-186 for a JTAG-AP.

**C1.2.1 Stalling accesses**

AP interfaces can support stalling accesses, which enable the AP to be connected to slow devices, such as a memory system or a long JTAG scan chain. In this way, the DAP can put an AP access into a pending state, and the access does not have to complete within a fixed number of cycles, which is important because often an AP access cannot complete until the associated memory access or JTAG scan has completed. For more information, see:

- *Stalling accesses* on page C2-154, for stalling accesses to a MEM-AP.
- *Stalling accesses* on page C3-191, for stalling accesses to a JTAG-AP.
C1.3 AP Programmers’ Model

This section describes the AP programmers’ model, which must be implemented by all APs.

C1.3.1 Summary

ADIv5 requires every AP to implement an AP Identification Register, IDR, at offset 0xFC. IDR is the last register in the AP register space, and is described in IDR, Identification Register.

The IDR is the only register that must be implemented by all Access Ports, see Table C1-1.

For information about the programmers’ model for specific AP implementations, see Chapter C2 The Memory Access Port (MEM-AP) and Chapter C3 The JTAG Access Port (JTAG-AP).

Table C1-1 Common AP programmers’ model

<table>
<thead>
<tr>
<th>Offset</th>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xFC</td>
<td>RO</td>
<td>IDR</td>
<td>Identification Register.</td>
</tr>
</tbody>
</table>

C1.3.2 IDR, Identification Register

**Purpose**

IDR identifies the Access Port. An IDR value of zero indicates that there is no AP present.

**Usage constraints**

The value of IDR after a reset is IMPLEMENTATION DEFINED.

IDR is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>RO</td>
</tr>
</tbody>
</table>

**Configurations**

IDR is implemented in DPv0, DPv1, and DPv2.

DAPs that comply with the ADIv5 specification must implement the JEP106 code and provide a value in the REVISION and CLASS fields.

**Attributes**

IDR is A 32-bit read-only register.

**Field descriptions**

The IDR bit assignments are:

<table>
<thead>
<tr>
<th>31</th>
<th>28</th>
<th>27</th>
<th>17</th>
<th>16</th>
<th>13</th>
<th>12</th>
<th>8</th>
<th>7</th>
<th>4</th>
<th>3</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>REVISION</td>
<td>DESIGNER</td>
<td>CLASS</td>
<td>RES0</td>
<td>VARIANT</td>
<td>TYPE</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**REVISION, bits[31:28]**

Starts at 0x0 for the first implementation of an AP design, and increments by 1 on each major or minor revision of the design. Major design revisions introduce functionality changes, minor revisions are bug fixes.
**DESIGNER, bits[27:17]**

Code that identifies the designer of the AP.

This field indicates the designer of the AP and not the implementer, except where the two are the same. To obtain a number, or to see the assignment of these codes, contact JEDEC http://www.jedec.org.

A JEDEC code takes the following form:

- A sequence of zero or more numbers, all having the value 0x7F.
- A following 8-bit number, that is not 0x7F, and where bit[7] is an odd parity bit. For example, ARM Limited is assigned the code 0x7F 0x7F 0x7F 0x7F 0x3B.

The encoding that is used in the IDR is as follows:

- The JEP106 continuation code, IDR bits[27:24], is the number of times that 0x7F appears before the final number. For example, for ARM Limited this field is 0x4.
- The JEP106 identification code, IDR bits[23:17], equals bits[6:0] of the final number of the JEDEC code. For example, for ARM Limited this field is 0x3B.

**Note**

The JEP106 codes are assigned by JEDEC to identify the manufacturer of a device. However, in the AP Identification register they identify the designer of the AP.

An implementer of an ARM MEM-AP or JTAG-AP must not change these AP Identification Register values.

**Note**

- For backwards compatibility, debuggers must treat an AP return a JEP106 field of zero as an AP designed by ARM. This encoding was used in early implementations of the DAP. In such an implementation, the REVISION and CLASS fields are also RAZ.
- DAPs that comply with the ADIv5 specificat ion must use the JEP106 code and provide a value in the REVISION and CLASS fields.

**CLASS, bits[16:13]**

Defines the class of AP. An AP belongs to a class if it follows a programmers’ model that is defined as part of the ADIv5 specification or extensions to it. This field can have the following values:

- 000000  No defined class.

**Bits[12:8]**

Reserved, RES0. This field is reserved for future ID register fields. If a debugger reads a non-zero value in this field, it must treat the AP as unidentifiable.

**VARIANT, bits[7:4]**

Together with the TYPE field, this field identifies the AP implementation. VARIANT differentiates AP implementations that have the same value of TYPE.

Each AP designer must maintain their own list of implementations and associated AP Identification codes.

**TYPE, bits[3:0]**

Indicates the type of bus, or other connection, that connects to the AP. Table C1-2 on page C1-146 lists the possible values of the Type field for an AP designed by ARM. It also shows the value of the CLASS field, which corresponds to bits[16:13] of the IDR, for each value of TYPE.

Together with the VARIANT field, this field identifies the AP implementation. AP implementations that have the same value of TYPE are differentiated by their VARIANT value.
Each AP designer must maintain their own list of implementations and associated AP Identification codes.

### Table C1-2 AP Identification types for an AP designed by ARM

<table>
<thead>
<tr>
<th>TYPE</th>
<th>Connection to AP</th>
<th>CLASS</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x0</td>
<td>JTAG connection</td>
<td>0b0000</td>
<td>VARIANT field, bits [7:4] of IDR, must be non-zero.</td>
</tr>
<tr>
<td>0x1</td>
<td>AMBA AHB3 bus</td>
<td>0b1000</td>
<td>-</td>
</tr>
<tr>
<td>0x2</td>
<td>AMBA APB2 or APB3 bus</td>
<td>0b1000</td>
<td>-</td>
</tr>
<tr>
<td>0x4</td>
<td>AMBA AXI3 or AXI4 bus, with optional ACE-Lite support</td>
<td>0b1000</td>
<td>Not defined in issue A of this document.</td>
</tr>
<tr>
<td>0x5</td>
<td>AMBA AHB5 bus</td>
<td>0b1000</td>
<td>-</td>
</tr>
<tr>
<td>0x6</td>
<td>AMBA APB4 bus</td>
<td>0b1000</td>
<td>-</td>
</tr>
<tr>
<td>Other</td>
<td>Reserved</td>
<td></td>
<td>-</td>
</tr>
</tbody>
</table>

### Accessing IDR

IDR can be accessed at the following address:

<table>
<thead>
<tr>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xFC</td>
</tr>
</tbody>
</table>
Chapter C2
The Memory Access Port (MEM-AP)

This chapter describes the implementation of the Memory Access Port (MEM-AP), and how a MEM-AP connects the DP to a debug component.

This chapter contains the following sections:

- About the MEM-AP on page C2-148.
- MEM-AP functions on page C2-152.
- Implementing a MEM-AP on page C2-162.
- MEM-AP examples of pushed-verify and pushed-compare on page C2-164.
- MEM-AP Programmers’ Model on page C2-166.
- MEM-AP register descriptions on page C2-167.

For information that applies to all APs, see Chapter C1 About the AP.
C2.1 About the MEM-AP

A MEM-AP provides a DAP with AP access to a memory-mapped abstraction of a set of debug resources in the system being debugged.

--- Note ---
Access to a MEM-AP might only access a register within the MEM-AP, without generating a memory access to the system being debugged.

C2.1.1 The programmers’ model for debug register access

The programmers’ model for debug registers is a memory map. Although use of a memory bus system is not required, this abstraction enables the same programming model to be used for accessing debug registers and system memory. With this model, the debug registers might be implemented as a peripheral within the system memory space.

The debug registers in a debug component occupy one or more 4KB blocks of address space, and a system might contain several such debug components.

Although the architecture specification permits a debug component to implement multiple 4KB blocks, most components implement a single block.

--- Note ---
Although a component can occupy only 4KB of address space, ARM recommends that the base address of each component is aligned to the largest translation granule supported by any processor that can access the component. For an ARMv8 processor, the granule size can be up to 64KB.

Debug register files

A 4KB block of address space accessible from an AP can be referred to as a debug register file. A single AP can access multiple debug register files. There is a base standard for debug register file identification, and debuggers must be able to recognize and ignore register files that they do not support.

A single MEM-AP can access a mixture of system memory and debug register files.

ROM Tables

A ROM Table is a special case of a debug register file. It is a 4KB memory block that identifies a system.

If there is only one debug component in the system to which the MEM-AP is connected, the ROM Table is optional. However, because the ROM Table contains a unique system identifier that identifies the complete SoC to the debugger, an implementation might choose to include a ROM Table even if there is only one other debug component in the system.

When a system includes more than one debug component it must include a ROM Table.

Chapter D2 About ROM Tables describes ROM Tables.

C2.1.2 Selecting and accessing the MEM-AP

Figure C2-1 on page C2-149 shows the implementation of a MEM-AP, and how the MEM-AP connects the DP to the debug components. Two example debug components are shown, a processor core and an Embedded Trace Macrocell (ETM), together with a ROM Table. APACC accesses to the DP are passed to the MEM-AP.

The method of selecting an AP, and selecting a specific register within the selected AP, is the same for MEM-APs and JTAG-APs. See also Selecting and accessing an AP on page C1-143.
C2 The Memory Access Port (MEM-AP)

C2.1 About the MEM-AP

The MEM-AP registers, and the memory map of the MEM-AP, are described in detail in MEM-AP register descriptions on page C2-167. However, you require a basic knowledge of the functions of these registers to understand the operation of the MEM-AP. The MEM-AP registers are shown in Figure C2-1:

Control/Status Word register, CSW

The CSW holds control and status information for the MEM-AP.

Transfer Address Register, TAR

The TAR holds the address for the next access to the memory system, or set of debug resources, which are connected to the MEM-AP. The MEM-AP can be configured so that the TAR is incremented automatically after each memory access. Reading or writing to the TAR does not cause a memory access.
**Data Read/Write register, DRW**

The DRW is used for memory accesses:

- Writing to the DRW initiates a write to the address specified by the TAR.
- Reading from the DRW initiates a read from the address that is specified by the TAR. When the read access completes, the value is returned from the DRW.

**Banked Data Registers, BD0 to BD3**

The Banked Data Registers, BD0-BD3, provide direct read or write access to a block of four words of memory, starting at the address that is specified in the TAR:

- Accessing BD0 accesses \((TAR[31:4] \ll 4)\) in memory.
- Accessing BD1 accesses \(((TAR[31:4] \ll 4) + 0x4)\) in memory.
- Accessing BD2 accesses \(((TAR[31:4] \ll 4) + 0x8)\) in memory.
- Accessing BD3 accesses \(((TAR[31:4] \ll 4) + 0xC)\) in memory.

The value in TAR[3:0] is ignored in constructing the access address:

- The values of bits[3:2] of the access address depend solely on which of the four banked data registers is being accessed.
- Bits[1:0] of the access are always zero.

**Configuration register, CFG**

The CFG register holds information about the configuration of the MEM-AP.

**Debug Base Address register, BASE**

The BASE register is a pointer into the connected memory system. It points to one of:

- The start of a set of debug registers for the single connected debug component.
- The start of a ROM Table that describes the connected debug components.

**Identification Register, IDR**

The IDR identifies the MEM-AP.

---

**Note**

This brief summary of the MEM-AP registers does not include cross-references to the detailed register descriptions. For more information about these registers, see [MEM-AP register descriptions on page C2-167](#).

---

**C2.1.4 MEM-AP register accesses and memory accesses**

---

**Note**

In this section, an access to the debug resources is described as a memory access.

---

This section summarizes all the possible APACC accesses to a MEM-AP, and covers accesses to each of the MEM-AP registers. These accesses are summarized in the following sections:

- **Accesses that do not initiate a memory access**.
- **Accesses that initiate a memory access on page C2-151**.
- **Accesses that support pushed transactions and the transaction counter on page C2-151**.

**Accesses that do not initiate a memory access**

APACC accesses to the following MEM-AP registers do not cause a memory access:

- The Control/Status Word register, CSW.
- The Transfer Address Register, TAR.
- The Configuration register, CFG.
- The Debug Base Address register, BASE.
- The Identification Register, IDR.
Accesses that initiate a memory access

This section introduces the APACC accesses to MEM-AP registers that initiate one or more memory accesses. These APACC accesses are:

- Accesses to the DRW register. A memory access is initiated, using the address that is held in the TAR.
- Accesses to one of the Banked Data Registers, BD0-BD3.
  The address that is used for the memory access depends on which Banked Data Register is accessed.
- Accesses to the Memory Barrier Transfer register, MBT.

However, if the MEM-AP implementation includes the Large Data Extension, and CSW.Size specifies a transfer size that is larger than a word, some DRW and BD0-BD3 accesses do not initiate a memory access, see DRW, Data Read/Write register on page C2-179 and Accessing BD0-BD3 on page C2-171.

Sometimes, a single AP transaction initiates more than one memory access:

- When the transaction counter is set. See The transaction counter on page B1-43.
- When packed transfers are supported and enabled and the transfer size is smaller than word. See Packed transfers on page C2-158.

For more information, see Packed transfers on page C2-158.

If an AP transaction initiates one or more memory accesses, the AP transaction does not complete until one of the following occurs:

- All the memory accesses complete successfully.
- A memory access terminates with an error response. In this case, any outstanding accesses to the debug component are abandoned.
- The AP accesses are aborted using the ABORT register.

Accesses that support pushed transactions and the transaction counter

A MEM-AP supports pushed transactions and sequences of transactions to the following registers only:

- DRW, Data Read/Write register.
- Banked Data registers 0-3, see BD0-BD3, Banked Data registers on page C2-170.

For more information, see:

- Pushed-compare and pushed-verify operations on page B1-44.
- The transaction counter on page B1-43.
C2 The Memory Access Port (MEM-AP)

C2.2 MEM-AP functions

This section describes the functions of a MEM-AP. These functions are controlled by the MEM-AP registers, as described in MEM-AP register descriptions on page C2-167.

The following sections describe functions that a MEM-AP must support:

- Enabling access to the connected debug device or memory system.
- Auto-incrementing the Transfer Address Register (TAR).
- Stalling accesses on page C2-154.
- Response to debug component errors on page C2-155.

The following sections describe functions for which it is IMPLEMENTATION DEFINED whether a particular MEM-AP supports them:

- Variable access size for memory accesses on page C2-156.
- Byte lanes on page C2-157.
- Packed transfers on page C2-158.
- Software access control on page C2-161.
- Implementing a MEM-AP on page C2-162.

Note

Some of the IMPLEMENTATION DEFINED functions are inter-dependent. Their dependencies are summarized in MEM-AP implementation requirements on page C2-162.

C2.2.1 Enabling access to the connected debug device or memory system

Access to the debug device or memory system is controlled by Device Enable signal, DEVICEEN. This signal is an input to the DAP. DEVICEEN is normally tied HIGH, so that it is asserted even when the Debug Enable signal, DBGEN, is LOW, allowing the MEM-AP to be programmed even when debug is disabled.

The current value of the DEVICEEN signal is shown by the read-only CSW.DeviceEn flag, which indicates whether the MEM-AP is able to issue transactions to the memory system to which it is connected.

When CSW.DeviceEn is 0b0, no transactions can be issued to any address, and any access to the Data Read/Write Register or to any of the Banked Data Registers immediately causes the CTRL/STAT.STICKYERR bit to be set to 0b1. The access does not cause a MEM-AP transaction.

If there is no DEVICEEN signal for a device, the DeviceEn flag must Read-As-One.

C2.2.2 Auto-incrementing the Transfer Address Register (TAR)

As indicated in The MEM-AP registers on page C2-149, the Transfer Address Register (TAR) holds an address in the address map of the debug resource that is connected to the MEM-AP. This address is used as:

- The address in the debug component memory map of read or write accesses that are initiated by a read or write of the DRW.
- The base address determines the address in the debug component memory map of read or write accesses that are initiated by a read or write of one of the Banked Data Registers, as described in Accesses that initiate a memory access on page C2-151.

Software can configure the MEM-AP to auto-increment the TAR on every read or write access to the DRW. Auto-incrementing is controlled by the CSW.AddrInc field.

When auto address incrementing is enabled, the address in the TAR is updated whenever an access to the DRW is successful. However, if the DRW transaction completes with an error response, or the transaction is aborted, the TAR is not incremented.
Note

Accesses to the Banked Data Registers never cause the TAR to auto-increment. The AddrInc field has no effect on accesses to the Banked Data Registers.

The permitted values of the AddrInc field are summarized in Table C2-1.

<table>
<thead>
<tr>
<th>AddrInc value</th>
<th>Description</th>
<th>Support required?</th>
</tr>
</thead>
<tbody>
<tr>
<td>0b00</td>
<td>Auto-increment off</td>
<td>Always.</td>
</tr>
<tr>
<td>0b01</td>
<td>Increment single</td>
<td>Always.</td>
</tr>
<tr>
<td>0b10</td>
<td>Increment packed</td>
<td>If Packed transfers are supported. See Packed transfers on page C2-158. If Packed transfers are not supported, the value 0b10 selects the Auto-increment off mode and reading the AddrInc value returns 0b00.</td>
</tr>
<tr>
<td>0b11</td>
<td>Reserved</td>
<td>-</td>
</tr>
</tbody>
</table>

The modes of operation that is associated with each of the possible settings of this field are:

Auto-increment off

The address in the TAR is not automatically incremented, and remains unchanged after any Data Read/Write Register access.

Increment single

After a successful DRW access, the address in the TAR is incremented by the size of the access. For information about different access sizes, see Variable access size for memory accesses on page C2-156.

Note

It is IMPLEMENTATION DEFINED whether a MEM-AP supports transfer sizes other than Word. If a MEM-AP only supports word transfers and Increment single is selected, the TAR always increments by four after a successful DRW transaction.

Increment packed

Setting AddrInc to 0b10, Increment packed, enables packed transfers, which pack multiple halfword or byte memory accesses into a single word APACC access. Packed transfers are described in more detail in Packed transfers on page C2-158.

It is IMPLEMENTATION DEFINED whether a MEM-AP supports packed transfers, but:

- An implementation that supports transfers smaller than a word must support packed transfers.
- Packed transfers cannot be supported on a MEM-AP that only supports word transfers.

When packed transfer operation is enabled and the transfer size is smaller than a word, each DRW access causes multiple memory accesses, and the value in the TAR is auto-incremented correctly after each memory access. For example:

- For packed accesses with a CSW.Size value of 0b001, denoting halfword (16-bits) transfers, each DRW read access generates two data bus transfers. The value in the TAR is incremented by 0x2 after each successful data bus transfer. As described in Packed transfers on page C2-158, the two halfword values from the two reads are packed into a single 32-bit word that is returned through the APACC.
• With packed accesses enabled, and a CSW.Size value of 0b000, denoting byte transfers, a single DRW write operation generates four 8-bit data bus transfers, and the TAR is incremented by 0x1 after each of these transfers.

Automatic address increment is only guaranteed to operate on the 10 least significant bits of the address that is held in the TAR. Whether it is possible to auto increment bit [10] and beyond is IMPLEMENTATION DEFINED, which means that auto address incrementing at a 1KB boundary is IMPLEMENTATION DEFINED. For example, if the TAR is 0x14A4, and the access size is word, successive accesses to the DRW increment TAR to 0x14A8, 0x14AC, and in steps of 4 bytes up to the end of the 1KB range at 0x17FC. The auto-increment behavior on the next DRW access is IMPLEMENTATION DEFINED.

### C2.2.3 Stalling accesses

A MEM-AP access by the DP to the DRW register or one of the Banked Data Registers BD0-BD3 might not complete until the required memory access is completed. Therefore, to be able to support slow connections, a MEM-AP must support stalling accesses, which do not have to be completed within a fixed number of cycles.

An example of the importance of stalling accesses can be found in the ARMv7 Debug Architecture, which specifies a mode of operation where accesses to the Data Transfer Registers (DTRs) and Instruction Transfer Register (ITR) do not complete until the processor is ready to accept new data. The following sequence describes how a processor that complies with the ARMv7 Debug Architecture, and an ADIV5 DAP that comprises a MEM-AP and a JTAG-DP, might co-operate to inform the debugger that it has to retry an access because of such a condition.

1. The initial conditions are:
   - The processor core is idle and configured to stall accesses to its ITR and DTRs when it is not ready to accept new data.
   - The DP SELECT register addresses a MEM-AP with a connection to the processor.
   - The AP TAR addresses the ITR of the processor core.

2. The debugger writes a first instruction to the ITR:
   - The debugger performs an AP write to DRW with the first instruction to execute:
     - The AP is ready, so the DP returns an OK/FAULT ACK response.
     - In the Update-DR state, the DP initiates a transfer to the AP.
   - The TAR addresses the ITR on the processor, and the AP access consists of a write to the DRW. Therefore, the AP initiates a write to the ITR through its connection to the processor.
   - The core accepts the transfer, because the processor is idle and the instruction complete flag, InstrCompl, is 0b1.
   - The transfer completes.
   - The core starts to execute the instruction from the ITR. InstrCompl is set to 0b0.

   **Note**
   The ACK value OK/FAULT is issued before the transfer is accepted by the core.

3. The debugger writes a second instruction to the ITR:
   - The debugger performs an AP write to DRW with the next instruction to execute:
     - The AP is ready, so the DP returns an OK/FAULT ACK response.
     - In the Update-DR state, the DP initiates a transfer to the AP.
   - The TAR has not changed, and the AP initiates a second write to the ITR through its connection to the processor.
   - The core is still executing the first instruction (InstrCompl is 0b0) and cannot accept the transfer.
   - The transfer cannot complete, and the AP remains busy.
ACK returns the value OK/FAULT because the AP is ready to accept a new transfer. The AP does not know that the core is not able to accept the transfer until it attempts the transfer.

4. The debugger writes a third instruction to the ITR:
   a. The debugger performs an AP write to DRW with the next instruction to execute:
      • The AP is not ready, so the DP returns a WAIT ACK response.
      • In the Update-DR state, the DP discards the AP access request, because the AP was not ready at Capture-DR.
   b. The debugger might retry the AP write until the DP returns the ACK value OK/FAULT instead of WAIT in the Capture-DR state to signal that the first instruction has completed.

5. When the core completes the first instruction, the following happens:
   a. InstrCompl is set to 0b1.
   b. The external debug interface on the core is now ready to accept the second instruction.
   c. The AP transfer from stage 3 is accepted by the core, and the second instruction is written to the ITR.
   d. The core starts to execute the second instruction. InstrCompl is set to 0b0 again.
   e. Because the AP transfer is complete, the AP returns to the ready state.

6. The debugger retries writing the third instruction to the ITR:
   a. The debugger performs an AP write to DRW with the third instruction:
      • The AP is ready, so the DP returns an OK/FAULT ACK response.
      • In the Update-DR state, the DP initiates a transfer to the AP.
   b. The TAR has not changed, therefore, the AP initiates another write to the ITR through its connection to the processor.
   c. The response to the AP write attempt depends on whether the processor has finished processing the last instruction that was written to the ITR:
      • If the processor is idle (InstrCompl is 0b1), the AP transfer completes, writing a new instruction to the ITR. The core starts to execute the new instruction, and the AP returns to the ready state. This stage, stage 6, of the debug session is repeated for the next instruction from the debugger.
      • If the processor is still processing the previous instruction, InstrCompl is 0b0. The processor cannot accept the transfer and the AP remains busy. The debug session repeats stage 4.

C2.2.4 Response to debug component errors

If the MEM-AP receives an error response from a debug component, it returns an error to the DP. As a result of this error, the DP sets the STICKYERR flag. For more information about error handling flags, see Sticky flags and DP error responses on page B1-41.
C2.2.5 Variable access size for memory accesses

It is IMPLEMENTATION DEFINED whether a MEM-AP supports memory access sizes other than word (32-bit).

If a MEM-AP implementation does not support the Large Data Extension, but does support various access sizes, it must support word, halfword, and byte accesses.

Note

The ARM Debug Interface specification does not require a MEM-AP to support access sizes other than word. If a MEM-AP can access other memory, such as system memory, however, ARM recommends that it supports other access sizes as well.

For more information, see MEM-AP implementation requirements on page C2-162.

The access size is controlled by the CSW.Size field. Table C2-2 shows the access size options.

Table C2-2 Size field values when the MEM-AP supports different access sizes

<table>
<thead>
<tr>
<th>Size value, CSW.Size</th>
<th>Memory access size</th>
<th>Support required?</th>
</tr>
</thead>
<tbody>
<tr>
<td>0b000</td>
<td>Byte (8-bits)</td>
<td>No</td>
</tr>
<tr>
<td>0b001</td>
<td>Halfword (16-bits)</td>
<td>No</td>
</tr>
<tr>
<td>0b010</td>
<td>Word (32-bits)</td>
<td>Yesa</td>
</tr>
<tr>
<td>0b011b</td>
<td>Doubleword (64-bits)</td>
<td>No</td>
</tr>
<tr>
<td>0b100b</td>
<td>128-bits</td>
<td>No</td>
</tr>
<tr>
<td>0b101b</td>
<td>256-bits</td>
<td>No</td>
</tr>
<tr>
<td>0b110 - 0b111</td>
<td>Reserved</td>
<td>-</td>
</tr>
</tbody>
</table>

a. On a MEM-AP implementation that does not support access sizes other than word, the Size field is read-only, and always returns the value 0b010.

b. Supported by the MEM-AP Large Data Extension, see MEM-AP Large Data Extension on page C2-163. If the extension is not implemented, this value is reserved.

When a CSW.Size specifies a size that is smaller than a word, the resulting data access is returned in byte lanes. See Byte lanes on page C2-157 for more information.

Caution

If a Banked Data Register is accessed with CSW.Size set to any size other than word or doubleword, behavior is UNPREDICTABLE.
# Byte lanes

A MEM-AP that supports memory transfers of less than 32-bits uses byte lanes for the data transfers between the DRW and the debug component. Which byte lanes are used depends on:

- The memory transfer size, which is specified by the `CSW.Size` field, see *Variable access size for memory accesses on page C2-156*.
- The two least significant bits of the `TAR`, `TAR[1:0]`.

If supported, packed transfers also use byte lanes for byte and halfword transfers, as described in *Packed transfers on page C2-158*.

Table C2-3 shows how byte lanes are used in DRW.

<table>
<thead>
<tr>
<th>CSW[2:0], Size</th>
<th>TAR[1:0]</th>
<th>Access data</th>
</tr>
</thead>
<tbody>
<tr>
<td>0b000, byte</td>
<td>0b00</td>
<td>DRW[7:0]</td>
</tr>
<tr>
<td></td>
<td>0b01</td>
<td>DRW[15:8]</td>
</tr>
<tr>
<td></td>
<td>0b10</td>
<td>DRW[23:16]</td>
</tr>
<tr>
<td></td>
<td>0b11</td>
<td>DRW[31:24]</td>
</tr>
<tr>
<td>0b001, halfword</td>
<td>0b00</td>
<td>DRW[15:0]</td>
</tr>
<tr>
<td></td>
<td>0b10</td>
<td>DRW[31:16]</td>
</tr>
<tr>
<td></td>
<td>0bX1</td>
<td>IMPLEMENTATION DEFINED(^a)</td>
</tr>
<tr>
<td>0b010, word</td>
<td>0b00</td>
<td>DRW[31:0]</td>
</tr>
<tr>
<td></td>
<td>0b1X, 0bX1</td>
<td>IMPLEMENTATION DEFINED(^a)</td>
</tr>
</tbody>
</table>

\(^a\) IMPLEMENTATION DEFINED behavior is one of the following:

- Unaligned portions of the address are ignored. For example, an unaligned word access to 0x8003 accesses the 32-bit value at 0x8000. The access is faulted, and the MEM-AP returns an error response. The access is made to the unaligned address specified in TAR[31:0], and the result is packed as if packed transfers were enabled, see *Packed transfers on page C2-158*. The data transfer might be split into more than one memory access across the connection to the debug component. For example, an unaligned word access to 0x8003 accesses the bytes at 0x8000, 0x8004, 0x8005, and 0x8006. This word access might generate four byte-wide accesses to memory, or the accesses to bytes 0x8004 and 0x8005 might be performed as a single halfword (16-bit) access.

## Big-endian support

The byte lane with the lowest address corresponds to the least significant byte of DRW or BD0-BD3, and can be described as little-endian.

Previous versions of this manual described a variant of the MEM-AP which supported an alternative byte-lane scheme, where the byte lane with the lowest address corresponded to the most significant byte of DRW or BD0-BD3, or big-endian. bit[0] of the CFG register was used to describe whether the MEM-AP was little-endian or big-endian. ADIv5.2 obsoletes this scheme.

If the target uses a big-endian memory arrangement, the external debugger must treat the values that are passed through the MEM-AP accordingly.
### Packed transfers

Whether a MEM-AP supports packed transfers is IMPLEMENTATION DEFINED. If packed transfers are supported, they are enabled by setting the auto address increment field, CSW.AddrInc, to 0b10 (Increment packed). See [Auto-incrementing the Transfer Address Register (TAR)] on page C2-152.

When packed transfers are enabled, each access to the DRW results in one of the following actions, depending on the value of the CSW.Size field, see [Variable access size for memory accesses] on page C2-156:

- If CSW.Size = 0b001 (halfword), there are two halfword (16-bit) accesses.
- If CSW.Size = 0b000 (byte), there are four byte (8-bit) accesses.

Use of packed transfers with CSW.Size set to a transfer size larger than word is UNPREDICTABLE.

#### Note

Packing occurs before any pushed comparisons are made. Pushed comparisons are made, and the STICKYCMP flag is set to 0b1 if necessary, only when a complete word of data has been packed into the DRW. See [Pushed-compare and pushed-verify operations] on page B1-44 for a description of pushed comparisons.

When packed transfers are enabled, after each successful memory access the address held in the Transfer Address Register is automatically updated by the access size.

Accesses are always made in increasing memory address order:

- For write accesses to memory, data is unpacked from the DRW in byte-lanes that depend on the memory address of each write access.
- For read accesses, data is packed into the DRW in byte-lanes that depend on the memory address of each read access.

The byte lanes for data packing and unpacking are the same as the byte lanes that are described in [Table C2-3 on page C2-157], as shown in the following examples:

- Example C2-1, [Halfword packed write operation].
- Example C2-2 on page C2-159, [Byte packed write operation] on page C2-159.
- Example C2-3 on page C2-159, [Halfword packed read operation] on page C2-159.

#### Note

The descriptions in these examples assume that each memory access completes successfully. If any access terminates with an error response, the sequence is halted at that point, and the MEM-AP returns an error to the DP.

---

**Example C2-1 Halfword packed write operation**

This example describes a single word (32-bit) write access to DRW on a MEM-AP with the following settings:

- CSW.Size = 0b001, specifying halfword (16-bit) memory accesses.
- CSW.AddrInc = 0b10, specifying packed transfer operation.
- TAR[31:0] = 0x00000000, the base address of the access.

Two write transfers are made. The *halfword* entries in [Table C2-3 on page C2-157] define the byte lanes for these accesses. The accesses are made in the following order:

1. \( \text{TAR}[1] = 0b0 \), so \( \text{DRW}[15:0] \) is written to address 0x00000000.
   
   After this transfer, the value in the TAR is increased by the transfer size of 2, and becomes 0x00000002.

2. \( \text{TAR}[1] = 0b1 \), so \( \text{DRW}[31:16] \) is written to address 0x00000002.
   
   After this transfer, the value in the TAR is increased by the transfer size, 2, and becomes 0x00000004.
Example C2-2 Byte packed write operation

This example describes a single word (32-bit) write access to DRW on a MEM-AP with the following settings:

- CSW.Size = 0b000, specifying byte (8-bit) memory accesses
- CSW.AddrInc = 0b10, specifying packed transfer operation
- TAR[31:0] = 0x00000002, the base address of the access.

Four write transfers are made. The byte entries in Table C2-3 on page C2-157 define the byte lanes for these accesses. The accesses are made in the following order:

1. TAR[1:0] == 0b10, so DRW[23:16] is written to address 0x00000002.
   After this transfer, the value in the TAR is increased by the transfer size, 1, and becomes 0x00000003.

2. TAR[1:0] == 0b11, so write DRW[31:24] is written to address 0x00000003.
   After this transfer, the value in the TAR is increased by the transfer size, 1, and becomes 0x00000004.

3. TAR[1:0] == 0b00, so write DRW[7:0] is written to address 0x00000004.
   After this transfer, the value in the TAR is increased by the transfer size, 1, and becomes 0x00000005.

4. TAR[1:0] == 0b01, so write DRW[15:8] is written to address 0x00000005.
   After this transfer, the value in the TAR is increased by the transfer size, 1, and becomes 0x00000006.

Example C2-3 Halfword packed read operation

This example describes a single word (32-bit) read access to DRW on a MEM-AP with the following settings:

- CSW.Size = 0b001, specifying halfword (16-bit) memory accesses.
- CSW.AddrInc = 0b10, to give packed transfer operation.
- TAR[31:0] = 0x00000002, to define the base address of the access.

Two read transfers are made. The little-endian halfword entries in Table C2-3 on page C2-157 define the byte lanes for these accesses. The accesses are made in the following order:

- TAR[1] == 0b1, so read a halfword from address 0x00000002, and pack this value into DRW[31:16].
  After this transfer, the value in the TAR is increased by the transfer size, 2, and becomes 0x00000004.

- TAR[1] == 0b0, so read a halfword from address 0x00000004, and pack this value into DRW[15:0].
  After this transfer, the value in the TAR is increased by the transfer size, 2, and becomes 0x00000006.

- The complete word has been read into the DRW, and the APACC read access completes.

The optional DP transaction counter, described in *The transaction counter* on page B1-43, enables an external debugger to make a single AP transaction request that generates multiple AP transactions. Each of these transactions transfers a single word (32-bits) of data, and the TAR is incremented automatically between the transactions. If the MEM-AP supports memory accesses smaller than word and packed transfers and packed transfer operation is enabled, each of the AP transactions that are driven by the transaction counter is split into multiple memory accesses. For example, if the transaction counter is programmed to generate eight word accesses, and the MEM-AP is programmed to make packed byte transfers, a total of 32 memory accesses of one byte are made.

C2.2.8 Slave Memory Ports

A MEM-AP can include a slave memory port, which can be used by an external bus master to access the area of memory that is mastered by the MEM-AP. For example, the external bus master can be permitted to access the debug registers of the system to which the MEM-AP is connected.
If a MEM-AP implements a slave memory port, slave memory port accesses are multiplexed with DAP accesses. Slave memory port accesses have bit[31] of the access address forced to zero. A debug component can use the value of this address bit to distinguish between slave memory port accesses and DAP accesses.

For more information about MEM-AP memory addressing, see BASE, Debug Base Address register on page C2-167.

Note
The DAP can emulate a slave memory port access by setting bit [31] of the Transfer Address Register to 0b0.
C2.2.9 Software access control

It is IMPLEMENTATION DEFINED whether the CSW register includes the debug software access enable flag CSW.DbgSwEnable.

The CSW.DbgSwEnable flag can be applied as follows:

**Using DbgSwEnable to control a slave memory port**

If a MEM-AP implements a slave memory port, the DbgSwEnable flag can be used to enable or disable the port as shown in Table C2-4. For information about slave memory ports, see *Slave Memory Ports* on page C2-159.

**Using DbgSwEnable to control software access to debug resources**

The DbgSwEnable flag can drive a system-level signal, `DBGSWENABLE`. This signal gates software access to debug resources. For example, in a processor that complies with the ARMv7 Debug Architecture, some CP14 registers are not accessible when `DBGSWENABLE` is LOW. For more information, see the *ARM Architecture Reference Manual, ARMv7-A and ARMv7-R edition*.

**Caution**

ARM strongly recommends not setting CSW.DbgSwEnable to zero. If CSW.DbgSwEnable is implemented and the MEM-AP is disabled, CSW.DbgSwEnable must be treated as one.

Table C2-4 Using DbgSwEnable to control a slave memory port

<table>
<thead>
<tr>
<th>Value of DbgSwEnable</th>
<th>Effect on slave memory port</th>
</tr>
</thead>
<tbody>
<tr>
<td>0b0</td>
<td>Disabled.</td>
</tr>
<tr>
<td>0b1</td>
<td>Enabled.</td>
</tr>
<tr>
<td></td>
<td>This value is the value after a reset.</td>
</tr>
</tbody>
</table>

Table C2-5 Using DbgSwEnable to control software access to debug resources

<table>
<thead>
<tr>
<th>Value of DbgSwEnable</th>
<th>Corresponding value of the DBGSWENABLE signal</th>
</tr>
</thead>
<tbody>
<tr>
<td>0b0</td>
<td>LOW.</td>
</tr>
<tr>
<td>0b1</td>
<td>HIGH.</td>
</tr>
<tr>
<td></td>
<td>This value is the value after a reset.</td>
</tr>
</tbody>
</table>

If neither of these applications is implemented, CSW.DbgSwEnable is RAZ.

If CSW.DbgSwEnable is implemented and the MEM-AP is disabled, CSW.DbgSwEnable must be treated as one.

**Caution**

ARM strongly recommends not setting CSW.DbgSwEnable to zero. If CSW.DbgSwEnable is implemented, setting it to zero can cause software that is executing on the target to malfunction.
C2.3 Implementing a MEM-AP

This section gives information about the implementation of a MEM-AP and contains the following:

- IMPLEMENTATION DEFINED features of a MEM-AP implementation.
- MEM-AP implementation requirements.
- MEM-AP Extensions on page C2-163.

### C2.3.1 IMPLEMENTATION DEFINED features of a MEM-AP implementation

The following features of a MEM-AP implementation are IMPLEMENTATION DEFINED:

- Whether the MEM-AP supports data bus access sizes other than word size.
- Whether the MEM-AP supports packed transfers.
- Whether the MEM-AP includes the MEM-AP Large Physical Address Extension on page C2-163, which implements support for addresses larger than 32 bits.
- Whether the MEM-AP includes MEM-AP Barrier Operation Extension on page C2-163, which implements support for barrier operations.
- Whether the MEM-AP supports the features that are described in Software access control on page C2-161.

These implementation choices affect the following register fields:

- CSW.{DbgSwEnable, Mode, AddrInc, Size}.
- CFG.{LD, LA, BE}.

In addition, the CSW register can include the following optional fields that are not described elsewhere in this chapter:

**CSW.Prot and CSW.Type, bits[30:24] and bits[15:12]**

These fields can be implemented to provide a bus access control mechanism. If implemented, it enables a debugger to specify flags for a memory access. The permitted values and their significance are IMPLEMENTATION DEFINED, because they relate to the underlying bus architecture. These bits must reset to a valid access type and ARM strongly recommends that these bits are reset to a useful access type. This reset value might not be zero. For example:

- If the bus supports privileged and non-privileged accesses, the reset value of this field must select privileged accesses.
- If the bus supports code and data accesses, the reset value must select data accesses.
- If the bus supports both Secure and Non-secure address spaces, CSW.Prot and CSW.Type must reset to select Non-secure addresses.

**CSW.SPIDEN, bit[23]**

This field can be implemented to indicate whether the MEM-AP can generate secure accesses.

Several reference implementation options for implementers and users of MEM-APs when connecting to standard memory interfaces are defined in Appendix E1 Standard Memory Access Port Definitions.

### C2.3.2 MEM-AP implementation requirements

The descriptions that are given in the section MEM-AP functions on page C2-152 indicate several areas where the MEM-AP functionality is IMPLEMENTATION DEFINED. However, the IMPLEMENTATION DEFINED features are inter-dependent. These dependencies are summarized here.

In a MEM-AP:

- The options for the size of data bus accesses are:
  - Support word (32-bit) accesses only.
— Support word (32-bit), halfword (16-bit), and byte (8-bit) accesses, and optionally support larger access sizes.

No other combinations of supported access sizes are permitted. For more information, see Variable access size for memory accesses on page C2-156.

• If access sizes smaller than word are not supported, packed transfers are not supported. Otherwise, it is IMPLEMENTATION DEFINED whether packed transfers are supported. For more information, see Packed transfers on page C2-158.

• It is IMPLEMENTATION DEFINED whether access sizes larger than 32-bit are supported. If larger access sizes are not supported, CFG.LD is RAZ. For more information, see MEM-AP Large Data Extension.

• It is IMPLEMENTATION DEFINED whether addresses larger than 32-bit are supported. If larger addresses are not supported, CFG.LA is RAZ. For more information, see MEM-AP Large Physical Address Extension.

• It is IMPLEMENTATION DEFINED whether barrier operations are supported. If barrier operations are not supported, CSW.Mode is RAZ. For more information, see MEM-AP Barrier Operation Extension.

C2.3.3 MEM-AP Extensions

The following subsections summarize the effects of the optional MEM-AP Extensions.

MEM-AP Large Physical Address Extension

The MEM-AP Large Physical Address Extension provides address spaces of up to 64-bits.

Implementing this extension changes the format of the following MEM-AP registers:

• BASE, Debug Base Address register on page C2-167.
• CFG, Configuration register on page C2-174.
• CSW, Control/Status Word register on page C2-176.
• DRW, Data Read/Write register on page C2-179.
• TAR, Transfer Address Register on page C2-181.

MEM-AP Large Data Extension

The MEM-AP Large Data Extension can support 32-bit, 64-bit, 128-bit, or 256-bit accesses, in addition to optional 8-bit and 16-bit accesses.

The following registers have different formats to support this extension:

• CSW, Control/Status Word register on page C2-176.
• DRW, Data Read/Write register on page C2-179.
• BD0-BD3, Banked Data registers on page C2-170.
• CFG, Configuration register on page C2-174.

Although the extension can support 64-bit, 128-bit, and 256-bit accesses, it does not require an implementation to support all these access sizes. If the CSW.Size field is written with a value corresponding to a size that is not supported, or with a reserved value:

• A read of the field returns a value corresponding to a supported size.
• MEM-AP behavior corresponds to the value returned by the read of the CSW.Size field.

MEM-AP Barrier Operation Extension

The MEM-AP Barrier Operation Extension provides support for barrier operations. If the bus supports a weak memory ordering model, then barrier operations must create order.

The following registers are new or have different formats to support this extension:

• CSW, Control/Status Word register on page C2-176.
• MBT, Memory Barrier Transfer register on page C2-181.
C2.4 MEM-AP examples of pushed-verify and pushed-compare

A Debug Port (DP) might support pushed operations, as described in Pushed-compare and pushed-verify operations on page B1-44. However, these operations involve interaction between the DP and an AP, because each pushed operation requires an AP read, which, in the case of a MEM-AP, requires a read from the connected debug memory system. This section gives some examples of pushed operations on a DP that is connected to a MEM-AP.

C2.4.1 Example of using a pushed-verify operation on a MEM-AP

The following pushed-verify mechanism verifies the contents of system memory:

1. Make sure that the MEM-AP Control/Status Word (CSW) register is set up to increment the Transfer Address Register (TAR) after each access.
2. Write the start address of the memory region that is to be verified to the TAR.
3. Write a series of expected values as AP transactions. On each write transaction, the DP issues an AP read access, compares the result against the value that is supplied in the AP write transaction, and sets the CTRL/STAT.STICKYCMP bit if the values do not match.

The TAR is incremented on each transaction.

In this way, the series of values that are supplied is compared against the contents of the memory region, and STICKYCMP is set to $0b1$ if they do not match.

C2.4.2 Example of using a pushed-find operation on a MEM-AP

The following pushed-find mechanism searches system memory for a particular word:

1. Make sure that the MEM-AP Control/Status Word (CSW) register is set up to increment the TAR after each access.
2. Write the start address of the debug register region that is to be searched to the TAR.
3. Repeatedly write the value to be searched for as an AP write transaction to the Data Read/Write register (DRW). On each transaction, the MEM-AP reads the location indicated by the TAR.

The return value is compared with the value supplied in the AP write transaction. If they match, the STICKYCMP flag is set to $0b1$. If they do not match, the TAR is incremented.

Pushed-find can be combined with byte lane masking to search for specific bytes.

For an example of how the transaction counter can refine this search operation, see Example of using the transaction counter for a pushed-compare operation on a MEM-AP on page C2-165.

Pushed-find without address incrementing can be used to poll a single location, for example to test the value of a flag after completion of an operation.
C2.4.3 Example of using the transaction counter for a pushed-compare operation on a MEM-AP

The transaction counter can refine the pushed-compare search operation that is described in Example of using a pushed-find operation on a MEM-AP on page C2-164. Pushed-compare enables searching system memory for a particular word, or, when used with byte lane masking, specific bytes. The transaction counter enables using a single AP write transaction to search an area of memory.

To perform a search under the control of the transaction counter:

1. Make sure that the MEM-AP Control/Status Word (CSW) register is set up to increment the TAR after each access.
2. Write the start address of the debug register region that is to be searched to the TAR.
3. Write to the transaction counter field, CTRL/STAT.TRNCNT to indicate the required number of repeat accesses. This value defines the size of the region to be searched.
4. Write the search value as an AP write to the Data Read/Write register (DRW). The MEM-AP repeatedly reads the location indicated by the TAR. The value that is returned by each read is compared with the value supplied in the AP write transaction. If they match, the STICKYCMP flag is set to 0b1 and the operation completes.
   - The TAR is incremented.
   - If the transaction counter is nonzero, it is decremented.

The operation completes when either the STICKYCMP flag is set to 0b1 or after the final read when the transaction counter was zero.
## C2.5 MEM-AP Programmers’ Model

Table C2-6 shows a memory map of the MEM-AP registers, and indicates where they are described in detail. All registers that are listed in Table C2-6 are required in every MEM-AP implementation. Reserved addresses in the register memory map are RES0.

Using the Debug Port to access Access Ports on page A1-28 explains how to access AP registers.

### Table C2-6 MEM-AP programmers’ model

<table>
<thead>
<tr>
<th>Offset</th>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>RW</td>
<td>CSW</td>
<td>See CSW, Control/Status Word register on page C2-176.</td>
</tr>
<tr>
<td>0x04 - 0x08</td>
<td>RW</td>
<td>TAR</td>
<td>See TAR, Transfer Address Register on page C2-181. If the implementation includes the Large Physical Address Extension, the word at offset 0x004 represents the least significant word of the transfer address, and the word at offset 0x008 represents the most significant word. If the implementation does not include the Large Physical Address Extension, the word at offset 0x004 represents the transfer address, and the word at offset 0x008 is RES0.</td>
</tr>
<tr>
<td>0x0C</td>
<td>RW</td>
<td>DRW</td>
<td>See DRW, Data Read/Write register on page C2-179.</td>
</tr>
<tr>
<td>0x10 - 0x1C</td>
<td>RW</td>
<td>BD0-BD3</td>
<td>See BD0-BD3, Banked Data registers on page C2-170.</td>
</tr>
<tr>
<td>0x20</td>
<td>IMP</td>
<td>MBT</td>
<td>See MBT, Memory Barrier Transfer register on page C2-181. The entries in this row only apply if the implementation includes the Barrier Operation Extension. Otherwise, this register is reserved, RES0.</td>
</tr>
<tr>
<td>0x24 - 0xEC</td>
<td>-</td>
<td>RES0</td>
<td>Reserved for future use.</td>
</tr>
<tr>
<td>0xF0</td>
<td>RO</td>
<td>BASE</td>
<td>See BASE, Debug Base Address register on page C2-167. If the implementation includes the Large Physical Address Extension, the word at this offset represents the most significant word of the debug base address. If the implementation does not include the Large Physical Address Extension, the word at this offset is RES0.</td>
</tr>
<tr>
<td>0xF4</td>
<td>RO</td>
<td>CFG</td>
<td>See CFG, Configuration register on page C2-174.</td>
</tr>
<tr>
<td>0xF8</td>
<td>RO</td>
<td>BASE</td>
<td>See BASE, Debug Base Address register on page C2-167. If the implementation includes the Large Physical Address Extension, the word at this offset represents the least significant word of the debug base address. If the implementation does not include the Large Physical Address Extension, the word at this offset represents the entire debug base address.</td>
</tr>
<tr>
<td>0xFC</td>
<td>RO</td>
<td>IDR</td>
<td>See IDR, Identification Register on page C1-144.</td>
</tr>
</tbody>
</table>
C2.6 MEM-AP register descriptions

This section describes the MEM-AP registers:

- **BASE, Debug Base Address register.**
- **BD0-BD3, Banked Data registers on page C2-170.**
- **CFG, Configuration register on page C2-174.**
- **CSW, Control/Status Word register on page C2-176.**
- **DRW, Data Read/Write register on page C2-179.**
- **MBT, Memory Barrier Transfer register on page C2-181.**
- **TAR, Transfer Address Register on page C2-181.**

C2.6.1 BASE, Debug Base Address register

The BASE characteristics are:

**Purpose**

BASE provides an index into the connected memory-mapped resource. This index value points to one of the following:

- The start of a set of debug registers.
- A ROM Table that describes the connected debug components.

To discover information about the debug components that are connected to the MEM-AP, a debugger can examine the four Component ID registers CIDR0-CIDR3, which are at offset 0xFF0 from the base address. To examine CIDRn, the debugger writes its address, base address + 0xFF0 + n×4, to the TAR and reads the DRW register. The return value allows the debugger to determine the component type of the connected component, which is one of the following:

- ROM Table.
- Debug component.
- Other.

The ADIv5 architecture specification does not specify requirements for the type of component pointed to by BASE.

For more information about CIDR0-CIDR3, see **CIDR0-CIDR3, Component Identification Registers on page D1-217**, and the **ARM® CoreSight™ Architecture Specification**.

**Usage constraints**

The following constraints apply:

- If the bus supports both Secure and Non-secure address spaces, the BASE register is defined to be a Non-secure address. Whether the ROM Tables are also accessible in the Secure address space is IMPLEMENTATION DEFINED.

- A debugger must handle the following situations as non-fatal errors:
  - The base address that is specified by BASEADDR is a faulting location.
  - The four words starting at (base address + 0xFF0) are not valid Component ID registers.
  - An entry in the ROM Table points to a faulting location.
  - An entry in the ROM Table points to a memory block that does not have a set of four valid Component ID registers at offset 0xFF0.

Typically, a debugger issues a warning if it encounters one of these situations. However, ARM recommends that it continues operating. An example of an implementation that might cause errors of this type is a system with static base address or ROM Table entries that enable entire subsystems to be disabled, for example by a tie-off input, packaging choice, fuse, or similar.
BASE is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
</tr>
</tbody>
</table>

**Configurations**

In the 64-bit register implementation, the two words making up BASE are not contiguous in the MEM-AP programmers’ model.

Early implementations of Debug Access Ports had different implementations of the Debug Base Address register, as described in *Legacy format of the BASE register on page C2-170*. The legacy format is a 32-bit register at offset 0xF8.

When BASE is implemented as a 64-bit register, it can specify any address in a 64-bit physical address space. However:

- ROM Tables support only 32-bit signed offset values.
- ARMv7-A processors with the MMU disabled, and ARMv7-R, ARMv6-M, ARMv7-M, and ARMv8-M processors can access only a 32-bit physical address space.

Therefore, ARM recommends that all debug components:

- Are located in the bottom 4GB of the physical address space.
- Are located in one 2GB half of the physical address space.

When BASE is implemented as a 32-bit register and the MEM-AP implements a dedicated connection between the DAP and a set of debug registers, the address map of the connection must be aliased into two logical 2GB segments. Segmentation enables the device to distinguish two types of access:

- Debugger-initiated accesses, which address the logical segment with TAR[31] = 0b1.
- System-initiated accesses, which, if permitted, address the logical segment with TAR[31] = 0b0.

With such an implementation, BASEADDR[31] must be 0b1.

**Note**

- Even where system-initiated accesses are not permitted, ARM recommends that the debug component address space is segmented in this way, and that debugger-initiated accesses have TAR[31] = 0b1.
- Other systems might include IMPLEMENTATION DEFINED methods for signaling debugger accesses to system components.

**Attributes**

BASE is a 32-bit or 64-bit read-only register.
### Field descriptions

The BASE bit assignments are:

<table>
<thead>
<tr>
<th>31</th>
<th>12</th>
<th>11</th>
<th>2</th>
<th>1</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>BASEADDR[31:12]</td>
<td>RES0</td>
<td>1</td>
<td>P</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Format, bit[1] of word at offset 0xF0

Base address register format.

This field is RAO, indicating the ADIv5 format.

--- Note ---

This bit is RAZ in one of the legacy Debug Base Address register formats, see *Legacy format of the BASE register on page C2-170.*

### BASEADDR[31:12], bits[31:12] of word at offset 0xF8

BASEADDR[63:32], bits[31:0] of word at offset 0xF0, 64-bit register only

The 20 or 52 most significant bits of the base address, which is the address offset of the start of the debug register space in the memory-mapped resource, or a ROM Table address. BASEADDR is padded with the 12-bit value 0x000 to complete the 32-bit or 64-bit base address.

If BASE is implemented as a 32-bit register, the word at offset 0xF0 is RES0.

The details of the memory area pointed to by the base address depend on the number of debug components that are connected to the ARM Debug Interface:

- If the ARM Debug Interface is connected to a single debug component, as in the system that is shown in Figure A1-3 on page A1-32, the base address is the start of the debug registers for that component.
  
  If a debug component occupies more than one 4KB page of memory, the base address is the address of the 4KB block which contains the Peripheral ID and Component ID registers of the component.

- If the ARM Debug Interface is connected to more than one debug component, as in the system that is shown in Figure A1-6 on page A1-34, the base address is the address of a ROM Table, which contains the addresses of the other debug components that are connected to the interface. For information about ROM Tables, see *Chapter D2 About ROM Tables.*
  
  A system that contains only a single debug component might be implemented with a separate ROM Table, as shown in Figure A1-5 on page A1-33. In this case, the base address is the address of the ROM Table.

### Bits[11:2] of word at offset 0xF8

Reserved, RES0.

### Format, bit[1] of word at offset 0xF8

Base address register format.

This field is RA0, indicating the ADIv5 format.

--- Note ---

This bit is RAZ in one of the legacy Debug Base Address register formats, see *Legacy format of the BASE register on page C2-170.*

### P, bit[0] of word at offset 0xF8

This field indicates whether a debug entry for this MEM-AP is present:

- 000: No debug entry is present.
- 001: Debug entry is present.
Note

Legacy format of the BASE register includes a description of the legacy format of BASE when there is no debug entry present.

Accessing BASE

BASE can be accessed from the MEM-AP register space:

<table>
<thead>
<tr>
<th>Offset if Large Physical Address extension is not implemented</th>
<th>Offset if Large Physical Address extension is implemented</th>
</tr>
</thead>
<tbody>
<tr>
<td>Least significant word</td>
<td>Most significant word</td>
</tr>
<tr>
<td>0xF8</td>
<td>0xF8</td>
</tr>
</tbody>
</table>

Legacy format of the BASE register

The legacy format of the BASE register is as follows:

Legacy format when no debug entries are present

The BASE bit assignment when there are no debug entries present are:

NOTPRESEN T, bits[31:0]

This field has the value 0xFFFFFFFF, indicating that there are no debug entries.

Legacy format for specifying BASEADDR

When bit[1] of the BASE register is 0b0, the legacy format of the register holds the base address value. In this case, the BASE bit assignments are:

BASEADDR, bits[31:12]


Bits[11:2] Reserved, RAZ.

FORMAT, bit[1]

RAZ, indicating that the BASE register uses the legacy 32-bit BASE register format.

Bit[0]

Reserved, RAZ.

The legacy format is defined only for 32-bit addresses and not permitted for a MEM-AP that implements the Large Physical Address Extension.

The legacy format must not be used for new ARM Debug Interface designs.

C2.6.2 BD0-BD3, Banked Data registers

The BD0-BD3 register characteristics are:

Purpose

BD0-BD3 map AP accesses directly to memory accesses, without having to change the value in the TAR. Together, the four Banked Data Registers give access to four words of the memory space, starting at the address that is specified in the TAR.

Each Banked Data register holds a 32-bit data value:

• In write mode, a Banked Data register holds a value to write to memory.

• In read mode, a Banked Data register holds a value that is read from memory.

Usage Constraints

Auto address incrementing is not performed when a Banked Data register is accessed. The value of CSW.AddrInc has no effect on Banked Data register accesses.
The Large Data Extension supports memory access size values that are greater than word size, as described in *Variable access size for memory accesses*.

- If the large data extension is implemented, accesses other than word or doubleword are **UNPREDICTABLE**.
- If the large data extension is not implemented, accesses other than word are **UNPREDICTABLE**.

The registers are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th>RW</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td>31 0</td>
<td></td>
</tr>
<tr>
<td>BD0</td>
<td>banked data</td>
</tr>
<tr>
<td>31 0</td>
<td></td>
</tr>
<tr>
<td>BD1</td>
<td>banked data</td>
</tr>
<tr>
<td>31 0</td>
<td></td>
</tr>
<tr>
<td>BD2</td>
<td>banked data</td>
</tr>
<tr>
<td>31 0</td>
<td></td>
</tr>
<tr>
<td>BD3</td>
<td>banked data</td>
</tr>
</tbody>
</table>

**Configurations**
- Included in all implementations.

**Attributes**
- BD0-BD3 are four 32-bit read/write registers.

**Field descriptions**

The BD0-BD3 bit assignments are:

- **Banked data, BD0-BD3 bits[31:0]**
  - Data values for the current transfer.
  - See *Accessing BD0-BD3* for more information about BD register accesses.

**Accessing BD0-BD3**

BD0-BD3 can be accessed from the MEM-AP register space.
If the Large Physical Address Extension is not implemented, BD0-BD3 can be accessed at the following offsets:

<table>
<thead>
<tr>
<th>Register</th>
<th>Offset</th>
<th>Memory Address that is accessed</th>
<th>Word Accessa</th>
<th>Doubleword Accessb</th>
</tr>
</thead>
<tbody>
<tr>
<td>BD1</td>
<td>0x14</td>
<td>(TAR[31:4] &lt;&lt; 4) + 0x4</td>
<td>TAR[31:4] &lt;&lt; 4, accessed second</td>
<td></td>
</tr>
<tr>
<td>BD2</td>
<td>0x18</td>
<td>(TAR[31:4] &lt;&lt; 4) + 0x8</td>
<td>TAR[31:4] &lt;&lt; 4 + 0x8, accessed first</td>
<td></td>
</tr>
<tr>
<td>BD3</td>
<td>0x1C</td>
<td>(TAR[31:4] &lt;&lt; 4) + 0xC</td>
<td>TAR[31:4] &lt;&lt; 4 + 0x8, accessed second</td>
<td></td>
</tr>
</tbody>
</table>

An access to a Banked Data register initiates an access to the memory address shown in the table. The AP access does not complete until the memory access has completed.

If the Large Physical Address Extension is implemented, BD0-BD3 can be accessed at the following offsets:

<table>
<thead>
<tr>
<th>Register</th>
<th>Offset</th>
<th>Memory Address that is accessed</th>
<th>Word Accessa</th>
<th>Doubleword Accessb</th>
</tr>
</thead>
<tbody>
<tr>
<td>BD1</td>
<td>0x14</td>
<td>(TAR[63:4] &lt;&lt; 4) + 0x4</td>
<td>TAR[63:4] &lt;&lt; 4, accessed second</td>
<td></td>
</tr>
<tr>
<td>BD2</td>
<td>0x18</td>
<td>(TAR[63:4] &lt;&lt; 4) + 0x8</td>
<td>TAR[63:4] &lt;&lt; 4 + 0x8, accessed first</td>
<td></td>
</tr>
<tr>
<td>BD3</td>
<td>0x1C</td>
<td>(TAR[63:4] &lt;&lt; 4) + 0xC</td>
<td>TAR[63:4] &lt;&lt; 4 + 0x8, accessed second</td>
<td></td>
</tr>
</tbody>
</table>

a. Bits[1:0] of the address are always 0b00.
b. Bits[2:0] of the address are always 0b000.

An access to a Banked Data register initiates an access to the memory address shown in the table. The AP access does not complete until the memory access has completed.

If the access size specified in CSW.Size is doubleword, the lower-numbered register holds the least significant word, and the higher-numbered register holds the most significant word. To access a value, a debugger must access both registers of the pair making up the doubleword, where the lower-numbered register is accessed first.

For example, if the Large Physical Address Extension is implemented, to read the doubleword value at (TAR[63:4] << 4), a debugger must:

1. Read BD0, to obtain bits[31:0] of the doubleword.
2. Read BD1, to obtain bits[63:32] of the doubleword.

When CSW.Size specifies doubleword access size, the following restrictions apply to the two required BD register accesses:

- The effect of mixing reads and writes in the sequence is UNPREDICTABLE.
- If CSW is accessed in the middle of the sequence, the following behavior is IMPLEMENTATION DEFINED:
  - Whether the CSW access is successful.
  - Whether the CSW access results in an error response from the AP.
- If CSW is accessed in the middle of the sequence, that sequence is terminated, and the next access to a BD register is the first access of a new sequence.
  If a write sequence is terminated, no memory write is initiated.
- The effect of not accessing the appropriate register first is UNPREDICTABLE.
• After accessing the first BD register of a pair, the effect of accessing any MEM-AP register other than CSW or the second BD register of the pair is UNPREDICTABLE. Examples of sequences that lead to an UNPREDICTABLE result include:
  — Accessing BD1 and then accessing BD2.
  — Two consecutive accesses to the same BD register.
C2.6.3 CFG, Configuration register

The CFG characteristics are:

Purpose

CFG indicates whether the MEM-AP implementation includes the Large Data and Large Physical Address Extensions.

Usage constraints

CFG is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
</tr>
</tbody>
</table>

Configurations

CFG is included in all implementations.

Attributes

CFG is a 32-bit read-only register.

Field descriptions

The CFG bit assignments are:

<table>
<thead>
<tr>
<th>Bits[31:3]</th>
<th>Reserved, RES0.</th>
</tr>
</thead>
<tbody>
<tr>
<td>31 0</td>
<td></td>
</tr>
</tbody>
</table>

LD, bit[2]

Large data. This bit indicates whether the MEM-AP implementation includes the Large Data Extension, which provides support for data items larger than 32-bits. LD has one of the following values:

0b0 The implementation does not support data items that are larger than 32 bits.
0b1 The implementation includes the Large Data Extension, and supports data items larger than 32 bits.

For more information, see MEM-AP Large Data Extension on page C2-163.

Regardless of the value of the LD field, the MEM-AP must support word-size data items, and might support smaller data items. See also CSW.Size.

LA, bit[1]

Long address. This field indicates whether the MEM-AP implementation includes the Large Physical Address Extension, which supports physical addresses of more than 32-bits. LA has one of the following values:

0b0 The implementation support only physical addresses of 32 bits or smaller.
Memory locations for the TAR and BASE registers, which are at offsets 0x08 and 0xF0 in the MEM-AP register map, are reserved.
0b1 The implementation supports physical addresses with more than 32 bits:
• The TAR is a 64-bit register, at offsets 0x04 and 0x08 in the MEM-AP register map.
• The BASE register is a 64-bit register, at offsets 0xF8 and 0xF0 in the MEM-AP register map.

For more information, see MEM-AP Large Physical Address Extension on page C2-163.

BE, bit[0]

Big-endian. ADIv5.2 obsoletes support for big-endian MEM-AP, and this bit must RAZ. For more information, see Big-endian support on page C2-157.
Accessing CFG

CFG can be accessed from the MEM-AP register space:

<table>
<thead>
<tr>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xF4</td>
</tr>
</tbody>
</table>
C2.6.4 CSW, Control/Status Word register

The CSW register characteristics are:

**Purpose**

CSW configures and controls accesses through the MEM-AP to or from a connected memory system.

**Usage constraints**

Some of the fields are read-only or IMPLEMENTATION DEFINED.

CSW as a whole is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RW</td>
</tr>
</tbody>
</table>

**Configurations**

CSW is included in all MEM-AP implementations.

**Attributes**

CSW is a 32-bit read/write register.

**Field descriptions**

The CSW bit assignments are:

<table>
<thead>
<tr>
<th>31 30 28 27 24 23 22 16 15 12 11 8 7 6 5 4 3 2 0</th>
</tr>
</thead>
<tbody>
<tr>
<td>PROT</td>
</tr>
</tbody>
</table>

**DbgSwEnable, bit[31]**

Debug software access enable.

This field is optional. If not implemented, it is RAZ.

If implemented, it has one of the following values:

- 0b0: Debug software access is disabled. If DeviceEn is 0b0, DbgSwEnable must be ignored and treated as one.
- 0b1: Debug software access is enabled.

The use of this field is IMPLEMENTATION DEFINED, see Software access control on page C2-161.

**Prot, bits[30:24]**

Used with the Type field to define the bus access protection control.

A debugger can use these fields to specify flags for a debug access. The permitted values and their significance are IMPLEMENTATION DEFINED, and depend on the underlying bus architecture. For more information, see Implementing a MEM-AP on page C2-162.

This field is optional. If not implemented, it is RES0.

**SPIDEN, bit[23]**

Secure Privileged Debug Enabled. This field has one of the following values:

- 0b0: Secure access is disabled.
- 0b1: Secure access is enabled.

This field is optional, and read-only. If not implemented, it is RES0.
Bits[22:16]
Reserved, RES0.

Type, bits[15:12]
Used with the Prot field to define the bus access protection control. A debugger can use these fields to specify flags for a debug access. The permitted values and their significance are IMPLEMENTATION DEFINED, and depend on the underlying bus architecture. For more information, see Implementing a MEM-AP on page C2-162. This field is optional. If not implemented, it is RES0.

Mode, bits[11:8]
Mode of operation of the MEM-AP. This field has one of the following values:
0b0000 Basic mode.
0b0001 Barrier support enabled. For more information, see MEM-AP Barrier Operation Extension on page C2-163.
Other Reserved.
The set of supported modes is IMPLEMENTATION DEFINED. If the implementation supports only one mode, this field can be RO.
If this field is RW, the reset value of this field is UNKNOWN.

TrInProg, bit[7]
Transfer in progress. This field has one of the following values:
0 The connection to the memory system is idle.
1 A transfer is in progress on the connection to the memory system.
After an ABORT operation, debug software can read this bit to check whether the aborted transaction completed.

DeviceEn, bit[6]
Device enabled.
This field has one of the following values:
0 The MEM-AP is not enabled.
1 Transactions can be issued through the MEM-AP.
This bit corresponds to the value of the DEVICEEN signal, which is a control input to the DAP. If DEVICEEN is not implemented this bit is RAO. See also Enabling access to the connected debug device or memory system on page C2-152. This field is read-only.

AddrInc, bits[5:4]
Address auto-increment and packing mode. This field controls whether the access address increments automatically on read and write data accesses through the DRW register. For more information, see Auto-incrementing the Transfer Address Register (TAR) on page C2-152 and Packed transfers on page C2-158. The reset value of this field is UNKNOWN.

Bit[3]
Reserved, RES0.

Size, bits[2:0]
The size of the data type that is used to access the MEM-AP, as shown in Table C2-7 on page C2-178.
It is IMPLEMENTATION DEFINED whether a MEM-AP supports access sizes other than 32-bits, and whether the Size field is RW or RO:

- If other sizes are supported, the Size field is RW, and the field indicates the size of the accesses to perform. When this field is RW, its reset value is UNKNOWN.
- If other sizes are not supported, this field is RO and it reads as 0b010 to indicate that only 32-bit accesses are supported.

<table>
<thead>
<tr>
<th>Size Field</th>
<th>Data Type</th>
<th>Supported</th>
</tr>
</thead>
<tbody>
<tr>
<td>0b000</td>
<td>Byte (8-bits)</td>
<td>IMPLEMENTATION DEFINED</td>
</tr>
<tr>
<td>0b001</td>
<td>Halfword (16-bits)</td>
<td>IMPLEMENTATION DEFINED</td>
</tr>
<tr>
<td>0b010</td>
<td>Word (32-bits)</td>
<td>Yes(^a)</td>
</tr>
<tr>
<td>0b011(^b)</td>
<td>Doubleword (64-bits)</td>
<td>IMPLEMENTATION DEFINED</td>
</tr>
<tr>
<td>0b100(^b)</td>
<td>128-bits</td>
<td>IMPLEMENTATION DEFINED</td>
</tr>
<tr>
<td>0b101(^b)</td>
<td>256-bits</td>
<td>IMPLEMENTATION DEFINED</td>
</tr>
<tr>
<td>0b110 - 0b111</td>
<td>Reserved</td>
<td>-</td>
</tr>
</tbody>
</table>

\(^a\) On a MEM-AP implementation that does not support access sizes other than word, the Size field is read-only, and always returns the value 0b010.

\(^b\) Supported by the MEM-AP Large Data Extension, see MEM-AP Large Data Extension on page C2-163. The following usage constraints apply:
- If the extension is not implemented, this value is reserved.
- If a reserved value, or a value corresponding to an unsupported access size, is written to this field, reading the field returns the value corresponding to a supported size, and the MEM-AP behaves according to the return value.

### Accessing CSW

CSW can be accessed from the MEM-AP register space:

<table>
<thead>
<tr>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
</tr>
</tbody>
</table>
C2.6.5 DRW, Data Read/Write register

The DRW characteristics are:

Purpose

DRW maps the value that is passed in an AP access directly to one or more memory accesses at the address that is specified in the TAR.

The value depends on the access mode:

• In write mode, DRW holds the value to write for the current transfer to the address specified in the TAR.
• In read mode, DRW holds the value that is read in the current transfer from the address that is specified in the TAR.

The AP access does not complete until the memory access, or accesses, complete.

Usage constraints

MEM-AP implementations that include the Large Data Extension enable accessing values with a data type that is larger than the size of DRW, which requires multiple access to DRW to complete a single memory access, as shown in Table C2-8.

Memory accesses that involve multiple DRW accesses have the following limitations:

• The effect of mixing reads and writes in the sequence is UNPREDICTABLE.
• An access to CSW in the middle of a sequence terminates that sequence. The next access to DRW is the first access of a new sequence. If a write sequence is terminated, no memory write is initiated.
• After the first DRW access of the sequence, the effect of accessing any MEM-AP register other than the CSW or DRW is UNPREDICTABLE.
• Depending on the value of CSW.AddrInc, the TAR might be incremented after each DRW access. See Auto-incrementing the Transfer Address Register (TAR) on page C2-152.

Table C2-8 DRW access behavior for different data type sizes

<table>
<thead>
<tr>
<th>Size of data type</th>
<th>CSW.Size</th>
<th>Required number of DRW accesses</th>
<th>Read behavior</th>
<th>Write behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td>8 bits(^{a,b})</td>
<td>0b000</td>
<td>1</td>
<td>Each read initiates a memory access and returns the value to be read using byte lanes.</td>
<td>Each write initiates a memory access and writes the value to be written using byte lanes.</td>
</tr>
<tr>
<td>16 bits(^{a,b})</td>
<td>0b001</td>
<td>1</td>
<td>Each read initiates a memory access and returns the value to be read.</td>
<td>Each write initiates a memory access and writes the value to be written.</td>
</tr>
</tbody>
</table>
| 32 bits\(^c\)   | 0b010    | 1                               | On first read:  
• Initiate a memory access.  
• Return the least significant 32-bit word of the value being read.  
On subsequent reads:  
• Do not initiate another memory access.  
• Return the next 32-bit word of the value being read.  
On the first read, the AP access does not complete until the memory access completes. | On writes before the last write:  
• Specifies the next 32-bit word of the value to be written, starting from the least significant word.  
• Do not initiate a memory access.  
On last write:  
• Specify the most significant 32-bit word of the value to be written.  
• Initiate a memory access.  
On the last write, the AP access does not complete until the memory access completes. |
| 64 bits\(^d\)   | 0b011    | 2                               | On first read:  
• Initiate a memory access.  
• Return the least significant 32-bit word of the value being read.  
On subsequent reads:  
• Do not initiate another memory access.  
• Return the next 32-bit word of the value being read.  
On the first read, the AP access does not complete until the memory access completes. | On writes before the last write:  
• Specifies the next 32-bit word of the value to be written, starting from the least significant word.  
• Do not initiate a memory access.  
On last write:  
• Specify the most significant 32-bit word of the value to be written.  
• Initiate a memory access.  
On the last write, the AP access does not complete until the memory access completes. |
| 128 bits\(^d\)  | 0b100    | 4                               | On writes before the last write:  
• Specifies the next 32-bit word of the value to be written, starting from the least significant word.  
• Do not initiate a memory access.  
On last write:  
• Specify the most significant 32-bit word of the value to be written.  
• Initiate a memory access.  
On the last write, the AP access does not complete until the memory access completes. |
| 256 bits\(^d\)  | 0b101    | 8                               | On writes before the last write:  
• Specifies the next 32-bit word of the value to be written, starting from the least significant word.  
• Do not initiate a memory access.  
On last write:  
• Specify the most significant 32-bit word of the value to be written.  
• Initiate a memory access.  
On the last write, the AP access does not complete until the memory access completes. |

\(^{a}\) Support is IMPLEMENTATION DEFINED.
b. A single access to the DRW register might result in multiple memory accesses, depending on the values of CSW.AddrInc. See Packed transfers on page C2-158.

c. Supported by all MEM-AP implementations.

d. Might be supported by MEM-AP applications that include the Large Data Extension. Support is IMPLEMENTATION DEFINED.

DRW is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RW</td>
</tr>
</tbody>
</table>

Configurations

The MEM-AP Large Data Extension, described in MEM-AP Large Data Extension on page C2-163, modifies the behavior of this register for accesses with CSW.Size set to a value larger than \(0b10\).

Attributes

DRW is a 32-bit MEM-AP register.

Field descriptions

The DRW bit assignments are:

<table>
<thead>
<tr>
<th>31</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Data</td>
</tr>
</tbody>
</table>

Data, bits[31:0]

Data value of the current transfer.

Accessing DRW

DRW can be accessed from the MEM-AP register space:

<table>
<thead>
<tr>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xC</td>
</tr>
</tbody>
</table>
C2.6.6 MBT, Memory Barrier Transfer register

The MBT register characteristics are:

**Purpose**

MBT generates a barrier operation on the bus.

**Usage constraints**

If CSW.Mode has a value other than 0b0001, writes to MBT are ignored.

MBT is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>IMPLEMENTATION DEFINED</td>
</tr>
</tbody>
</table>

**Configurations**

If the Barrier Operation Extension is not implemented, MBT is RES0.

MBT is implemented only if the MEM-AP implementation includes the MEM-AP Barrier Operation Extension, see [MEM-AP Barrier Operation Extension on page C2-163](#).

**Attributes**

MBT is a 32-bit MEM-AP register.

Other properties of the register are IMPLEMENTATION DEFINED.

**Field descriptions**

The MBT bit assignments are:

<table>
<thead>
<tr>
<th>Bits[31:0]</th>
</tr>
</thead>
<tbody>
<tr>
<td>IMPLEMENTATION DEFINED</td>
</tr>
</tbody>
</table>

**Accessing MBT**

MBT can be accessed from the MEM-AP register space:

<table>
<thead>
<tr>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x20</td>
</tr>
</tbody>
</table>

C2.6.7 TAR, Transfer Address Register

The TAR characteristics are:

**Purpose**

TAR holds the memory address to be accessed through AP accesses.

--- **Note**

The address that is held in TAR represents an address in the memory system to which the MEM-AP is connected. It is not an address within the MEM-AP itself.
Configurations and Usage constraints

When using the DRW, TAR specifies the memory address to access:

- If the MEM-AP does not support accesses smaller than word, TAR[1:0] is RES0.
- The contents of TAR can be incremented automatically on a successful DRW access, see Auto-incrementing the Transfer Address Register (TAR) on page C2-152.

When accessing memory through BD0-BD3, Banked Data registers on page C2-170, bits [3:0] of TAR are ignored, and TAR[63:4] or TAR[31:4] specifies the base address of the 16-byte block of memory that can be accessed.

The size and reset value of TAR are as follows:

<table>
<thead>
<tr>
<th>Large Physical Address Extension</th>
<th>TAR Size</th>
<th>Reset Value</th>
<th>Least significant word (offset 0x04)</th>
<th>Most significant word (offset 0x08)</th>
</tr>
</thead>
<tbody>
<tr>
<td>No</td>
<td>32 bits</td>
<td>UNKNOWN</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Yes</td>
<td>64 bits</td>
<td>UNKNOWN</td>
<td>0x000000000</td>
<td></td>
</tr>
</tbody>
</table>

The register is accessible as follows:

| Default | RW |

Attributes

TAR is a 32-bit or 64-bit MEM-AP register.

Field descriptions

The TAR bit assignments are:

Address[63:32], bits[31:0] of the register word at offset 0x08

- Most significant word of the memory address for the current transfer.
- If the MEM-AP implementation does not include the Large Physical Address Extension, this field is RES0.

Address[31:0], bits[31:0] of the register word at offset 0x04

- Least significant word of the memory address for the current transfer.
### Accessing TAR

TAR can be accessed from the MEM-AP register space:

<table>
<thead>
<tr>
<th>Offset</th>
<th>Least significant byte</th>
<th>Most significant byte</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x04</td>
<td>0x00</td>
<td>0x08</td>
<td></td>
</tr>
</tbody>
</table>

*a. Applicable only to MEM-AP implementations with a Large Physical Address Extension.*
C2 The Memory Access Port (MEM-AP)
C2.6 MEM-AP register descriptions
Chapter C3
The JTAG Access Port (JTAG-AP)

This chapter describes the implementation of the JTAG Access Port (JTAG-AP), and how a JTAG-AP provides a Debug Port connection to one or more JTAG components. The JTAG-AP is an optional component of a Debug Access Port.

This chapter contains the following sections:
• About the JTAG-AP on page C3-186.
• Operation of the JTAG-AP on page C3-190.
• The JTAG Engine Byte Command Protocol on page C3-193.
• JTAG-AP register summary on page C3-200.
• JTAG-AP register descriptions on page C3-201.

Note

Chapter C1 About the AP gives additional information about APs.
## C3.1 About the JTAG-AP

The JTAG Access Port is an optional component of a Debug Access Port (DAP). It enables up to eight legacy IEEE 1149.1 JTAG scan chains to be connected to the DAP. Each scan chain can contain any number of TAPs, however ARM recommends that only one TAP is connected to each scan chain.

An external debugger accesses a JTAG component, which is connected to a JTAG-AP, through a JTAG scan chain. The debugger accesses this scan chain using APACC accesses to registers in the JTAG-AP. A debugger also has to access JTAG-AP registers to control the JTAG-AP, or to obtain status or identification information from the JTAG-AP.

### C3.1.1 Selecting and accessing the JTAG-AP

Figure C3-1 shows the implementation of a JTAG-AP, and how the JTAG-AP connects the DP to up to eight JTAG devices. APACC accesses to the DP are passed to the JTAG-AP.

The method of selecting an AP, and selecting a specific register within the selected AP, is the same for MEM-APs and JTAG-APs, and is summarized in Selecting and accessing an AP on page C1-143.

---

**Figure C3-1 JTAG-AP connecting the DP to JTAG devices**

---
C3.1.2  Logical structure of the JTAG-AP

A JTAG-AP:
— Interprets a sequence of command bytes from the Command FIFO.
— Drives standard JTAG signals to the JTAG Port Multiplexer.
— Receives the TDO signal from the Port Multiplexer.
— Generates a response and passes it to the Response FIFO.

A JTAG-AP comprises:

• The JTAG Port Multiplexer, which multiplexes up to eight JTAG ports to the JTAG Engine. In addition to forwarding the standard JTAG signals to and from each port, it provides control and status signals for each port.

  — Note ————
  The Port Multiplexer also supports the RTCK (return clock) extension to the JTAG protocol, enabling the JTAG scan chains to be self-timed. The JTAG signals from and to the JTAG-AP are asynchronous to the Debug Port signals.

• Byte Command and Response FIFOs, which enable efficient use of the JTAG Engine.

  The following rules apply to the FIFO sizes:
  — The Response FIFO must be 7 bytes deep.
  — The Command FIFO must be at least 4 bytes deep. Although the Command FIFO can be up to 7 bytes deep, there is unlikely to be any advantage in having a Command FIFO that is larger than 4 bytes.

• The JTAG-AP registers, which can be divided into three groups:
  — An Identification Register.
  — Control and status registers.
  — FIFO access registers.

  Figure C3-2 on page C3-188 shows the JTAG-AP structure.
Figure C3-2 Structure of the JTAG Access Port (JTAG-AP)
### C3.1.3 JTAG port signals

The signal bundle between the JTAG Port Multiplexer and each implemented JTAG port includes:

- The standard IEEE 1149.1 JTAG signals.
- The non-IEEE 1149.1 extension RTCK signal.
- Port control and status signals.

Table C3-1 gives the full signal list, which applies to each implemented port.

<table>
<thead>
<tr>
<th>Signal</th>
<th>Direction</th>
<th>Description</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>TCK</td>
<td>Out</td>
<td>Test Clock</td>
<td>JTAG IEEE 1149.1 standard signals.</td>
</tr>
<tr>
<td>TMS</td>
<td>Out</td>
<td>Test Mode Select</td>
<td></td>
</tr>
<tr>
<td>TDI</td>
<td>Out</td>
<td>Test Data In</td>
<td></td>
</tr>
<tr>
<td>TDO</td>
<td>In</td>
<td>Test Data Out</td>
<td></td>
</tr>
<tr>
<td>TRST*</td>
<td>Out</td>
<td>Test Reset</td>
<td>Active LOW JTAG IEEE 1149.1 standard signal.</td>
</tr>
<tr>
<td>RTCK</td>
<td>In</td>
<td>Return Clock</td>
<td>JTAG extension signal, not specified by IEEE 1149.1.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>If the connected JTAG device has no Return Clock, RTCK must be</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>synthesized for the port.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Implementation of the RTCK signal is</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>IMPLEMENTATION DEFINED.</td>
</tr>
<tr>
<td>nSRSTOUT</td>
<td>Out</td>
<td>Subsystem Reset</td>
<td>Active LOW.</td>
</tr>
<tr>
<td>SRSTCONNECTED</td>
<td>In</td>
<td>Subsystem Reset Connected</td>
<td>Tie-off configuration signals to the JTAG Port Multiplexer.</td>
</tr>
<tr>
<td>PORTCONNECTED</td>
<td>In</td>
<td>Port Connected</td>
<td>Can be deasserted by the JTAG subsystem, for example when the connected TAP powers down.</td>
</tr>
<tr>
<td>PORTENABLED</td>
<td>In</td>
<td>Port Enabled</td>
<td></td>
</tr>
</tbody>
</table>

a. Signal directions are given relative to the JTAG Port Multiplexer in the JTAG-AP.
C3.2 Operation of the JTAG-AP

The JTAG-AP communicates with the device using standard JTAG signals and scan chains. This operation is controlled by the JTAG Engine. The Engine includes a serializer that takes TDI data out of the Command FIFO and returns TDO data to the Response FIFO, see Figure C3-2 on page C3-188.

The external debugger:

1. Encodes JTAG commands and data into the JTAG Engine Byte Command Protocol, which is described in The JTAG Engine Byte Command Protocol on page C3-193.
2. Writes to the BWFIFO registers to transfer the encoded JTAG Engine commands and data to the JTAG Command FIFO.
3. Reads from the BRFIFO registers to collect JTAG TDO in response to the encoded JTAG Engine commands.
4. Decodes the actual TDO data from the response data.

The JTAG Engine provides the connection between stages 2 and 3 of this process.

--- Note ---

The JTAG-AP can connect to up to eight JTAG devices. The debugger must write to the PSEL register to select which JTAG port or ports the JTAG Port Multiplexer connects to the JTAG Engine.

---

The debugger can start reading data from TDO before completing writing data to TDI, as long as it has completed writing the command header. A debugger can take advantage of this principle to exchange data that exceeds the size of the command and response FIFOs.

For example:

1. The debugger writes two bytes to BWFIFO2, to specify:
   a. A TDI_TDO scan, with 64 bits of TDI data.
   b. The TDO data is to be returned to the debugger.
2. The debugger writes a word to BWFIFO4, containing the first 32 bits of TDI data.
3. The debugger reads a word from BRFIFO4, to obtain the first 32 bits of TDO data.
4. The debugger writes another word to BWFIFO4, with the next 32 bits of TDI data.
5. The debugger reads another word from BRFIFO4, to obtain the next 32 bits of TDO data.

This method provides an efficient encapsulation of the JTAG scan chain.

If the requested data is not available, a read of BRFIFO stalls, as described in Stalling accesses on page C3-191.

To reduce the number of stalls that are caused by AP accesses to devices with a slow clock, the debugger can write several bytes of TDI data before attempting to read the first byte of TDO data.

Operation of the JTAG-AP is described in more detail in The JTAG Engine Byte Command Protocol on page C3-193.
C3.2 Operation of the JTAG-AP

C3.2.1 Stalling accesses

AP accesses to JTAG engine FIFOs can be stalled.

As shown in Figure C3-2 on page C3-188, the JTAG Engine FIFOs comprise the following registers:

- The Byte Response FIFO Registers, BRFIFO1 to BRFIFO4.
- The Byte Command FIFO Registers, BWFIFO1 to BWFIFO4.

The JTAG Engine FIFOs are described in BxFIFO1-BxFIFO4, and can be used to access the JTAG state machine and JTAG scan chains as described in The JTAG Engine Byte Command Protocol on page C3-193.

AP accesses to JTAG-AP registers that do not access the JTAG Engine FIFOs cannot be stalled. As shown in Figure C3-2 on page C3-188, this rule applies to the following registers:

- CSW.
- PSEL.
- PSTA.
- IDR.

A JTAG-AP access can stall in the following situations:

Stalling read accesses

The JTAG-AP can stall read accesses to the Byte Response FIFO Registers, BRFIFO1 to BRFIFO4.

Depending which of these registers is targeted, a single register read transfers between one and four bytes of data from the byte Response FIFO. The register access stalls if the FIFO does not contain enough data. For example, if the Response FIFO only contains two bytes of data and a read access is performed to BRFIFO4 to transfer four bytes of data, the access stalls and remains stalled until there are four bytes of data available in the Response FIFO.

CSW.RFIFOCNT can be read to find the number of bytes of data that are available in the Response FIFO. A read of the CSW always completes immediately.

Stalling write accesses

The JTAG-AP can stall write accesses to the Byte Command FIFO Registers, BWFIFO1 to BWFIFO4.

Depending which of these registers is targeted, a single register write transfers between one and four bytes of data into the byte Command FIFO. The register access stalls if the FIFO does not contain enough free space to accept all the write data. For example, if the Command FIFO only has one byte free and a write access to BWFIFO3 is performed to transfer three bytes into the Command FIFO, the access stalls and remains stalled until the Command FIFO is able to accept the three bytes of data.

CSW.WFIFOCNT can be read to find the number of command bytes in the Command FIFO that are waiting to be processed by the JTAG Engine, which can be used to calculate the number of free bytes in the FIFO. A read of the CSW always completes immediately.

C3.2.2 Resetting connected JTAG devices or subsystems

Resets of JTAG devices or subsystems that are connected to the JTAG-AP can be triggered with the following signals:

- The TRST* signal for JTAG Test Resets.
- The nSRSTOUT signal for subsystem resets.

These signals are controlled by the CSW.TRST_OUT and CSW.SRST_OUT fields. A JTAG test reset might have to be clocked out for several TCK cycles with TMS HIGH to generate the reset. For more information see CSW, Control/Status Word Register on page C3-206.
C3.2.3 Pushed transaction and transaction counter support

A JTAG-AP supports pushed transactions and sequences of transactions to the following registers only:

- PSTA.
- BxFIFO1-BxFIFO4.

For more information, see:

- Pushed-compare and pushed-verify operations on page B1-44.
- The transaction counter on page B1-43.
C3.3 The JTAG Engine Byte Command Protocol

All JTAG commands, including TMS and TDI data, are written to the JTAG-AP Command FIFO through the interface that is provided by the four Byte Write FIFO Registers, BWFIFO1 to BWFIFO4. To provide high command packing, the JTAG commands are encoded as a byte protocol, and depending on which of the Byte Write FIFO registers is written to, up to four bytes can be written to the FIFO in a single operation. See BWFIFO1-BWFIFO4, Byte FIFO registers for write access on page C3-203.

Data from the TDO signal from the JTAG Port Multiplexor is transferred to the JTAG-AP Response FIFO. The four Byte Read FIFO Registers provide an interface to the Response FIFO. See BRFIFO1-BRFIFO4, Byte FIFO registers for read access on page C3-201.

In the JTAG Engine Byte Command Protocol, all commands are one byte (8-bits). Table C3-2 summarizes the commands, and the following sections describe them in more detail. Where appropriate, the command descriptions also describe the TDO data that is produced by the command, and how it is encoded in the Byte Read FIFOs.

### Table C3-2 Summary of JTAG Engine Byte Command Protocol

<table>
<thead>
<tr>
<th>Bits of the Command byte</th>
<th>Opcode</th>
</tr>
</thead>
<tbody>
<tr>
<td>[7] [6] [5] [4] [3] [2] [1] [0]</td>
<td></td>
</tr>
<tr>
<td>0</td>
<td>Opcode payload</td>
</tr>
<tr>
<td>1 0 0</td>
<td>Opcode payload</td>
</tr>
<tr>
<td>1 0 1</td>
<td>X X X X X X</td>
</tr>
<tr>
<td>1 1 0</td>
<td>X X X X X X</td>
</tr>
<tr>
<td>1 1 1</td>
<td>X X X X X X</td>
</tr>
</tbody>
</table>

#### C3.3.1 The encoding of the TMS packet

The TMS packet is a single byte. The payload of the packet holds:
- Between one and five data bits to be sent on TMS.
- An indication of whether TDI is held at 0 or at 1 while these bits are sent.

While a TMS packet is being executed, no response is captured from TDO. The normal use of TMS packets is to move around the JTAG state machine. See The Debug TAP State Machine (DBGTAPSM) on page B3-88.

Table C3-3 shows the possible encodings of a TMS packet.

### Table C3-3 TMS packet encodings

<table>
<thead>
<tr>
<th>Command byte</th>
<th>Bits of TMS data</th>
</tr>
</thead>
<tbody>
<tr>
<td>[7] [6] [5] [4] [3] [2] [1] [0]</td>
<td></td>
</tr>
<tr>
<td>0 TDI 0 0 1 TMS[2] TMS[1] TMS[0]</td>
<td>3</td>
</tr>
<tr>
<td>0 TDI 0 0 0 1 TMS[1] TMS[0]</td>
<td>2</td>
</tr>
<tr>
<td>0 TDI 0 0 0 0 1 TMS[0]</td>
<td>1</td>
</tr>
</tbody>
</table>

When the JTAG Engine decodes a TMS packet, TDI is held at the value indicated by bit [6] while all the TMS data bits are sent. If you have to send TMS bits with different TDI values, you must use multiple TMS packets.
The TMS data bits are sent LSB first, so in each row of Table C3-3 on page C3-193, TMS[0] is the first bit to be sent.

For example, the TMS packet that is used to send the TMS bit sequence 1-1-0-1, while keeping TDI at 1, is shown in Figure C3-3. As the diagram shows, this sequence of TMS signals takes four TCK cycles.

![Figure C3-3 TMS packet example with TDI held at 1](image)

To send TMS bit sequence 1-0, while keeping TDI at 0, the TMS packet is as shown in Figure C3-4. As shown in the diagram, this sequence of TMS signals takes two TCK cycles.

![Figure C3-4 TMS packet example with TDI held at 0](image)

### C3.3.2 The encoding of the TDI_TDO packet

A TDI_TDO packet is a multi-byte packet that is at least two bytes long. It comprises:

- The TDI_TDO opcode byte.
- A second byte, that contains:
  - For short packets, of fewer than seven TDI bits, the packed TDI bits.
  - Otherwise, the length of the packet.
- If required, between one and sixteen extra bytes containing the TDI bits.

The following subsections describe these bytes.

#### The TDI_TDO opcode byte, the first byte of the packet

This byte is the packet header. It indicates the start of a TDI_TDO packet, and contains information about the command subtype. Figure C3-5 shows the format of this byte.

![Figure C3-5 TDI_TDO first byte (opcode) format](image)
Bits [3:0] are control bits that define the TDI_TDO subtype. Table C3-4 describes all the bits of the first byte of the TDI_TDO packet.

Table C3-4 Format of the first byte of TDI_TDO (opcode)

<table>
<thead>
<tr>
<th>Bit</th>
<th>Name</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>[7]</td>
<td>TDI_TDO</td>
<td>0b1</td>
<td>The value of these bits indicates whether this byte is the first byte of a</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>TDI_TDO packet</td>
</tr>
<tr>
<td>[6]</td>
<td></td>
<td>0b0</td>
<td></td>
</tr>
<tr>
<td>[5]</td>
<td></td>
<td>0b0</td>
<td></td>
</tr>
<tr>
<td>[3]</td>
<td>TMS</td>
<td>-</td>
<td><strong>TMS</strong> value to use on the last cycle of the scan:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• 0b0 = <strong>TMS</strong> LOW on last cycle</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• 0b1 = <strong>TMS</strong> HIGH on last cycle</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>For all earlier cycles of the scan:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• If the previous TMS or TDI_TDO packet finished with <strong>TMS</strong> high</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>for the last cycle, it is UNPREDICTABLE whether <strong>TMS</strong> is HIGH or LOW for</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>this scan.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• In all other cases, <strong>TMS</strong> is LOW.</td>
</tr>
<tr>
<td>[2]</td>
<td>RTDO</td>
<td>-</td>
<td><strong>Read TDO.</strong> This bit determines whether <strong>TDO</strong> values returned during</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>the scan are captured and placed in the Response FIFO:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0b0 = Do not capture <strong>TDO</strong></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0b1 = Capture <strong>TDO</strong>.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td><strong>Caution</strong> Do not set this bit to 0b1 if more than one JTAG port is</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>selected and enabled. If you do, the <strong>TDO</strong> values captured are</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>UNKNOWN.</td>
</tr>
<tr>
<td>[1]</td>
<td>TDI</td>
<td>-</td>
<td><strong>TDI</strong> value to use throughout the scan if the UTDI bit is 0b1:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0b0 = hold <strong>TDI</strong> signal LOW throughout the scan</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0b1 = hold <strong>TDI</strong> signal HIGH throughout the scan</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>The value of the TDI bit is ignored if the UTDI is 0b0.</td>
</tr>
<tr>
<td>[0]</td>
<td>UTDI</td>
<td>-</td>
<td><strong>Use TDI bit.</strong> This bit determines whether the TDI bits to be used</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>during the scan are supplied in the other bytes of the TDI_TDO packet, or</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>whether the TDI bit, bit [1], specifies the <strong>TDI</strong> signal to use throughout</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>the scan:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0b0 = <strong>TDI</strong> bits for the scan are supplied in the other bytes of the</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>TDI_TDO packet.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0b1 = **The TDI bit, bit [1], determines the <strong>TDI</strong> signal to use throughout</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>the scan.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>If this bit is 0b1, no TDI data is included in the TDI_TDO packet.</td>
</tr>
</tbody>
</table>

a. Given for bits that have a fixed value for the TDI_TDO first byte.
b. When the Packed format is used for the second byte of the packet, certain bits of that byte are designated as TDI data bits. If UTDI = 0b1, however, the value of these bits is ignored, as described in The TDI_TDO length byte, the second byte of the packet on page C3-196. There is no advantage in using the packed format when UTDI = 0b1, but it is possible to do so.
The TDI_TDO length byte, the second byte of the packet

There are two alternative formats for the second byte of the TDI_TDO packet:

**Normal**

If bit [7] of the TDI_TDO length byte is zero, the byte is in the normal length byte format, and specifies the length of the scan, which can be any value between 1 and 128 bits. Bits [6:0] of the byte give the length in bits of the required scan, minus one, as shown in Figure C3-6.

![Figure C3-6 TDI_TDO second byte (length byte), normal format](image)

When the TDI_TDO length byte is in the normal format:

- If the UTDI bit of the first byte of the TDI_TDO packet is 0b0, the TDI data for the scan is packed into extra bytes of the packet, that follow the length byte. See *The data bytes, the remaining byte or bytes of the packet on page C3-197* for more information.

- If the UTDI bit of the first byte of the TDI_TDO packet is 0b1, no TDI data is required for the scan, and the length byte is the last byte of the packet. If the UTDI bit is 0b1, the TDI_TDO packet is always two bytes long.

See *The TDI_TDO opcode byte, the first byte of the packet on page C3-194* for more information about the UTDI bit.

**Packed**

If bit [7] of the second byte of the TDI_TDO packet is one, the byte is in the packed length byte format, and contains between one and six bits of TDI data:

- The length of the required scan is implied by the data in bits [6:0].

- If the UTDI bit of the first byte of the TDI_TDO packet is 0b0, the TDI data for the scan is packed into the least significant bits of the length byte.

- The second byte is the last byte of the TDI_TDO packet, meaning the packet is two bytes long.

---

**Note**

The packed format of the TDI_TDO length byte can only be used if the required scan contains six bits or less.

Figure C3-7 shows the permitted contents of the length byte when the packed format is used.

![Figure C3-7 TDI_TDO second byte (length byte), packed format](image)

The packed format for the TDI_TDO length byte is summarized in Table C3-5 on page C3-197.
When the TDI_TDO length byte is in the packed format:

- If the UTDI bit of the first byte of the TDI_TDO packet is 0b0, the data that is packed into bits[5:0] of the length byte determines the value of the TDI signal during the scan. Bit[0] of the length byte always holds TDI[0], meaning that this bit determines the TDI signal value for the first TCK cycle of the scan.

- If the UTDI bit of the first byte of the TDI_TDO packet is 0b1, the data that is packed into bits[5:0] of the length byte only indicates the length of the required scan, and does not affect the value of the TDI signal during the scan. For example, if the complete length byte is 0b10001XXX, referring to Figure C3-7 on page C3-196 shows that a scan of 3 bits is required. The TDI signal value, for all three bits, is the TDI value from the first byte of the packet, see Table C3-3 on page C3-193.

See also The TDI_TDO opcode byte, the first byte of the packet on page C3-194.

---

**Note**

The packed format can be used when the UTDI bit in the first byte of the packet is 0b1. However, there is no advantage in using the packed format when UTDI = 0b1, because the normal format is easier to use, and the TDI_TDO packet is two bytes long, whichever format is used.

### The data bytes, the remaining byte or bytes of the packet

If the TDI_TDO opcode byte is 0x00, and the length byte is in the normal format, the TDI_TDO packet is more than two bytes long. In this case:

- Bits[6:0] of the length byte contain the required scan length minus one, in bits.
- The TDI data for the scan is packed into extra bytes of the packet.

The packing of TDI data uses as few bytes as possible, and the least significant bit of TDI data, TDI[0], is always bit[0] of the first data byte. TDI[0] is the TDI signal value for the first TCK cycle of the scan.

The number of data bytes required is the length of the scan divided by eight, rounded up to an integer value. In the last data byte, any bits that are not required for TDI data must be 0b0. For example, a scan of 21 cycles requires three data bytes, giving a total TDI_TDO packet size of five bytes. Figure C3-8 on page C3-198 shows the formatting of the complete TDI_TDO packet for this example.
The bit assignments for the bytes shown in Figure C3-8 are:

**Byte 1, the opcode byte**

- **Bits[7:5]** The TDI_TDO opcode, 0b100.
- **Bit[3]** The TMS bit. A value of 0b1 indicates that TMS must be HIGH for the last cycle of the scan.
- **Bit[2]** The RTDO bit. A value of 0b1 indicates that TDO data must be captured during the scan.

**Byte 2, the length byte**

- **Bit[7]** A value of 0b0 indicates that this length byte is in normal format.
- **Bits[6:0]** The value of ((length of scan) - 1). This field has the value 0b0010100, which is 20, meaning the scan length is 21 bits.

**Bytes 3 and 4, the first and second data bytes**

These bytes contain TDI[15:0], the TDI data for the first 16 cycles of the scan.

**Byte 5, the third data byte**

This byte contains TDI[20:16], the TDI data for the final five cycles of the scan. Any bits that are not required for TDI data must be 0b0, so bits [7:5] = 0b000.

### C3.3.3 Response bytes from a TDI_TDO packet

If the Read TDO (RTDO) bit, which is bit [2] of a TDI_TDO packet header, is 0b1, the value of the TDO signal is captured for each TCK cycle of the scan. This captured TDO data is packed into bytes, and each byte is inserted into the Response FIFO when it is completed.

Figure C3-8 shows a TDI_TDO packet with RTDO = 0b1.

**Note**

If more than one JTAG port is selected and enabled, the returned TDO values are **UNKNOWN**.

The number of bytes of TDO data that is inserted in the Response FIFO is the scan length divided by eight, rounded up to an integer value. When the scan length is not an exact multiple of 8, the last byte of returned data is padded with bits having a value of 0b0.

The scan stalls if the Response FIFO is full when a byte of TDO data is ready for insertion.

Figure C3-9 on page C3-199 shows the formatting of the TDO data bytes transferred to the Response FIFO for a scan of 21 TCK cycles where TDO capture is enabled.
Figure C3-9 TDI_TDO response data formatting example. Scan of 21 TCK cycles

If the RTDO bit is 00, no response bytes are placed in the Response FIFO.

For details about the Read TDO (RTDO) bit, see The TDI_TDO opcode byte, the first byte of the packet on page C3-194.
## JTAG-AP register summary

Table C3-6 shows the memory map of the JTAG-AP registers, and indicates where they are described in detail. Using the Debug Port to access Access Ports on page A1-28 explains how to access AP registers.

All the registers that are listed in Table C3-6 are required in every JTAG-AP implementation.

<table>
<thead>
<tr>
<th>Register</th>
<th>Address</th>
<th>Access</th>
<th>Reset value</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>CSW</td>
<td>0x00</td>
<td>RW</td>
<td>Depends on the state of the connected signals when the register is read(^{a})</td>
<td>CSW</td>
</tr>
<tr>
<td>PSEL</td>
<td>0x04</td>
<td>RW</td>
<td>UNKNOWN PSEL</td>
<td>PSEL</td>
</tr>
<tr>
<td>PSTA</td>
<td>0x08</td>
<td>RW</td>
<td>0x00000000</td>
<td>PSTA</td>
</tr>
<tr>
<td>BxFIFO1-BxFIFO4</td>
<td>0x0C</td>
<td>-</td>
<td>-</td>
<td>Reserved, RES0</td>
</tr>
<tr>
<td></td>
<td>0x10</td>
<td>RO</td>
<td>(^{b})</td>
<td>Read, single entry</td>
</tr>
<tr>
<td></td>
<td></td>
<td>WO</td>
<td>-</td>
<td>Write, single entry</td>
</tr>
<tr>
<td></td>
<td>0x14</td>
<td>RO</td>
<td>(^{b})</td>
<td>Read, two entries</td>
</tr>
<tr>
<td></td>
<td></td>
<td>WO</td>
<td>-</td>
<td>Write, two entries</td>
</tr>
<tr>
<td></td>
<td>0x18</td>
<td>RO</td>
<td>(^{b})</td>
<td>Read, three entries</td>
</tr>
<tr>
<td></td>
<td></td>
<td>WO</td>
<td>-</td>
<td>Write, three entries</td>
</tr>
<tr>
<td></td>
<td>0x1C</td>
<td>RO</td>
<td>(^{b})</td>
<td>Read, four entries</td>
</tr>
<tr>
<td></td>
<td></td>
<td>WO</td>
<td>-</td>
<td>Write, four entries</td>
</tr>
<tr>
<td>IDR</td>
<td>0xFC</td>
<td>RO</td>
<td>IMPLEMENTATION DEFINED</td>
<td>See IDR, Identification Register on page C1-144</td>
</tr>
</tbody>
</table>

\(^{a}\) For details about the reset values of individual fields, see the CSW field descriptions.

\(^{b}\) Accesses to Byte FIFO Read Registers stall until data is available in the FIFO. Therefore they do not have reset values.
C3.5 JTAG-AP register descriptions

This section describes each of the JTAG-AP registers. Table C3-6 on page C3-200 shows these registers, and indexes the full register descriptions in this section. The following subsections describe these registers:

- BRFIFO1-BRFIFO4, Byte FIFO registers for read access.
- BWFIFO1-BWFIFO4, Byte FIFO registers for write access on page C3-203.
- CSW, Control/Status Word Register on page C3-206.
- PSEL, Port Select register on page C3-209.
- PSTA, Port Status Register on page C3-211.

C3.5.1 BRFIFO1-BRFIFO4, Byte FIFO registers for read access

The BRFIFO1-BRFIFO4 characteristics are:

**Purpose**

Enable one, two, three, or four bytes to be read in parallel from the Response FIFO.

<table>
<thead>
<tr>
<th>Register</th>
<th>BRFIFO1</th>
<th>BRFIFO2</th>
<th>BRFIFO3</th>
<th>BRFIFO4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Address</td>
<td>0x10</td>
<td>0x14</td>
<td>0x18</td>
<td>0x1C</td>
</tr>
<tr>
<td>Number of bytes read from Response FIFO</td>
<td>1</td>
<td>2</td>
<td>3</td>
<td>4</td>
</tr>
</tbody>
</table>

The JTAG Engine Byte Command protocol that is used for the commands and responses is described in The JTAG Engine Byte Command Protocol on page C3-193.

**Usage constraints**

BRFIFO1-BRFIFO4 are mapped to the same JTAG-AP register addresses as BWFIFO1-BWFIFO4. The AP accesses the BRFIFO on read operations, and the BWFIFO on write operations.

An AP transaction that reads more responses than are available in the Response FIFO stalls until enough data is available to match the request. To check the number of response bytes that are available, read the CSW.RFIFOCNT field before initiating an AP transaction to read from the Response FIFO.

BRFIFO1-BRFIFO4 are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
</tr>
</tbody>
</table>

**Configurations**

BRFIFO1-BRFIFO4 are included in all implementations.

**Attributes**

BRFIFO1-BRFIFO4 are a set of four 32-bit RO registers.
Field descriptions

The BRFIFO1-BRFIFO4 bit assignments are:

<table>
<thead>
<tr>
<th>BRFIFO1</th>
<th>31</th>
<th>24</th>
<th>23</th>
<th>16</th>
<th>15</th>
<th>8</th>
<th>7</th>
<th>0</th>
<th>0x10</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>RAZ</td>
<td>RAZ</td>
<td>RAZ</td>
<td>Byte 1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>BRFIFO2</th>
<th>31</th>
<th>24</th>
<th>23</th>
<th>16</th>
<th>15</th>
<th>8</th>
<th>7</th>
<th>0</th>
<th>0x14</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>RAZ</td>
<td>RAZ</td>
<td>Byte 2</td>
<td>Byte 1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>BRFIFO3</th>
<th>31</th>
<th>24</th>
<th>23</th>
<th>16</th>
<th>15</th>
<th>8</th>
<th>7</th>
<th>0</th>
<th>0x18</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>RAZ</td>
<td>Byte 3</td>
<td>Byte 2</td>
<td>Byte 1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>BRFIFO4</th>
<th>31</th>
<th>24</th>
<th>23</th>
<th>16</th>
<th>15</th>
<th>8</th>
<th>7</th>
<th>0</th>
<th>0x1C</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Byte 4</td>
<td>Byte 3</td>
<td>Byte 2</td>
<td>Byte 1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

BRFIFO1 bits[31:8]

RAZ

Byte 1, BRFIFO1 bits[7:0]
The first byte to be read from the Response FIFO.

BRFIFO2 bits[31:16]

RAZ

Byte 2, BRFIFO2 bits[15:8]
The second byte to be read from the Response FIFO.

Byte 1, BRFIFO2 bits[7:0]
The first byte to be read from the Response FIFO.

BRFIFO3 bits[31:24]

RAZ

Byte 3, BRFIFO3 bits[23:16]
The third byte to be read from the Response FIFO.

Byte 2, BRFIFO3 bits[15:8]
The second byte to be read from the Response FIFO.

Byte 1, BRFIFO3 bits[7:0]
The first byte to be read from the Response FIFO.

Byte 4, BRFIFO4 bits[31:24]
The fourth byte to be read from the Response FIFO.

Byte 3, BRFIFO4 bits[23:16]
The third byte to be read from the Response FIFO.

Byte 2, BRFIFO4 bits[15:8]
The second byte to be read from the Response FIFO.

Byte 1, BRFIFO4 bits[7:0]
The first byte to be read from the Response FIFO.
Accessing BRFIFO1-BRFIFO4

BRFIFO1-BRFIFO4 can be accessed from the JTAG-AP register space:

<table>
<thead>
<tr>
<th>Access</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>Read</td>
<td>BRFIFO1 0x10</td>
</tr>
</tbody>
</table>

Number of bytes read 1 2 3 4

C3.5.2 BWFIFO1-BWFIFO4, Byte FIFO registers for write access

The BWFIFO1-BWFIFO4 characteristics are:

Purpose

Enable one, two, three, or four bytes to be written in parallel to the Command FIFO.

<table>
<thead>
<tr>
<th>Register</th>
<th>BWFIFO1</th>
<th>BWFIFO2</th>
<th>BWFIFO3</th>
<th>BWFIFO4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Address</td>
<td>0x10</td>
<td>0x14</td>
<td>0x18</td>
<td>0x1C</td>
</tr>
</tbody>
</table>

Number of bytes written to Command FIFO 1 2 3 4

The JTAG Engine Byte Command protocol that is used for the commands and responses is described in *The JTAG Engine Byte Command Protocol* on page C3-193.

Usage constraints

BWFIFO1-BWFIFO4 are mapped to the same JTAG-AP register addresses as BRFIFO1-BRFIFO4. The AP accesses the BRFIFO for read operations, and the BWFIFO for write operations.

An AP transaction that writes more commands than there is space for in the Command FIFO stalls until there is enough space in the Command FIFO. Space in the Command FIFO is freed as commands are executed by the JTAG Engine. To check the number of commands already present in the Command FIFO, read the CSW.WFIFOCNT field before initiating an AP transaction to write to the Command FIFO. The number of additional commands you can write to the FIFO can be calculated by subtracting the return value from the size of the Command FIFO.

BWFIFO1-BWFIFO4 registers are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>WO</td>
</tr>
</tbody>
</table>

Configurations

BWFIFO1-BWFIFO4 are included in all implementations.

Attributes

BWFIFO1-BWFIFO4 are a set of four 32-bit WO registers.
Field descriptions

The BWFIFO1-BWFIFO4 bit assignments are:

- **BWFIFO1 bits[31:8]**
  - RES0
  - Byte 1, BWFIFO1 bits[7:0]
    - The first byte to be written to the Command FIFO.

- **BWFIFO2 bits[31:16]**
  - RES0
  - Byte 2, BWFIFO2 bits[15:8]
    - The second byte to be written to the Command FIFO.
  - Byte 1, BWFIFO2 bits[7:0]
    - The first byte to be written to the Command FIFO.

- **BWFIFO3 bits[31:24]**
  - RES0
  - Byte 3, BWFIFO3 bits[23:16]
    - The third byte to be written to the Command FIFO.
  - Byte 2, BWFIFO3 bits[15:8]
    - The second byte to be written to the Command FIFO.
  - Byte 1, BWFIFO3 bits[7:0]
    - The first byte to be written to the Command FIFO.

- **BWFIFO4 bits[31:24]**
  - Byte 4, BWFIFO4 bits[31:24]
    - The fourth byte to be written to the Command FIFO.
  - Byte 3, BWFIFO4 bits[23:16]
    - The third byte to be written to the Command FIFO.
  - Byte 2, BWFIFO4 bits[15:8]
    - The second byte to be written to the Command FIFO.
  - Byte 1, BWFIFO4 bits[7:0]
    - The first byte to be written to the Command FIFO.
## Accessing BWFIFO1-BWFIFO4

BWFIFO1-BWFIFO4 can be accessed from the JTAG-AP register space:

<table>
<thead>
<tr>
<th>Access</th>
<th>Offset</th>
<th>BWFIFO1</th>
<th>BWFIFO2</th>
<th>BWFIFO3</th>
<th>BWFIFO4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Write</td>
<td></td>
<td>0x10</td>
<td>0x14</td>
<td>0x18</td>
<td>0x1C</td>
</tr>
<tr>
<td>Number of bytes written</td>
<td>1</td>
<td>2</td>
<td>3</td>
<td>4</td>
<td></td>
</tr>
</tbody>
</table>
C3.5.3 CSW, Control/Status Word Register

The CSW register attributes are:

Purpose

CSW register configures and controls transfers through the JTAG interface.

Usage constraints

Several fields in the register are read-only, see Field descriptions. CSW is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th>RW</th>
</tr>
</thead>
</table>

Configurations

CSW is included in all implementations.

Attributes

CSW is a 32-bit read/write register.

Field descriptions

The CSW bit assignments are:

```
31 30 28 27 26 24 23  4  3  2  1  0
RES0
RFIFOCNT
RES0
WFIFOCNT
SERACTV
PORTCONNECTED
SRSTCONNECTED
TRST_OUT
SRST_OUT
```

SERACTV, bit[31]

JTAG Engine active.
This read-only field can have one of the following values:

- 0b0 JTAG Engine is inactive, provided WFIFOCNT is also 0b0.
- 0b1 JTAG Engine is processing commands from the Command FIFO.

--- Note ---
The JTAG Engine is only guaranteed to be inactive if both SERACTV and WFIFOCNT are zero.

The reset value of this field is 0b0.

WFIFOCNT, bits[30:28]

Command FIFO outstanding byte count.
This read-only field returns the number of command bytes held in the Command FIFO that have yet to be processed by the JTAG Engine. The reset value is 0b0000.

Bit[27]

Reserved, RES0.

RFIFOCNT, bits[26:24]

Response FIFO outstanding byte count.
This read-only field returns the number of bytes of response data available in the Response FIFO. The reset value of this field is 0b000.

**Bits[23:4]**

Reserved, RES0.

**PORTCONNECTED, bit[3]**
Selected ports connected.
This read-only field returns the logical AND of the PORTCONNECTED signals from all ports that are currently selected.
The reset value depends on the state of the connected signals when the register is read.

**SRSTCONNECTED, bit[2]**
Selected ports reset connected.
This read-only field returns the logical AND of the SRSTCONNECTED signals from all ports that are currently selected.
The reset value depends on the state of the connected signals when the register is read.

**TRST_OUT, bit[1]**
This field drives the TRST* signal for the currently selected port or ports.

0b0  Deassert TRST* HIGH.
0b1  Assert TRST* LOW.

--- Note ---
The TRST* signal is active LOW: when TRST_OUT has the value 0b1, the TRST* output is LOW.

TRST_OUT does not self-reset: it must be cleared to 0b0 by a software write. The reset value is 0b0.
Although TRST_OUT drives the TRST* signal, writing to this field only causes the field value to change. It might be necessary to clock the devices connected to the selected JTAG ports using TCK, to enable the devices to recognize the change on TRST*:
1. Write 0b1 to the CSW.TRST_OUT bit, to specify that TRST* must be asserted LOW.
2. Drive a sequence of at least five TMS = 1 clocks from the JTAG Engine by issuing the command 0b0111111 to the JTAG Engine. This sequence guarantees that the TAP enters the Test-Logic/Reset state, even if it has no TRST* connection.
3. Write 0b0 to CSW.TRST_OUT, to make sure that the TRST* signal is HIGH on subsequent TCK cycles.
If the JTAG connection is not clocked in this way while TRST* is asserted LOW, some or all TAPs might not reset.

**SRST_OUT, bit[0]**
This field drives the nSRSTOUT signal for the port or ports that are currently selected, and can have one of the following values:

0b0  Deassert nSRSTOUT HIGH.
0b1  Assert nSRSTOUT LOW.

--- Note ---
The nSRSTOUT signal is active LOW: when SRST_OUT has the value 0b1, the nSRSTOUT output is LOW.

SRST_OUT does not self-reset: it must be cleared to 0b0 by a software write. The reset value is 0b0.
Accessing CSW

CSW can be accessed from the JTAG-AP register space:

<table>
<thead>
<tr>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
</tr>
</tbody>
</table>
C3.5.4 PSEL, Port Select register

The PSEL characteristics are:

**Purpose**

PSEL selects one or more JTAG ports to be driven by the JTAG Engine.

**Usage constraints**

You must only write to PSEL when the JTAG Engine is inactive and the WFIFO is empty. Writing to PSEL at any other time has UNPREDICTABLE results, so before writing to PSEL, you must read the JTAG-AP CSW and make sure that the SERACTV and WFIFOCNT fields are both zero.

The reset value of PSEL is UNKNOWN.

PSEL is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th>RW</th>
</tr>
</thead>
</table>

**Configurations**

PSEL is included in all implementations.

**Attributes**

PSEL is a 32-bit read/write register.

**Field descriptions**

The PSEL bit assignments are:

<table>
<thead>
<tr>
<th>Bit</th>
<th>Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>31</td>
<td>RES0</td>
</tr>
<tr>
<td>8:7</td>
<td>PSEL7-PSEL0</td>
</tr>
</tbody>
</table>

**Bits[31:8]**

Reserved, RES0.

**PSEL7-PSEL0, bits[7:0]**

Select control for the JTAG ports.

The possible values of each of the PSEL\(n\) fields are:

- 0b0: JTAG port \(n\) is not selected.
- 0b1: JTAG port \(n\) is selected.

If JTAG port \(n\) is not connected to the JTAG-AP, it is IMPLEMENTATION DEFINED whether PSEL\(n\) is read/write or RES0.

**Note**

JTAG port \(n\) is enabled only if all the following are true:

- The port is connected to the JTAG-AP.
- PSEL\(n\) is 0b1.
- The PORTENABLED signal from the port to the JTAG-AP is asserted HIGH.

When more than one JTAG port is selected in PSEL:

- The same values for TDI, TMS, TRST*, and nSRSTOUT are driven to all selected ports.
• The return values from TDO are unknown.

Using the normal, serially connected model for JTAG, Instruction Register updates are always made in parallel, which enables updating multiple TAPs in parallel. This update mechanism can be useful, for example to provide synchronized behavior.

Because each JTAG port can contain multiple TAPs connected in series, the process for updating TAPs in parallel is as follows:

1. Scan each JTAG port in turn, by selecting each port in turn in the PSEL register. When scanning a port, leave the required TAP in the TAP Exit1 or Exit2 state.
2. When all ports have been scanned in this way, write to PSEL again to select all the required ports.
3. Scan through the TAP Update state. All the TAPs are updated synchronously.

### Accessing PSEL

PSEL can be accessed from the JTAG-AP register space:

<table>
<thead>
<tr>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x04</td>
</tr>
</tbody>
</table>
### C3.5.5 PSTA, Port Status Register

The PSTA register characteristics are:

**Purpose**

PSTA indicates whether a connected and selected JTAG port has been disabled, even if it has been re-enabled.

**Usage constraints**

Writing a value with any non-zero bits to PSTA when the JTAG-AP engine is not idle is UNPREDICTABLE. The JTAG-AP Engine is idle when both `CSW.SERACTV` and `CSW.WFIFOCNT` are zero.

The reset value of PSTA0-PSTA7 is 0b0.

The register is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th>RW</th>
</tr>
</thead>
</table>

**Configurations**

PSTA is included in all implementations.

**Attributes**

PSTA is a 32-bit read/write register.

**Field descriptions**

The PSTA bit assignments are:

<table>
<thead>
<tr>
<th>31</th>
<th>8</th>
<th>7</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td></td>
<td></td>
<td>PSTA7-PSTA0</td>
</tr>
</tbody>
</table>

**Bits[31:8]**

RES0.

**PSTA7-PSTA0, bits[7:0]**

Each field PSTAn represents a sticky status flag for JTAG port $n$, and behaves as R/W1C. PSTAn is set to 0b1 if all the following are true:

- JTAG port $n$ is connected to the JTAG-AP.
- PSEL.PSELn is 0b1.
- JTAG port $n$ is disabled.

Once set to 0b1, PSTAn remains set until it is written with the value 0b1.

As long as PSTAn is 0b1, JTAG port $n$ remains disabled.

If JTAG port $n$ is not connected to the JTAG-AP, PSTAn is RAZ.
Table C3-7 shows the behavior of PSTAn on reads and writes:

<table>
<thead>
<tr>
<th>Value</th>
<th>Meaning on reads</th>
<th>Action on writes</th>
</tr>
</thead>
<tbody>
<tr>
<td>0b0</td>
<td>Port has not been disabled, or port is not connected.</td>
<td>No action, write is ignored.</td>
</tr>
<tr>
<td>0b1</td>
<td>Port has been disabled.</td>
<td>Clear PSTAn to 0b0.</td>
</tr>
</tbody>
</table>

Accessing PSTA

PSTA can be accessed from the JTAG-AP register space:

<table>
<thead>
<tr>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x88</td>
</tr>
</tbody>
</table>
Part D

Identification Registers and ROM Tables
Chapter D1
Component and Peripheral ID Registers

This chapter describes the Component and Peripheral ID Registers, which must be present in the register space of every debug component that complies with the ARM Peripheral Identification specification.

The debug register files and ROM Tables that are shown in Figure A1-5 on page A1-33, and other illustrations of debug systems, include the Component and Peripheral ID registers.

This chapter contains the following sections:

- **About the Component and Peripheral ID registers on page D1-216.**
- **Component and Peripheral Identification Registers Reference Information on page D1-217.**
- **Legacy Peripheral ID layout on page D1-224.**

__________ Note ____________

Contact ARM for details about the ARM Peripheral Identification specification.
D1.1 About the Component and Peripheral ID registers

The Component and Peripheral ID registers provide a generic model for component identification.

A generic component occupies a continuous register space that covers one or more 4KB blocks. The Peripheral and Component ID registers are always at the end of this register space, with the Component ID Registers occupying the last four words of this block, which means that, if a component occupies more than one 4KB block, the Component and Peripheral ID Registers are at the end of the last block.

Table D1-1 shows the memory map of the Component and Peripheral ID Registers. All listed registers are required in every debug component implementation.

### Table D1-1 Summary of Component and Peripheral ID Registers

<table>
<thead>
<tr>
<th>Address</th>
<th>Name</th>
<th>Access</th>
<th>Value</th>
<th>See</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xFD0</td>
<td>PIDR4</td>
<td>RO</td>
<td>IMPLEMENTATION DEFINEDa</td>
<td>PIDR0-PIDR7, Peripheral Identification Registers on page D1-220</td>
</tr>
<tr>
<td>0xFD4</td>
<td>PIDR5</td>
<td>RO</td>
<td>0x00000000</td>
<td></td>
</tr>
<tr>
<td>0xFD8</td>
<td>PIDR6</td>
<td>RO</td>
<td>0x00000000</td>
<td></td>
</tr>
<tr>
<td>0xFDC</td>
<td>PIDR7</td>
<td>RO</td>
<td>0x00000000</td>
<td></td>
</tr>
<tr>
<td>0xFE0</td>
<td>PIDR0</td>
<td>RO</td>
<td>IMPLEMENTATION DEFINEDa</td>
<td></td>
</tr>
<tr>
<td>0xFE4</td>
<td>PIDR1</td>
<td>RO</td>
<td>IMPLEMENTATION DEFINEDa</td>
<td></td>
</tr>
<tr>
<td>0xFE8</td>
<td>PIDR2</td>
<td>RO</td>
<td>IMPLEMENTATION DEFINEDa</td>
<td></td>
</tr>
<tr>
<td>0xFEC</td>
<td>PIDR3</td>
<td>RO</td>
<td>IMPLEMENTATION DEFINEDa</td>
<td></td>
</tr>
<tr>
<td>0xFF0</td>
<td>CIDR0</td>
<td>RO</td>
<td>0x0000000D</td>
<td>CIDR0-CIDR3, Component Identification Registers on page D1-217</td>
</tr>
<tr>
<td>0xFF4</td>
<td>CIDR1</td>
<td>RO</td>
<td>IMPLEMENTATION DEFINEDa</td>
<td></td>
</tr>
<tr>
<td>0xFF8</td>
<td>CIDR2</td>
<td>RO</td>
<td>0x00000005</td>
<td></td>
</tr>
<tr>
<td>0xFFF</td>
<td>CIDR3</td>
<td>RO</td>
<td>0x00000081</td>
<td></td>
</tr>
</tbody>
</table>

a. See the register description for more information.
D1.2 Component and Peripheral Identification Registers Reference Information

This section has reference information for the Component and Peripheral Identification Registers:

D1.2.1 CIDR0-CIDR3, Component Identification Registers

The CIDR characteristics are:

**Purpose**

CIDR0-CIDR3 provide the Component ID, which has the following functions:

- Identify the 4KB block of memory space as a component.
- Identify the component type by acting as a preamble to a component type-specific set of identification registers.

**Note**

In addition to the Component ID Registers and Peripheral ID Registers, the CoreSight Architecture Specification requires CoreSight components to implement various other registers in the address space 0xF00 to 0xFFF. For details, see the ARM CoreSight Architecture Specification.

**Usage constraints**

CIDR0-CIDR3 occupy the last four words of a 4KB register space of a component. If the register space of a component occupies more than one 4KB block they are the last four words of the last 4KB block.

ROM Table components have a standard register space layout, which is defined in Component and Peripheral ID Registers for ROM Tables on page D2-228.

Processors that comply with the ARMv7 Debug Architecture, and trace macrocells that comply with the ETM Architecture Specification version 3.2 or later, identify themselves as Debug components. For more information see the ARM Architecture Reference Manual, ARMv7-A and ARMv7-R edition and the ETM Architecture Specification.

CIDR0-CIDR3 are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th>RO</th>
</tr>
</thead>
</table>

**Configurations**

CIDR0-CIDR3 are included in all implementations.

**Attributes**

CIDR0-CIDR3 are four 32-bit management registers.

**Field Descriptions**

The CIDR bit assignments are:

<table>
<thead>
<tr>
<th>Bit Assignment</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>31-0</td>
<td>RES0</td>
</tr>
<tr>
<td>8</td>
<td>PRMBL_3</td>
</tr>
<tr>
<td></td>
<td>0xFFC</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Bit Assignment</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>31-0</td>
<td>RES0</td>
</tr>
<tr>
<td>8</td>
<td>PRMBL_2</td>
</tr>
<tr>
<td></td>
<td>0xFF8</td>
</tr>
</tbody>
</table>
D1 Component and Peripheral ID Registers
D1.2 Component and Peripheral Identification Registers Reference Information

CIDR3 bits[31:8]

RES0.

PRMBL_3, CIDR3 bits[7:0]

Preamble, segment 3. Must be 0xB1.

CIDR2 bits[31:8]

RES0.

PRMBL_2, CIDR2 bits[7:0]

Preamble, segment 2. Must be 0x05.

CIDR1 bits[31:8]

RES0.

CLASS, CIDR1 bits[7:4]

The component class, which can be one of the values that are listed in Table D1-2.

Table D1-2 CLASS field encodings

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x0</td>
<td>Generic verification component.</td>
</tr>
<tr>
<td>0x1</td>
<td>ROM Table. See also <em>ROM Table Types</em> on page D2-227. For detailed information about Class 0x1 ROM Tables, see Chapter D3 <em>Class 0x1 ROM Tables</em>.</td>
</tr>
<tr>
<td>0x2-0x8</td>
<td>Reserved.</td>
</tr>
<tr>
<td>0x9</td>
<td>CoreSight component. For general information about CoreSight components, see the <em>CoreSight Architecture Specification</em>. A CoreSight component can be a Class 0x9 ROM Table, which can be identified from the DEVARCH.ARCHID having the value 0x0A7. See also <em>ROM Table Types</em> on page D2-227. For detailed information about Class 0x9 ROM Tables, see Chapter D4 <em>Class 0x9 ROM Tables</em>.</td>
</tr>
<tr>
<td>0xA</td>
<td>Reserved.</td>
</tr>
<tr>
<td>0xB</td>
<td>Peripheral Test Block.</td>
</tr>
<tr>
<td>0xC-0x9</td>
<td>Reserved.</td>
</tr>
<tr>
<td>0xE</td>
<td>Generic IP component.</td>
</tr>
<tr>
<td>0xF</td>
<td>CoreLink, PrimeCell, or system component with no standardized register layout, for backwards compatibility.</td>
</tr>
</tbody>
</table>
PRMBL_1, CIDR1 bits[3:0]
   Preamble, segment 1. Must be 0x0.

CIDR0 bits[31:8]
   RES0.

PRMBL_0, CIDR0 bits[7:0]
   Preamble, segment 0. Must be 0x0.

**Accessing CIDR0-CIDR3**

CIDR0-CIDR3 can be accessed at the following address:

<table>
<thead>
<tr>
<th>Offset</th>
<th>CIDR0</th>
<th>CIDR1</th>
<th>CIDR2</th>
<th>CIDR3</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xFF0</td>
<td>0xFF4</td>
<td>0xFF8</td>
<td>0xFFF</td>
<td>0xFFF</td>
</tr>
</tbody>
</table>
D1.2.2 PIDR0-PIDR7, Peripheral Identification Registers

The PIDR characteristics are:

**Purpose**

PIDR0-PIDR7 provide information that is used to identify a component. A component is uniquely identified by the following fields, which are encoded in the PIDR:

- JEP106 continuation code.
- JEP106 identification code.
- Part Number.
- Revision.
- Customer Modified.
- RevAnd.

Debug components have a standard layout of Peripheral Identification Registers, as defined in the *ARM CoreSight Architecture Specification*.

**Usage constraints**

PIDR0-PIDR7 are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th>IMPLEMENTATION DEFINED</th>
</tr>
</thead>
</table>

**Configurations**

Included in all implementations.

**Attributes**

PIDR0-PIDR7 are eight 32-bit management registers.

**Field Descriptions**

The PIDR bit assignments are:

<table>
<thead>
<tr>
<th>PIDR_3</th>
<th>RES0</th>
<th>REVAND</th>
<th>CMOD</th>
<th>0xFEC</th>
</tr>
</thead>
<tbody>
<tr>
<td>31</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>8</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>7</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PIDR_2</th>
<th>RES0</th>
<th>REVISION</th>
<th>DES_1</th>
<th>0xFE8</th>
</tr>
</thead>
<tbody>
<tr>
<td>31</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>8</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>7</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PIDR_1</th>
<th>RES0</th>
<th>DES_0</th>
<th>PART_1</th>
<th>0xFE4</th>
</tr>
</thead>
<tbody>
<tr>
<td>31</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>8</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>7</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PIDR_0</th>
<th>RES0</th>
<th>PART_0</th>
<th>0xFE0</th>
</tr>
</thead>
<tbody>
<tr>
<td>31</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>8</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>7</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Bits[31:8] of PIDR3

RES0.

REV AND, PIDR3 bits[7:4]

The REV AND field indicates minor errata fixes specific to this design, for example metal fixes after implementation. Usually this field is zero. If the field is required, ARM recommends that component designers ensure that it can be changed by a metal fix, for example by driving it from registers that reset to zero.

CMOD, PIDR3 bits[3:0]

Customer Modified. If the component is reusable IP, the CMOD field indicates whether the customer has modified the behavior of the component. CMOD can have one of the following values:

- 0x0: The component is not modified from the original design.
- Any other value: The component has been modified.

ARM recommends that the user or debugger reads the documentation for the component to determine the modifications that are made to the component.

For any two components with the same Unique Component Identifier:

- If the value of the CMOD fields of both components equals zero, the components are identical.
- If the CMOD fields of both components have the same non-zero value, it does not necessarily mean that they have been subjected to the same modifications.
- If the value of the CMOD field of either of the two components is non-zero, they might not be identical, even though they have the same Unique Component Identifier.

Note

CoreSight versions before version 3.0 permitted using the CMOD field to distinguish between different components. This permission is removed in CoreSight version 3.0.

Bits[31:8] of PIDR2

RES0.
REVISION, PIDR2 bits[7:4]

The REVISION field is an incremental value starting at 0x0 for the first design of a component. It is increased by 1 for both major and minor revisions and is used as a look-up to establish the exact major and minor revision.

JEDEC, PIDR2 bit[3]

Must be 0x1 to indicate that a JEDEC-assigned value is used.

DES_1, PIDR2 bits[2:0]

JEP106 identification and continuation codes, which are stored in PIDR1, PIDR2, and PIDR4 as follows:

DES_0, PIDR1 bits[7:4] JEP106 identification code bits[3:0].
DES_1, PIDR2 bits[2:0] JEP106 identification code bits[6:4].
DES_2, PIDR4 bits[3:0] JEP106 continuation code.

These codes indicate the designer of the component and not the implementer, except where the two are the same. To obtain a number, or to see the assignment of these codes, contact JEDEC http://www.jedec.org.

A JEDEC code takes the following form:
• A sequence of zero or more numbers, all having the value 0x7F.
• A following 8-bit number, that is not 0x7F, and where bit[7] is an odd parity bit.

For example, ARM Limited is assigned the code 0x7F 0x7F 0x7F 0x7F 0x3B.
• The continuation code is the number of times 0x7F appears before the final number. For example, for ARM Limited this code is 0x4.
• The identification code is bits[6:0] of the final number. For example, ARM Limited has the code 0x3B.

Bits[31:8] of PIDR1

RES0.

DES_0, PIDR1 bits[7:4]

JEP106 identification and continuation codes, which are stored in PIDR1, PIDR2, and PIDR4 as follows:

DES_0, PIDR1 bits[7:4] JEP106 identification code bits[3:0].
DES_1, PIDR2 bits[2:0] JEP106 identification code bits[6:4].
DES_2, PIDR4 bits[3:0] JEP106 continuation code.

For details, see the description of the DES_1 field.

PART_1, PIDR1 bits[3:0]

Part number, which is selected by the designer of the component, and stored in PIDR1 and PIDR3 as follows:

PART_0, PIDR0 bits[7:4] Part number bits[7:0].
PART_1, PIDR1 bits[3:0] Part number bits[11:8].

Bits[31:8] of PIDR0

RES0.

PART_0, PIDR0 bits[7:0]

Part number, which is selected by the designer of the component, and stored in PIDR1 and PIDR3 as follows:

PART_0, PIDR0 bits[7:4] Part number bits[7:0].
PART_1, PIDR1 bits[3:0] Part number bits[11:8].
Bits[31:0] of PIDR7
RES0.

Bits[31:0] of PIDR6
RES0.

Bits[31:0] of PIDR5
RES0.

Bits[31:8] of PIDR4
RES0.

SIZE, PIDR4 bits[7:4]
The SIZE field is a 4-bit value that indicates the memory size that is used by this component. It is expressed as the logarithm to the base 2 of the number of 4KB blocks the component occupies.

DES_2, PIDR4 bits[3:0]
JEP106 identification and continuation codes, which are stored in PIDR1, PIDR2, and PIDR4 as follows:

DES_0, PIDR1 bits[7:4] JEP106 identification code bits[3:0].
DES_1, PIDR2 bits[2:0] JEP106 identification code bits[6:4].
DES_2, PIDR4 bits[3:0] JEP106 continuation code.
For details, see the description of the DES_1 field.

Accessing PIDR0-PIDR7

PIDR0-PIDR7 can be accessed at the following address:

<table>
<thead>
<tr>
<th>Offset</th>
<th>PIDR0</th>
<th>PIDR1</th>
<th>PIDR2</th>
<th>PIDR3</th>
<th>PIDR4</th>
<th>PIDR5</th>
<th>PIDR6</th>
<th>PIDR7</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xFE0</td>
<td>0xFE4</td>
<td>0xFE8</td>
<td>0xFEC</td>
<td>0xFD0</td>
<td>0xFD4</td>
<td>0xFD8</td>
<td>0xFD0</td>
<td>0xFD0</td>
</tr>
</tbody>
</table>

"Accessing PIDR0-PIDR7"
D1.3 Legacy Peripheral ID layout

Legacy peripheral components have the following characteristics:

- They do not use JEP106 Identity Codes.
- They implement only four Peripheral ID Registers.
- The Configuration Register, which corresponds to the Peripheral ID3 Register, contains peripheral-specific build options, for example the width of a bus.

Table D1-3 shows the format of the peripheral identification registers in legacy components.

<table>
<thead>
<tr>
<th>Address</th>
<th>Register</th>
<th>Access</th>
<th>Bits</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xFD0 - 0xFD0C</td>
<td>-</td>
<td>-</td>
<td>[31:0]</td>
<td>-</td>
<td>Reserved. Might be used by component. If so, value is IMPLEMENTATION DEFINED.</td>
</tr>
<tr>
<td>0xFE0</td>
<td>Peripheral ID0</td>
<td>RO</td>
<td>[31:8]</td>
<td>-</td>
<td>Reserved. RAZ.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>[7:0] IMPLEMENTATION DEFINED Part number[7:0]</td>
</tr>
<tr>
<td>0xFE4</td>
<td>Peripheral ID1</td>
<td>RO</td>
<td>[31:8]</td>
<td>-</td>
<td>Reserved. RAZ.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>[7:4] IMPLEMENTATION DEFINED ASCII Identity code[3:0]</td>
</tr>
<tr>
<td>0xFE8</td>
<td>Peripheral ID2</td>
<td>RO</td>
<td>[31:8]</td>
<td>-</td>
<td>Reserved. RAZ.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>[7:4] IMPLEMENTATION DEFINED Revision number of peripheral.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>[3] 0b0</td>
<td>ASCII Identity code is used.</td>
</tr>
<tr>
<td>0xFE8</td>
<td>Peripheral ID3</td>
<td>RO</td>
<td>[31:8]</td>
<td>-</td>
<td>Reserved. RAZ.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>[7:0]</td>
<td>IMPLEMENTATION DEFINED Configuration Register.</td>
</tr>
</tbody>
</table>
Chapter D2
About ROM Tables

The chapter describes ROM Tables. It includes the following sections:

- **ROM Tables Overview** on page D2-226.
- **ROM Table Types** on page D2-227.
- **Component and Peripheral ID Registers for ROM Tables** on page D2-228.
- **The component address** on page D2-229.
- **Location of the ROM Table** on page D2-230.
- **ROM Table hierarchies** on page D2-231.
D2.1 ROM Tables Overview

ROM Tables hold information about debug components.

- Systems with a single debug component do not require a ROM Table. However, a designer might choose to implement such a system to include a ROM Table.
- Systems with more than one debug component must include at least one ROM Table.

A ROM Table connects to a bus controlled by a Memory Access Port (MEM-AP). In other words, the ROM Table is part of the address space of the memory system that is connected to a MEM-AP. More than one ROM Table can be connected to a single bus.

A ROM Table always occupies 4KB of memory.
D2.2 ROM Table Types

The following types of ROM Tables are permitted to be used with ADlv5:

Class 0x1 ROM Tables

In a Class 0x1 ROM Table implementation:

- The Component class field, CIDR1.CLASS, is 0x1, which identifies the component as a Class 0x1 ROM Table.
- The PIDR4.SIZE field must be 0.
- A ROM Table must occupy a single 4KB block of memory.
- A Class 0x1 ROM Table is a read-only device.

For a detailed description of the Class 0x1 ROM Table entries and registers, see Chapter D3 Class 0x1 ROM Tables.

Class 0x9 ROM Tables

In a Class 0x9 ROM Table implementation:

- The Component class field, CIDR1.CLASS, is 0x9, which identifies the component as a CoreSight Component.
- The DEVTYPE and DEVID registers contain information about the ROM Table, as described in Chapter D4 Class 0x9 ROM Tables.
- The PIDR4.SIZE field must be 0.
- A ROM Table must occupy a single 4KB block of memory.
- For ADlv5 implementations, the DEVID.FORMAT field must be 0, which indicates that the ROM Table entries are 32 bits wide.

For a detailed description of the Class 0x9 ROM Table entries and registers, see Chapter D4 Class 0x9 ROM Tables.

Note

Class 0x9 ROM Tables can be used alongside Class 0x1 ROM Tables, and both Class 0x9 and Class 0x1 ROM Tables might be present in systems with an ADlv5-compliant interface.
D2.3 Component and Peripheral ID Registers for ROM Tables

Any ROM Table must implement a set of Component and Peripheral ID Registers, that start at offset 0xF00 in the ROM Table. *PIDR0-PIDR7, Peripheral Identification Registers* on page D1-220 in Chapter D1 Component and Peripheral ID Registers describes these registers. This section only describes particular features of the registers when they relate to a ROM Table.

D2.3.1 Identifying the debug SoC or platform

The top-level ROM Table Peripheral ID Registers uniquely identify the SoC or platform. If a system has more than one Memory Access Port with a connected ROM Table, the information from the Peripheral ID Registers of all the top-level ROM Tables, considered collectively, is required to uniquely identify the SoC or platform. An example of a system with multiple MEM-APs is shown in Figure A1-6 on page A1-34.

If there is any change in the set of components that are identified by the ROM Table, or any change in the connections to those components, then the Peripheral ID Registers must be updated to reflect the change.

Each possible configuration must be uniquely identifiable from the Peripheral ID Register values, because the Peripheral ID can be used by the debugger to name the description of the system.

If a debugger performs topology detection on the system that it connects to, it can save its description of the system with the Peripheral ID. If that system is connected to the debugger again, the debugger can retrieve that saved description, avoiding any requirement for topology detection.

If two different systems have the same Peripheral ID, a debugger might retrieve an incorrect description. If this situation occurs, you must force the debugger to perform topology detection again.

If the ADI implements DPv2, the DP TARGETID register also uniquely identifies the SoC or platform, and ARM deprecates use of the top-level ROM Table Peripheral ID registers as a unique identifier by tools.

--- Note ---

- If SWJ-DP is implemented, it is not required that both the JTAG-DP and SW-DP implement the same DP architecture version, and therefore TARGETID. Tools might be using a DP that does not implement DPv2.

- Deprecation of the use of the top-level ROM Table peripheral ID registers by tools does not remove the requirement on implementations to provide a unique identifier in the top-level ROM Table peripheral ID registers. Future releases of this manual might remove this requirement.
D2.4 The component address

Each debug component occupies one or more 4KB blocks of address space. This block of address space is referred to as the Debug Register File for the component. For examples, see Figure A1-3 on page A1-30, and other figures in Chapter A1.

The Address offset field of a ROM Table entry, ROMENTRY<\textit{n}>.OFFSET, points to the start of the 4KB block which contains the Peripheral ID and Component ID registers of component \textit{n}. The base address of this 4KB block is calculated using the following equation:

\[
\text{Component}_n\_\text{Address} = \text{ROM}_\text{Base}_\text{Address} + (\text{ROMENTRY}<\textit{n}>.\text{OFFSET} \ll 12)
\]

The Component and Peripheral ID Registers for component \textit{n} start at Component\_n\_Address + 0xFD0.

For a component that occupies more than one 4KB block, the size of the component and the base address of the component are IMPLEMENTATION DEFINED, and might be determined by a combination of the values in the Peripheral ID registers and other IMPLEMENTATION DEFINED registers.

___ Note ___

For a component which occupies more than 4KB, the ROM Table entry always points to the 4KB block which contains the Peripheral ID and Component ID registers, and this 4KB might occupy any 4KB block in the Debug Register File of the component.

Previous versions of this specification used the PIDR4.SIZE field to define the size and base address of the component. The use of the PIDR4.SIZE field is deprecated, and ARM recommends that for all components:

- Debuggers ignore the value of PIDR4.SIZE.
- New components set PIDR4.SIZE to zero.

Previous versions of this specification required the Peripheral ID and Component ID registers to occupy the highest 4KB block of the Debug Register File. This requirement is removed.

In general, the ROM Table indicates all the valid addresses in the memory map of the connection to the system being debugged. For more information about accesses to addresses that are not pointed to by the ROM Table, see MEMTYPE, Memory Type Register on page D3-302.

ARM recommends that the debug component base address is aligned to the largest translation granule supported by any processor that can access the component, which is up to 64KB for an ARMv8 processor.

For more information about the Component and Peripheral ID Registers, see Chapter D1 Component and Peripheral ID Registers.
D2.5 Location of the ROM Table

This section describes how to provide a pointer to the top-level ROM Table.

While entries in a ROM Table are always relative addresses, the top-level pointer to a ROM Table always takes the form of an absolute address.

From an Access Port

Each Memory Access Port (MEM-AP) contains a BASE register that indicates one of the following:

- The base address of a ROM Table.
- The address of a debug component, which must be the only debug component that is accessible from that AP. The memory system that is accessed by this MEM-AP does not contain a ROM Table.
- No debug components are accessible from this AP, which is indicated by BASE.P having the value 0b0.

From processor cores

The operating system or debug monitor must be aware of the memory map of the system to find the ROM Table and debug components.
D2.6 ROM Table hierarchies

Normally, each ROM Table entry, ROMENTRY<n>, points to the memory space of a debug component. The Component and Peripheral ID Registers for that component start at offset 0xFD0 in a 4KB section of the memory space of the component. The Component class field CIDR1.CLASS, bits [7:4] of the Component ID1 Register, identifies the type of the component. This field is described in CIDR0-CIDR3, Component Identification Registers on page D1-217.

ROMENTRY<n> can point to another ROM Table, which is referred to as a lower-level ROM Table:

A ROM Table can include more than one entry that points to lower-level ROM Tables, and a hierarchy of ROM Tables can exist. All ROM Tables within that hierarchy must be scanned to discover all the debug components in the system.

A system with an interface that is compliant with ADIv5 can contain both Class 0x1 and Class 0x9 ROM Tables in a single implementation.

When identifying Class 0x1 ROM Tables, DEV ARCH and DEVTYPE are treated as having a value of 0.

If more than the maximum number of ROM Table entries are required, the ROM Table must be expanded by creating a ROM Table hierarchy which contains as many ROM Table entries as necessary.

The MEM-AP BASE register must point to the top-level ROM Table in the hierarchy.

Figure D2-1 shows an example of a ROM Table hierarchy.

A hierarchy of ROM Tables might increase the total number of ROM Table entries in the system.

A hierarchy might be implemented for some other reason, for example to reflect the logical organization of the debug components of the system. There might be only a few entries in each ROM Table within a hierarchy.

D2.6.1 Peripheral ID Registers in lower-level ROM Tables

The Peripheral ID value that is obtained from the Peripheral ID Registers of any ROM Table that is not a top-level ROM Table is used to identify the subsystem described by the ROM Table. It is not used to identify the SoC or platform.
**D2.6.2 Component Revision Numbers**

When a component is changed, the revision number that is contained in the Unique Component Identifier of that component must be changed to ensure that debug tools can differentiate the versions of the component, which usually involves changing one or more of PIDR2.REVISION and PIDR3.REVAND. For details about the Unique Component Identifier, see the ARM® CoreSight™ Architecture Specification v3.0.

In systems that are designed as multiple subsystems of components, each subsystem has a ROM Table that indicates the locations of the components in the subsystem. When changing the revision of a component in a subsystem:

- The revision of the subsystem that the component is part of may or may not change.
- The revision number of the ROM Table describing that subsystem may or may not change.

As a result, debug tools must inspect the revision of each component within a subsystem to uniquely identify the revision of those components and must not rely on the revision of the ROM Table to uniquely identify the revision of all the components within the subsystem.

For example, if the revision number of a trace macrocell that is part of a subsystem with a ROM Table which describes the layout of the subsystem changes, the revision of the ROM Table may not change, and multiple instances of the subsystem with the same revision number could exist in the ROM Table, even though the components making up the subsystems have different revision numbers for each subsystem.

**D2.6.3 Prohibited ROM Table references**

Every debug component within a system must appear only once in the ROM Table, or ROM Table hierarchy, that is visible to an external debugger. Figure D2-2 shows a prohibited case, where entries in ROM Tables B and C both point to ROM Table D.

![Figure D2-2 Prohibited duplicate ROM Table reference from ROM Table](image)

Figure D2-3 on page D2-233 shows a similar prohibited case, where entries in ROM Table A and MEM-AP 2 both point to ROM Table B.
In addition, circular ROM Table references are prohibited. A ROM Table entry must not point to a ROM Table that directly or indirectly points to itself. In particular, ROM Table entries must not point back to the top-level ROM Table, as is shown in Figure D2-4, where both ROM Table B and ROM Table C have prohibited links back to ROM Table A.

There is no requirement that components in separate ROM Table hierarchies must be in separate systems, which includes multiple APs in a single ADI implementation, and multiple ADI implementations. For example, if MEM-AP 1 in ADI implementation 1 points to a hierarchy of ROM Tables which includes a pointer to trace macrocell A, and MEM-AP 2 in ADI implementation 2 points to a hierarchy of ROM Tables which includes a pointer to trace sink B, then trace from trace macrocell A can be collected by trace sink B, as shown in Figure D2-5.
D2 About ROM Tables
D2.6 ROM Table hierarchies
Chapter D3
Class 0x1 ROM Tables

The chapter describes Class 0x1 ROM Tables. It includes the following sections:

- About Class 0x1 ROM Tables on page D3-236.
- Class 0x1 ROM Table summary on page D3-237.
- Use of power domain IDs on page D3-239.
- Register Descriptions on page D3-241.
D3.1 About Class 0x1 ROM Tables

In a Class 0x1 ROM Table implementation:

- The Component class field, CIDR1.CLASS, is 0x1, which identifies the component as a Class 0x1 ROM Table.
- The PIDR4.SIZE field must be 0, because a ROM Table must occupy a single 4KB block of memory.

Class 0x1 ROM Tables can be used alongside Class 0x9 ROM Tables, and both Class 0x1 and Class 0x9 ROM Tables might be present in systems with an ADIv5-compliant interface.

See also:

- For general information about ROM Tables, see Chapter D2 About ROM Tables.
- For information about the Component and Peripheral ID Registers, see Chapter D1 Component and Peripheral ID Registers. The class configuration is described in the field description of the CIDR1.CLASS field, in section CIDR0-CIDR3, Component Identification Registers on page D1-217.
- For information about Class 0x9 ROM Tables, see Chapter D4 Class 0x9 ROM Tables.
D3.2 Class 0x1 ROM Table summary

This section summarizes the characteristics of Class 0x1 ROM Tables.

D3.2.1 Class 0x1 ROM Table Layout

A Class 0x1 ROM Table:
• Occupies a single 4KB block of memory, and starts at offset 0x000 in this block.
• Has a series of entries, each of which is a register.
• Has a final entry, which is one of the following:
  — A marker with the value 0x00000000, which signals the end of the ROM Table.
  — A regular entry at offset 0xEFC. A ROM Table entry at this offset is always the final entry, even if it does not have the value 0x00000000.
• Almost always has an unused area between the entry that marks the end of the ROM Table entries and the start of the reserved area at offset 0xF00. This unused area is reserved, RES0. If a ROM Table contains 960 entries, there is no unused area.

Table D3-1 shows the Class 0x1 ROM Table registers, in order of their address offset in the 4KB block where the programmers’ model resides. For detailed descriptions of each register, see Register Descriptions on page D3-241.

Table D3-1 ROM Table register summary

<table>
<thead>
<tr>
<th>Offset</th>
<th>Type</th>
<th>Valid bits</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Entries, including any unused area</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x000 to (N-1)×4</td>
<td>RO</td>
<td>1-28</td>
<td>ROMENTRY&lt;n&gt;</td>
<td>Up to 960 ROM Table entries. The end of the area that contains ROM Table entries is IMPLEMENTATION DEFINED, and depends on the number of ROM Table entries, which is denoted N.</td>
</tr>
<tr>
<td>N×4</td>
<td>RO</td>
<td>32</td>
<td>ROMENTRY&lt;n&gt;</td>
<td>Marker that indicates the final entry in a ROM Table with fewer than 960 entries. The offset of this entry depends on the number of ROM Table entries, which is denoted N. See also ROM Table entries that are marked not present on page D3-238.</td>
</tr>
<tr>
<td>(N+1)×4 to 0xEFC</td>
<td>-</td>
<td>-</td>
<td>Unused area of the ROM Table.</td>
<td>RES0. The offset depends on the number of ROM Table entries, which is denoted N. This area is not present if N is 960.</td>
</tr>
<tr>
<td>Reserved area</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0xF00 - 0xFC8</td>
<td>-</td>
<td>-</td>
<td>Reserved area of the ROM Table.</td>
<td>RES0.</td>
</tr>
<tr>
<td>MEMTYPE and ID registers</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0xFCC</td>
<td>RW</td>
<td>1</td>
<td>MEMTYPE</td>
<td>Memory Type Register.</td>
</tr>
<tr>
<td>0xFD0 - 0xFD7</td>
<td>RO</td>
<td>8</td>
<td>PIDR4-PIDR7</td>
<td>Peripheral Identification Registers, PIDR0-PIDR7.</td>
</tr>
<tr>
<td>0xFE0 - 0xFE7</td>
<td>RO</td>
<td>8</td>
<td>PIDR0-PIDR3</td>
<td>Component Identification Registers, CIDR0-CIDR3.</td>
</tr>
<tr>
<td>0xFF0 - 0xFFC</td>
<td>RO</td>
<td>8</td>
<td>CIDR0-CIDR3</td>
<td></td>
</tr>
</tbody>
</table>

a. An implementation is unlikely to require more than the maximum number of entries in a ROM Table. However, ROM Table hierarchies on page D2-231 describes how larger ROM Tables can be constructed.
D3.2.2 ROM Table entries that are marked not present

The descriptions of the debug components are stored in sequential locations in the ROM Table, starting at the ROM Table base address. However, a ROM Table entry can be marked not present by setting the PRESENT field of the entry to a value that indicates that the entry is not present.

When scanning the ROM Table, an entry that is marked as not present must be skipped. Unless the entry has the value 0x00000000, however, you must not assume that an entry that is marked not present represents the end of the ROM Table. For example, a ROM Table might be generated using static configuration tie-offs that indicate the presence or absence of particular devices, giving not present entries in the ROM Table.
D3.3 Use of power domain IDs

If the following conditions are met, a Class 0x1 ROM Table entry, ROMENTRY<n>, has a valid power domain ID \( m \):

- ROMENTRY<n>.PRESENT is 0b1, indicating that the ROM Table entry is present.
- ROMENTRY<n>.POWERIDVALID is 0b1, indicating that the power ID is valid.
- ROMENTRY<n>.POWERID is \( m \), the power domain ID.

If any of the ROMENTRY<n> has a valid power domain ID, the ROM Table must include a valid entry that points to a power requestor that enables a debugger to request power to the power domains that are specified in the ROM Table. The power requestor must comply with the following rules:

- The power requestor must not have a valid power domain ID.
- The power requestor must be in the same power domain as the ROM Table.

For any component with a valid power domain ID, ARM recommends that, before accessing any register in a component, the debugger first accesses the power requestor to request that power is applied to the component. Otherwise the component might not be powered, or it might be powered down at any time.

D3.3.1 Power domain entries

The power domain ID is specific to components identified by the Class 0x1 ROM Table, which enables hierarchies of power domains to be constructed with each level enabling access to a level below.

Figure D3-1 shows an example Class 0x1 ROM Table that indicates the locations of three components.

---

**Figure D3-1 Single Class 0x1 ROM Table with power domain IDs**

In Figure D3-1, the first component, \( p \), has no valid power domain ID and is the power requestor. The other two components, \( m \) and \( n \), have power domain IDs of 0 and 1 respectively. The debugger requests power for these components, by using the power requestor \( p \).

Figure D3-2 on page D3-240 shows an example system with nested power domains.
In Figure D3-2, ROM Table A is the top-level ROM Table and indicates the presence of:

- Power requestor \( p \), which must be in the same power domain as the ROM.
- Component \( m \), which is in power domain 0.
- ROM Table B, which is in power domain 1.

ROM Table B indicates the presence of power requestor \( q \) and components \( i \) and \( j \), so power for components \( i \) and \( j \) is requested through power requestor \( q \). Because power requestor \( q \) is in power domain 1, the power domains it controls are subdomains of power domain 1, and are labeled 1.0 and 1.1.

The power domain IDs indicated by ROM Table B are different from the power domain IDs indicated by ROM Table A and are nested within power domain 1.

### D3.3.2 Algorithm to discover power domain IDs

Inspect each Class 0x1 ROM Table in the system, starting at the top-level ROM Table. For each valid Class 0x1 ROM Table entry ROMENTRY\(<n>\):

1. If ROMENTRY\(<n>\).POWERIDVALID is 0b1, the power domain ID information is present. To request power for this entry, use the ROMENTRY\(<n>\).POWERID field, bits[8:4], to program the power requestor.

2. If ROMENTRY\(<n>\).POWERIDVALID is 0b0, no power domain ID information is present.
   - Inspect the component and determine if it is a power requestor. Power requestor components have no power domain ID. Make a note of whether a power requestor is detected.
   - If the component is not a power requestor, the absence of a power domain ID value indicates that it is powered, and no power requests are required to power this component.

---

**Note**

If no power requestor is indicated in this ROM Table, all entries in this ROM Table must not have valid power domain IDs.

If there are Class 0x9 ROM Tables in the system, use the algorithm that is described in Chapter D4 Class 0x9 ROM Tables, section *Algorithm to discover power domain IDs* to discover power domains in them.
D3.4 Register Descriptions

This section provides detailed descriptions of the registers in a Class 0x1 ROM Table, in alphabetical order.

D3.4.1 CIDR0-CIDR3, Component Identification Registers

This section describes the bit assignments for ROM Table components. For a full description of the CIDR registers, see CIDR0-CIDR3, Component Identification Registers.

The CIDR characteristics are:

**Purpose**

Provide information to identify a CoreSight component.

**Usage constraints**

CIDR0-CIDR3 are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th>RO</th>
</tr>
</thead>
</table>

**Configurations**

Included in all implementations.

**Attributes**

CIDR0-CIDR3 are four 32-bit management registers.

**Field descriptions**

The CIDR bit assignments are:

CIDR3 0xFFC

31 8 7 0
RES0 PRMBL_3

CIDR2 0xFF8

31 8 7 0
RES0 PRMBL_2

CIDR1 0xFF4

31 8 7 4 3 0
RES0 CLASS PRMBL_1

CIDR0 0xFF0

31 8 7 0
RES0 PRMBL_0

CIDR3 bits[31:8]

RES0.

PRMBL_3, CIDR3 bits[7:0]

0x81.

CIDR2 bits[31:8]

RES0.
PRMBL_2, CIDR2 bits[7:0]
  0x05.

CIDR1 bits[31:8]
  RES0.

CLASS, CIDR1 bits[7:4]
  0x1.

PRMBL_1, CIDR1 bits[3:0]
  0x0.

CIDR0 bits[31:8]
  RES0.

PRMBL_0, CIDR0 bits[7:0]
  0x00.

Accessing the CIDR

CIDR0-CIDR3 can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xFF0</td>
</tr>
<tr>
<td></td>
<td>0xFF4</td>
</tr>
<tr>
<td></td>
<td>0xFF8</td>
</tr>
<tr>
<td></td>
<td>0xFFC</td>
</tr>
</tbody>
</table>

D3.4.2 MEMTYPE, Memory Type Register

The MEMTYPE characteristics are:

Purpose

Identifies the type of memory present on the bus that connects to the ROM Table. In particular, it identifies whether system memory is connected to the bus.

Configurations

Included in all implementations.

Attributes

A 32-bit register.

Field descriptions

The MEMTYPE bit assignments are:

<table>
<thead>
<tr>
<th>Bits[31:1]</th>
<th>Reserved, RES0.</th>
</tr>
</thead>
<tbody>
<tr>
<td>31</td>
<td>RES0</td>
</tr>
<tr>
<td>30</td>
<td></td>
</tr>
<tr>
<td>29</td>
<td></td>
</tr>
<tr>
<td>...</td>
<td></td>
</tr>
<tr>
<td>0</td>
<td></td>
</tr>
</tbody>
</table>
SYSMEM, bit[0]

System memory present. Indicates whether system memory is present on the bus that connects to the ROM Table. The possible values are:

0b0 System memory not present on bus. This value indicates that the bus is a dedicated debug bus.
0b1 System memory is also present on this bus.

MEMTYPE.SYSMEM indicates the memory accesses that the ADI can make:

When SYSMEM is 0b0

The ROM Table indicates all the valid addresses in the memory system that the ADI is connected to, and the result of accessing any other address is UNPREDICTABLE. For more information, see The component address on page D2-229.

When SYSMEM is 0b1

There might be other valid addresses in the memory system that the ADI is connected to. The result of accessing these addresses is IMPLEMENTATION DEFINED, and:

- The ADI specification does not include any mechanism that the debugger can use to discover what addresses it can access, other than the addresses that are listed in the ROM Table.
- If the ADI accesses addresses that are not in the ROM Table, there can be side effects on the system that the ADI is connected to.

Accessing MEMTYPE

MEMTYPE can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xFCC</td>
</tr>
</tbody>
</table>

D3.4.3 PINDR0-PIDR7, Peripheral Identification Registers

This section describes the bit assignments for ROM Table components. For a full description of the PIDR, see PINDR0-PIDR7, Peripheral Identification Registers on page D1-220.

The PIDR characteristics are:

Purpose

Provide information to identify a CoreSight component.

Usage constraints

PIDR0-PIDR7 are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
</tr>
</tbody>
</table>

Configurations

Included in all implementations.

Attributes

PIDR0-PIDR7 are eight 32-bit management registers.
Field descriptions

The PIDR bit assignments are:

<table>
<thead>
<tr>
<th>PIDR_3</th>
<th>31</th>
<th>8</th>
<th>7</th>
<th>4</th>
<th>3</th>
<th>0</th>
<th>0xFEC</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>RES0</td>
<td>REVAND</td>
<td>CMOD</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PIDR_2</th>
<th>31</th>
<th>8</th>
<th>7</th>
<th>4</th>
<th>3</th>
<th>2</th>
<th>0</th>
<th>0xFE8</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>RES0</td>
<td>REVISION</td>
<td>DES_1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PIDR_1</th>
<th>31</th>
<th>8</th>
<th>7</th>
<th>4</th>
<th>3</th>
<th>0</th>
<th>0xFE4</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>DES_0</td>
<td>PART_1</td>
<td>0xFE</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PIDR_0</th>
<th>31</th>
<th>8</th>
<th>7</th>
<th>0</th>
<th>0</th>
<th>0xFE0</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>PART_0</td>
<td>0xFO</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PIDR_7</th>
<th>31</th>
<th>0</th>
<th>0</th>
<th>0xFDC</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>0xFD</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PIDR_6</th>
<th>31</th>
<th>0</th>
<th>0</th>
<th>0xFD8</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>0xFD</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PIDR_5</th>
<th>31</th>
<th>0</th>
<th>0</th>
<th>0xFD4</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>0xFD</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PIDR_4</th>
<th>31</th>
<th>8</th>
<th>7</th>
<th>4</th>
<th>3</th>
<th>0</th>
<th>0xFD0</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>SIZE</td>
<td>DES_2</td>
<td>0xFD</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

PIDR3 bits[31:8]

RES0.

REVAND, PIDR3 bits[7:4]

See register descriptions in *PIDR0-PIDR7, Peripheral Identification Registers on page D1-220.*

CMOD, PIDR3 bits[3:0]

See register descriptions in *PIDR0-PIDR7, Peripheral Identification Registers on page D1-220.*

PIDR2 bits[31:8]

RES0.

REVISION, PIDR2 bits[7:4]

See register descriptions in *PIDR0-PIDR7, Peripheral Identification Registers on page D1-220.*
JEDEC, PIDR2 bits[3]

0b1

DES_1, PIDR2 bits[2:0]
See register descriptions in PIDR0-PIDR7, Peripheral Identification Registers on page D1-220.

PIDR1 bits[31:8]
RES0.

DES_0, PIDR1 bits[7:4]
See register descriptions in PIDR0-PIDR7, Peripheral Identification Registers on page D1-220.

PART_1, PIDR1 bits[3:0]
See register descriptions in PIDR0-PIDR7, Peripheral Identification Registers on page D1-220.

PIDR0 bits[31:8]
RES0.

PART_0, PIDR0 bits[7:0]
See register descriptions in PIDR0-PIDR7, Peripheral Identification Registers on page D1-220.

PIDR7 bits[31:0]
RES0.

PIDR6 bits[31:0]
RES0.

PIDR5 bits[31:0]
RES0.

PIDR4 bits[31:8]
RES0.

SIZE, PIDR4 bits[7:4]
0x0 A ROM Table occupies a single 4KB block of memory.

DES_2, PIDR4 bits[3:0]
See register descriptions in PIDR0-PIDR7, Peripheral Identification Registers.

Accessing the PIDR

PIDR0-PIDR7 can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>PIDR0</td>
<td>0xFE0</td>
</tr>
<tr>
<td>PIDR1</td>
<td>0xFE4</td>
</tr>
<tr>
<td>PIDR2</td>
<td>0xFE8</td>
</tr>
<tr>
<td>PIDR3</td>
<td>0xFEC</td>
</tr>
<tr>
<td>PIDR4</td>
<td>0xFD0</td>
</tr>
<tr>
<td>PIDR5</td>
<td>0xFD4</td>
</tr>
<tr>
<td>PIDR6</td>
<td>0xFD8</td>
</tr>
<tr>
<td>PIDR7</td>
<td>0xFDC</td>
</tr>
</tbody>
</table>

D3.4.4 ROMENTRY<n>, Class 0x1 ROM Table entries

A Class 0x1 ROM Table contains up to 960 ROM Table entries. Each entry that is present, ROMENTRY<n>, describes a single component, component n.
The series of ROM Table entries start at the base address of the ROM Table. The value of a ROMENTRY\(<n>\) depends on the subsystem that is implemented.

The ROMENTRY\(<n>\) characteristics are:

**Purpose**

Describes a single debug component within the system.

**Usage constraints**

The ROMENTRY\(<n>\) registers are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th>RO</th>
</tr>
</thead>
</table>

**Configurations**

Included in all implementations.

**Attributes**

ROMENTRY\(<n>\) are up to 512 32-bit registers.

**Field descriptions**

The ROMENTRY\(<n>\) bit assignments are:

<table>
<thead>
<tr>
<th>31</th>
<th>12</th>
<th>11</th>
<th>9</th>
<th>8</th>
<th>4</th>
<th>3</th>
<th>2</th>
<th>1</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>OFFSET</td>
<td>RES0</td>
<td>POWERID</td>
<td>RES0</td>
<td>POWERIDVALID</td>
<td>FORMAT</td>
<td>PRESENT</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

0x000+n×4

**OFFSET, bits[31:12]**

The address of the component, relative to the base address of this ROM Table. Negative values are permitted, using two’s complement.

**Note**

If FORMAT and PRESENT both have a value that is not equal to 0b0, OFFSET must not be zero, because a zero address offset points back to the ROM Table that contains this ROMENTRY\(<n>\).

For more information, see *The component address on page D2-229*.

**Bits[11:9]**

RES0.

**POWERID, bits[8:4]**

The Power domain ID of the component. This field:

- Supports up to 32 Power domains using values 0x00 to 0x1F.
- Is only valid if the POWERIDVALID field, which consists of bit[2] of the same ROM Table entry, is 0b1, otherwise this field must be RAZ.

For more information about Power domains, see the *CoreSight Architecture Specification*.

**Bit[3]**

RES0.
POWERIDVALID, bit[2]
Indicates if the Power domain ID field contains a Power domain ID:
- 0b0: A Power domain ID is not provided.
- 0b1: The POWERID field, which consists of bits[8:4] of the same ROM Table entry, provides a Power domain ID.

FORMAT, bit[1]
Indicates the format of the ROM Table. This field has the following value:
- RAO: 32-bit ROM Table format.

PRESENT, bit[0]
Indicates whether an entry is present at this location in the ROM Table. This field can have one of the following values:
- 0b0: The ROM entry is not present.
- 0b1: The ROM entry is present.

For more information, see *ROM Table entries that are marked not present* on page D3-238.

Accessing the ROMENTRY<n>
The ROMENTRY<n> for component $n$ can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>$0x000 + n \times 4$</td>
</tr>
</tbody>
</table>
Chapter D4
Class 0x9 ROM Tables

The chapter describes Class 0x9 ROM Tables.

It includes the following sections:
- About Class 0x9 ROM Tables on page D4-250.
- Class 0x9 ROM Table summary on page D4-251.
- Use of power domain IDs on page D4-254
- Reset control on page D4-260
- Register descriptions on page D4-262.
D4.1 About Class 0x9 ROM Tables

In a Class 0x9 ROM Table implementation:

- The Component class field, CIDR1.CLASS, is 0x9, identifying the component as a CoreSight component.
- The Component Architecture Register, DEVARCH, identifies the component as a Class 0x9 ROM Table.

Class 0x9 ROM Tables can be used alongside Class 0x1 ROM Tables, and both Class 0x9 and Class 0x1 ROM Tables might be present in systems with an ADIv5-compliant interface.

See also:

- For general information about ROM Tables, see Chapter D2 About ROM Tables.
- For information about the Component and Peripheral ID Registers, see Chapter D1 Component and Peripheral ID Registers. The class configuration is described in the field description of the CIDR1.CLASS field, in section CIDR0-CIDR3, Component Identification Registers on page D1-217.
- For information about Class 0x1 ROM Tables, see Chapter D3 Class 0x1 ROM Tables.
D4.2 Class 0x9 ROM Table summary

This section summarizes the characteristics of Class 0x9 ROM Tables.

D4.2.1 Class 0x9 ROM Table Layout

Table D4-1 shows the Class 0x9 ROM Table registers, in order of their address offset in the 4KB block where the programmers’ model resides. For detailed descriptions of each register, see Register descriptions on page D4-262.

A Class 0x9 ROM Table:

- Occupies a single 4KB block of memory, and starts at offset 0x000 in this block.
- Has a series of entries, each of which is a register.
- Has a final entry, which is one of the following:
  - A marker that signals the end of the ROM Table, which is an entry that is all zeroes.
  - A regular entry at offset 0x7FC. A ROM Table entry at this offset is always the final entry, even if its PRESENT field does not have the value 0b00.
- Almost always has an unused area between the final entry of the ROM Table and the start of the reserved area at offset 0x800. This unused area is RES0. If a ROM Table contains 512 entries, there is no unused area.

Table D4-1 ROM Table register summary

<table>
<thead>
<tr>
<th>Offset</th>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x000 to (N–1)×4</td>
<td>RO</td>
<td>ROMENTRY&lt;n&gt;</td>
<td>Up to 512 ROM Table entries. The end of the area that contains ROM Table entries is IMPLEMENTATION DEFINED, and depends on the number of ROM Table entries, which is denoted N.</td>
</tr>
<tr>
<td>N×4</td>
<td>RO</td>
<td>ROMENTRY&lt;n&gt;</td>
<td>Marker that indicates the final entry in a ROM Table with fewer than 512 entries. The offset of this entry depends on the number of ROM Table entries, which is denoted N. See also ROM Table entries that are marked not present on page D4-253.</td>
</tr>
<tr>
<td>(N+1)×4 to 0x7FC</td>
<td>-</td>
<td>Unused area of the ROM Table.</td>
<td>RES0. The offset depends on the number of ROM Table entries, which is denoted N. This area is not present if N is 512. See also ROM Table entries that are marked not present on page D4-253.</td>
</tr>
<tr>
<td>0x800 - 0x9FC</td>
<td>-</td>
<td>Reserved.</td>
<td>RES0.</td>
</tr>
</tbody>
</table>

Reserved area

<table>
<thead>
<tr>
<th>Offset</th>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xA00 - 0xA7C</td>
<td>RW</td>
<td>DBGPCR&lt;n&gt;</td>
<td>Debug Power Control Registers.</td>
</tr>
<tr>
<td>0xA80 - 0xAF0</td>
<td>RW</td>
<td>DBGPSR&lt;n&gt;</td>
<td>Debug Power Status Registers.</td>
</tr>
<tr>
<td>0xB00 - 0xB7C</td>
<td>RW</td>
<td>SYSPCR&lt;n&gt;</td>
<td>System Power Control Registers.</td>
</tr>
<tr>
<td>0xB80 - 0xBF0</td>
<td>RW</td>
<td>SYSPSR&lt;n&gt;</td>
<td>System Power Status Registers.</td>
</tr>
<tr>
<td>0xC00</td>
<td>RO</td>
<td>PRIDR0</td>
<td>Power Reset Identification Register 0.</td>
</tr>
<tr>
<td>0xC04 - 0xC0C</td>
<td>RO</td>
<td>PRIDR0</td>
<td>RES0.</td>
</tr>
</tbody>
</table>
Table D4-1 ROM Table register summary (continued)

<table>
<thead>
<tr>
<th>Offset</th>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xC10</td>
<td>RW</td>
<td>DBGRST RR</td>
<td>Debug Reset Request Register.</td>
</tr>
<tr>
<td>0xC14</td>
<td>RO</td>
<td>DBGRSTAR</td>
<td>Debug Reset Acknowledge Register.</td>
</tr>
<tr>
<td>0xC18</td>
<td>RW</td>
<td>SYSRST RR</td>
<td>System Reset Request Register.</td>
</tr>
<tr>
<td>0xC1C</td>
<td>RO</td>
<td>SYSRSTAR</td>
<td>System Reset Acknowledge Register.</td>
</tr>
<tr>
<td>0xC20–0xCF C</td>
<td>-</td>
<td>-</td>
<td>RES0.</td>
</tr>
<tr>
<td>0xD00–0xEFC</td>
<td>-</td>
<td>-</td>
<td>RES0.</td>
</tr>
</tbody>
</table>

### CoreSight management registers

<table>
<thead>
<tr>
<th>Offset</th>
<th>Type</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xF00</td>
<td>RW</td>
<td>ITCTRL</td>
<td>Integration Mode Control Register.</td>
</tr>
<tr>
<td>0xF04–0xF9C</td>
<td>-</td>
<td>-</td>
<td>RES0.</td>
</tr>
<tr>
<td>0xFA0</td>
<td>RW</td>
<td>CLAIMSET</td>
<td>Claim Tag Registers.</td>
</tr>
<tr>
<td>0xFA4</td>
<td>RW</td>
<td>CLAIMCLR</td>
<td></td>
</tr>
<tr>
<td>0xFA8</td>
<td>RO</td>
<td>DEVAFF0</td>
<td>Device Affinity Registers.</td>
</tr>
<tr>
<td>0xFB4</td>
<td>RO</td>
<td>LAR</td>
<td>Lock Access and Lock Status Registers.</td>
</tr>
<tr>
<td>0xFB8</td>
<td>RO</td>
<td>AUTHSTATUS</td>
<td>Authentication Status Register.</td>
</tr>
<tr>
<td>0xFB0</td>
<td>RO</td>
<td>DEVARCH</td>
<td>Device Architecture Register.</td>
</tr>
<tr>
<td>0xFC0</td>
<td>RO</td>
<td>DEVID2</td>
<td>Device ID Registers.</td>
</tr>
<tr>
<td>0xFC4</td>
<td>RO</td>
<td>DEVID1</td>
<td></td>
</tr>
<tr>
<td>0xFC8</td>
<td>RO</td>
<td>DEVID</td>
<td>Device ID Register.</td>
</tr>
<tr>
<td>0xFC</td>
<td>RO</td>
<td>DEVTYPE</td>
<td>Device Type Register.</td>
</tr>
<tr>
<td>0xFD0–0xFD C</td>
<td>RO</td>
<td>PIDR4-PIDR7</td>
<td>Peripheral Identification Registers.</td>
</tr>
<tr>
<td>0xFE0–0xFE C</td>
<td>RO</td>
<td>PIDR0-PIDR3</td>
<td></td>
</tr>
<tr>
<td>0xFF0–0xFF C</td>
<td>RO</td>
<td>CIDR0-CIDR3</td>
<td>Component Identification Registers.</td>
</tr>
</tbody>
</table>

a. An implementation is unlikely to require more than the maximum number of entries in a ROM Table. However, *ROM Table hierarchies* on page D2-231 describes how larger ROM Tables can be constructed.
D4.2.2 ROM Table entries that are marked *not present*

The descriptions of the debug components are stored in sequential locations in the ROM Table, starting at the ROM Table base address. However, a ROM Table entry can be marked *not present* by setting the PRESENT field of the entry to a value that indicates that the entry is not present:

- If ROMENTRY<n>.PRESENT has the value 0b10, it *is not present* and must be skipped. Do not assume that the entry represents the end of the ROM Table when scanning the ROM Table. For example, a ROM Table might be generated using static configuration tie-offs that indicate the presence or absence of particular devices, giving *not present* entries in the ROM Table.

- If ROMENTRY<n>.PRESENT has the value 0b00, it *is not present* and indicates the end of the ROM Table.
D4.3 Use of power domain IDs

If the following conditions are met, a Class 0x9 ROM Table entry, ROMENTRY<\text{n}>, has a valid power domain ID \( m \):

- ROMENTRY<\text{n}>.PRESENT is 0b1, indicating that the ROM Table entry is present.
- ROMENTRY<\text{n}>.POWERIDVALID is 0b1, indicating that the power ID is valid.
- ROMENTRY<\text{n}>.POWERID is \( m \), the power domain ID.

The mechanism to power up power domain \( m \) can be one of the following:

- If DBGPCR<\text{m}>.PRESENT reads as 0b1, the power request mechanism for DBGPCR<\text{m}>.PR is implemented, and can be used to request power for power domain \( m \), as described in the field descriptions for the DBGPCR<\text{n}>.
- If DBGPCR<\text{m}>.PRESENT reads as 0b0, the power request mechanism for power domain \( m \) is IMPLEMENTATION DEFINED.

ARM recommends that debug tools do not attempt accesses to any component with a valid power domain ID without first powering up the component.

D4.3.1 Power domain entries

The power domain ID is specific to components identified by the Class 0x9 ROM Table, which enables hierarchies of power domains to be constructed with each level enabling access to a level below.

Figure D4-1 shows an example Class 0x9 ROM Table that indicates the locations of two components, \( m \) and \( n \). Components \( m \) and \( n \) are in debug power domain 0 and 1, respectively. The debugger requests power for these power domains through the power and reset registers in the programmers’ model of ROM Table A.

![Figure D4-1 Single ROM Table with power domain IDs](image)
Figure D4-2 shows an example system with nested power domains.

In Figure D4-2, ROM Table A is the top-level ROM Table and indicates the presence of:

- Component \( m \), which is in debug power domain ID 0.
- Component \( n \), which is a Class 0x9 ROM Table, ROM Table B, in debug power domain 1.

ROM Table B indicates the presence of components \( i \) and \( j \), and power for these components is requested through the power and reset registers in the programmers’ model of ROM Table B. Because ROM Table B is in power domain 1, these power domains are subdomains of power domain 1, and are labeled 1.0 and 1.1.

The power domain IDs indicated by ROM Table B are different from the power domain IDs indicated by ROM Table A and are nested within power domain 1.

**D4.3.2 Algorithm to discover power domain IDs**

Inspect each Class 0x9 ROM Table in the system, starting at the top-level ROM Table. For each valid Class 0x9 ROM Table entry ROMENTRY\(<n>\):

1. If ROMENTRY\(<n>\).POWERIDVALID is 0b1, the power domain ID information is present. To request power for this entry, use the DBGPCR\(<n>\) register in the programmers’ model of the ROM Table, using the value of \( n \) that refers to ROMENTRY\(<n>\).
2. If ROMENTRY\(<n>\).POWERIDVALID is 0b0, no power domain ID information is present, so the component is powered.

If there are Class 0x1 ROM Tables in the system, use the algorithm that is described in Chapter D3 Class 0x1 ROM Tables, section Algorithm to discover power domain IDs to discover power domains in them.

**D4.3.3 Debug power requests**

If access to a component is needed and the ROM entry for that component has a valid power domain ID, the debugger must request power to that component before attempting to access it.
The process for issuing a power request for a debug component is shown in Figure D4-3.

![Debug power request process](image)

**Figure D4-3 Debug power request process**

A power request for a component must be removed if one of the following applies:

- The component is no longer in use. Removing the power request allows the system to consider removing power to the power domain that includes the component.
- A mechanism to preserve the component state after it is powered down is in place, for example an automated save and restore mechanism.
The process for removing a power request for a debug component is shown in Figure D4-4.

**Figure D4-4 Debug power request removal process**

### D4.3.4 System power requests

A debugger might need to access power domains that are supported by the system, but for which no power domain IDs are defined in the ROM Table. Examples include power domains for the system interconnect, and normal system memory. The power request functionality for these systems might include optional system power request controls.

It is IMPLEMENTATION DEFINED which system power domains are associated with a system power request.
The process for issuing a power request for a system component is shown in Figure D4-5.

Figure D4-5 System power request process
The process for removing a power request for a system component is shown in Figure D4-6.

![Figure D4-6 System power request removal process](image)
D4.4 Reset control

The reset control registers in the ROM Table can be used to issue reset requests:

- The debug power control registers, DBGRSTRR and DBGRSTAR, can be used to manage reset requests for up to 32 debug reset domains, as described in Debug reset control.
- The system power control registers, SYSRSTAR and DBGRSTAR, can be used to manage reset requests for up to 32 system reset domains, as described in System reset control.

For detailed descriptions of the ROM Table registers, see Register descriptions on page D4-262.

D4.4.1 Debug reset control

The DBGRSTR in a Class 0x9 ROM Table provides a debug logic reset request function.

The process for issuing a reset request for a debug component is shown in Figure D4-7. When performing a debug reset request, the debugger must proceed through each step of this process.

D4.4.2 System reset control

The SYSRSTR and SYSRSTAR in a Class 0x9 ROM Table provide a system reset request function.

When SYSRSTR.SYSRR is 0b1, the system must be held in reset. When SYSRSTR.SYSRR is 0b1, a reset of any debug logic, for example the debug interface and logic on a processor, is permitted to happen, but the debug logic must be released from reset as soon as it has been reset. Releasing the debug logic allows a debugger to configure the debug logic while holding the system in reset, resulting in the debug logic being programmed and operating immediately after the system reset is released.

Note

If SYSRSTR.SYSRR is reset by either a system reset or a debug reset, the system is not held in reset.
This function is similar to the nSRST function provided on some physical debug ports, see System reset control behavior on page B2-88.

The process for issuing a system reset request is shown in Figure D4-8. When performing a system reset request, the debugger must proceed through each step of this process.

![Figure D4-8 System reset request process](image-url)
D4.5 Register descriptions

D4.5.1 AUTHSTATUS, Authentication Status Register

The AUTHSTATUS characteristics are:

**Purpose**

AUTHSTATUS indicates whether certain functions are enabled.

**Usage constraints**

Power requests using the DBGPCR<\(n\)> or SYSPCR<\(n\)> registers are considered non-invasive debug functions and are ignored when all debug functions are disabled.

If the system supports separate Secure and Non-secure functionality, reset requests using DBGRSTRR or SYSRSTRR are considered to be Secure invasive debug functions, and are ignored when Secure invasive debug is disabled.

If the system does not support separate Secure and Non-secure functionality, reset requests using DBGRSTRR or SYSRSTRR are considered to be invasive debug functions, and are ignored when invasive debug is disabled.

If the system does not support separate Secure and Non-secure functionality, then:

- AUTHSTATUS.SNID and AUTHSTATUS.NSNID are identical.
- AUTHSTATUS.SID and AUTHSTATUS.NSID are identical.

AUTHSTATUS is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th>RO</th>
</tr>
</thead>
</table>

**Configurations**

Included in all implementations.

**Attributes**

AUTHSTATUS is a 32-bit register.

**Field descriptions**

The AUTHSTATUS bit assignments are:

<table>
<thead>
<tr>
<th>31</th>
<th>8</th>
<th>7</th>
<th>6</th>
<th>5</th>
<th>4</th>
<th>3</th>
<th>2</th>
<th>1</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>SNID</td>
<td>SID</td>
<td>NSID</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Bits[31:8]**

RES0.

**SNID, bits[7:6]**

Secure noninvasive debug.

This field can have one of the following values:

- 0000: Debug level is not supported.
- 0010: Supported and disabled.

\((SPIDEN \mid SPNIDEN) \& (DBGEN \mid NIDEN) = \text{FALSE}\).
0b11   Supported and enabled. 
      \((\text{SPIDEN} | \text{SPNIDEN}) \& (\text{DBGEN} | \text{NIDEN}) == \text{TRUE}\).

All other values are reserved.

\textbf{SID, bits[5:4]}

Secure invasive debug.
This field can have one of the following values:
0b00   Debug level is not supported.
0b10   Supported and disabled. \((\text{SPIDEN} \& \text{DBGEN}) == \text{FALSE}\).
0b11   Supported and enabled. \((\text{SPIDEN} \& \text{DBGEN}) == \text{TRUE}\).

All other values are reserved.

\textbf{NSNID, bits[3:2]}

Non-secure noninvasive debug.
This field can have one of the following values:
0b00   Debug level is not supported.
0b10   Supported and disabled. \((\text{NIDEN} \& \text{DBGEN}) == \text{FALSE}\).
0b11   Supported and enabled. \((\text{NIDEN} \& \text{DBGEN}) == \text{TRUE}\).

All other values are reserved.

\textbf{NSID, bits[1:0]}

Non-secure invasive debug.
This field can have one of the following values:
0b00   Debug level is not supported.
0b10   Supported and disabled. \text{DBGEN} == \text{FALSE}.
0b11   Supported and enabled. \text{DBGEN} == \text{TRUE}.

All other values are reserved.

\textbf{Accessing AUTHSTATUS}

AUTHSTATUS can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xFB8</td>
</tr>
</tbody>
</table>

\textbf{D4.5.2 CIDR0-CIDR3, Component Identification Registers}

This section describes the bit assignments for ROM Table components. For a full description of the CIDR, see \textit{CIDR0-CIDR3, Component Identification Registers} on page D1-217.

The CIDR characteristics are:

\textbf{Purpose}

Provide information to identify a CoreSight component.
Usage constraints

CIDR0-CIDR3 are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th>RO</th>
</tr>
</thead>
</table>

Configurations

Included in all implementations.

Attributes

CIDR0-CIDR3 are four 32-bit management registers.

Field descriptions

The CIDR bit assignments are:

<table>
<thead>
<tr>
<th>Bit Assignments</th>
</tr>
</thead>
<tbody>
<tr>
<td>31 8 7 0</td>
</tr>
<tr>
<td>CIDR3</td>
</tr>
<tr>
<td>RES0</td>
</tr>
<tr>
<td>PRMBL_3</td>
</tr>
<tr>
<td>0xFFC</td>
</tr>
<tr>
<td>31 8 7 0</td>
</tr>
<tr>
<td>CIDR2</td>
</tr>
<tr>
<td>RES0</td>
</tr>
<tr>
<td>PRMBL_2</td>
</tr>
<tr>
<td>0xFF8</td>
</tr>
<tr>
<td>31 8 7 4 3 0</td>
</tr>
<tr>
<td>CIDR1</td>
</tr>
<tr>
<td>RES0</td>
</tr>
<tr>
<td>CLASS</td>
</tr>
<tr>
<td>PRMBL_1</td>
</tr>
<tr>
<td>0xFF4</td>
</tr>
<tr>
<td>31 8 7 0</td>
</tr>
<tr>
<td>CIDR0</td>
</tr>
<tr>
<td>RES0</td>
</tr>
<tr>
<td>PRMBL_0</td>
</tr>
<tr>
<td>0xFF0</td>
</tr>
</tbody>
</table>

CIDR3 bits[31:8]

res0.

PRMBL_3, CIDR3 bits[7:0]

0x81.

CIDR2 bits[31:8]

res0.

PRMBL_2, CIDR2 bits[7:0]

0x05.

CIDR1 bits[31:8]

res0.

CLASS, CIDR1 bits[7:4]

0x9 CoreSight component.

PRMBL_1, CIDR1 bits[3:0]

0x0.
CIDR0 bits[31:8]
  RES0.

PRMBL_0, CIDR0 bits[7:0]
  0x00.

Accessing the CIDR

CIDR0-CIDR3 can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>CIDR0</td>
<td>0xFF0</td>
</tr>
<tr>
<td>CIDR1</td>
<td>0xFF4</td>
</tr>
<tr>
<td>CIDR2</td>
<td>0xFF8</td>
</tr>
<tr>
<td>CIDR3</td>
<td>0xFFC</td>
</tr>
</tbody>
</table>

D4.5.3 CLAMSCT and CLAIMCLR, Claim Tag Set Register and Claim Tag Clear Register

The characteristics of CLAIMSET and CLAIMCLR are:

**Purpose**

The Claim tag registers provide various bits that can be separately set and cleared to indicate whether functionality is in use by a debug agent.

For a Class 0x9 ROM Table, no claim tags are implemented.

**Usage constraints**

CLAIMSET and CLAIMCLR are accessible as follows:

<table>
<thead>
<tr>
<th>CLAIMSET</th>
<th>CLAIMCLR</th>
</tr>
</thead>
<tbody>
<tr>
<td>RW</td>
<td>RW</td>
</tr>
</tbody>
</table>

**Configurations**

Included in all implementations.

**Attributes**

CLAIMSET and CLAIMCLR are a set of 32-bit registers.

**Field descriptions**

The CLAIMSET and CLAIMCLR bit assignments are:

CLAIMCLR, bits[31:0]
  RAZ/WI, which corresponds to 0 claim tags being used.
CLAIMSET, bits[31:0]
RAZ/WI, which corresponds to 0 claim tags being used.

Accessing CLAIMSET and CLAIMCLR
CLAIMSET and CLAIMCLR can be accessed at the following addresses:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>CLAIMSET</td>
<td>0xFA0</td>
</tr>
<tr>
<td>CLAIMCLR</td>
<td>0xFA4</td>
</tr>
</tbody>
</table>

D4.5.4 DBGPCR<n>, Debug Power Control Registers

The DBGPCR<n> characteristics are:

**Purpose**
Power request version 0 supports up to 32 debug power domains, with separate registers for each debug domain that provide controls for power requests.

The register that controls power requests for debug power domain \( n \) is DBGPCR<n>. DBGPCR<n> is used for the following purposes:

- To indicate whether a power request mechanism is implemented for debug power domain \( n \).
- To request power to debug power domain \( n \).

**Usage constraints**
Debug power requests are ignored when all debug functionality is disabled. For details, see the description of AUTHSTATUS.

The DBGPCR<n> are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RW</td>
</tr>
</tbody>
</table>

**Configurations**
Included in all implementations.

**Attributes**
DBGPCR<n> are up to 32 32-bit registers.

**Field descriptions**
The DBGPCR<n> bit assignments are:

```
31          2  1  0
DBGPCRn       RES0  0xA00+n×4
PR
PRESENT
```

**Bits[31:2]**
RES0.
PR, bit[1]

Power request. This field can have one of the following values:

0b0 Power is not requested for debug power domain \( n \).

0b1 Power is requested for debug power domain \( n \).

This field is reserved if DBGPCR\(<n>\).PRESENT is 0b0, which indicates that power requests are not implemented for debug power domain \( n \).

PRESENT, bit[0]

This RO field is IMPLEMENTATION DEFINED, and indicates whether the power request for debug power domain \( n \) is implemented. PRESENT can have one of the following values:

0b0 Power request for debug power domain \( n \) is not implemented.

0b1 Power request for debug power domain \( n \) is implemented, and therefore DBGPCR\(<n>\).PR and DBGPSR\(<n>\) are also implemented.

If, for a ROMENTRY\(<m>\) with a POWERIDVALID value of 0b1 and a POWERID value of \( n \), a read of DBGPCR\(<n>\).PRESENT returns a value of 0b0, the mechanism to power up the debug power domain with the ID \( n \) is IMPLEMENTATION DEFINED.

ARM recommends that debug tools do not attempt accesses to components where ROMENTRY\(<m>\).POWERIDVALID is 0b1 without first powering up the component using either the DBGPCR\(<n>\) register or an IMPLEMENTATION DEFINED method.

Accessing the DBGPCR\(<n>\)

The DBGPCR\(<n>\) for debug power domain \( n \) can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xA00 + ( n \times 4 )</td>
</tr>
</tbody>
</table>

### D4.5.5 DBGPSR\(<n>\), Debug Power Status Registers

The DBGPSR\(<n>\) characteristics are:

**Purpose**

Power request version 0 supports up to 32 debug power domains, with separate registers for each domain providing controls for power requests.

The register that indicates the current power status for debug power domain \( n \) is DBGPSR\(<n>\).

**Usage constraints**

DBGPCR\(<n>\).PRESENT indicates whether this register is implemented.

The DBGPSR\(<n>\) are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th>RO</th>
</tr>
</thead>
</table>

**Configurations**

Included in all implementations.

**Attributes**

DBGPSR\(<n>\) are up to 32 32-bit registers.
Field descriptions

The DBGPSR<n> bit assignments are:

<table>
<thead>
<tr>
<th>Bit(s)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td></td>
</tr>
<tr>
<td>PS</td>
<td></td>
</tr>
<tr>
<td>0b00</td>
<td>Debug power domain n might not be powered.</td>
</tr>
<tr>
<td>0b01</td>
<td>Debug power domain n is powered.</td>
</tr>
<tr>
<td>0b10</td>
<td>Reserved.</td>
</tr>
<tr>
<td>0b11</td>
<td>Debug power domain n is powered and must remain powered until DBGPCR&lt;n&gt;.PR is set to 0b0.</td>
</tr>
</tbody>
</table>

An implementation of the power request mechanism is not expected to be capable of indicating both the 0b01 and 0b11 values of DBGPSR<n>.PS.

- When DBGPSR<n>.PS reads as 0b01, power is applied to debug power domain n. If DBGPCRn.PR is 0b1, ARM recommends that power to debug power domain n is continually maintained until DBGPCR<n>.PR is set to 0b0, to ensure that debug-related programmed state is not lost during a debug session.

- When DBGPSR<n>.PS can read as 0b11, the four-phase handshake with DBGPCR<n>.PR that is shown in Figure D4-9 guarantees that debug power domain n is powered when required:
  - At t0, DBGPCR<n>.PR is written with 0b1 to request power.
  - At t1, DBGPSR<n>.PS is set to 0b11 to indicate that the power request has been seen and power has been provided and is maintained.
  - At t2, DBGPCR<n>.PR is written with 0b0 to clear the power request.
  - At t3, DBGPSR<n>.PS is cleared to 0b00 to acknowledge that the power request has been removed.

<table>
<thead>
<tr>
<th>Time</th>
<th>BBGPCRn.PR</th>
<th>BBGPCRn.PS</th>
<th>Power status</th>
</tr>
</thead>
<tbody>
<tr>
<td>t0</td>
<td>0b00</td>
<td>0b00</td>
<td>Power not guaranteed</td>
</tr>
<tr>
<td>t1</td>
<td>0b11</td>
<td>0b11</td>
<td>Powered</td>
</tr>
<tr>
<td>t2</td>
<td>0b00</td>
<td>0b00</td>
<td>Power not guaranteed</td>
</tr>
</tbody>
</table>

Figure D4-9 Power handshake

Between t1 and t2, power must be supplied to power domain n, and must not be removed. If t1 is never reached because the system cannot power up the domain, DBGPSR<n>.PS must remain 0b00. The debugger might choose to remove the power request by writing 0b0 to DBGPCR<n>.PR, although this practice is not recommended.

DBGPCR<n>.PR must not be used to initiate a power request when DBGPSR<n>.PS reads as 0b11, because this value indicates that the handshake from a previous request is still completing.
Accessing the DBGPSR<\text{n}>

The DBGPSR<\text{n}> for debug power domain \text{n} can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xA80 + 4 \times \text{n}</td>
</tr>
</tbody>
</table>

**D4.5.6 DBGRSTAR, Debug Reset Acknowledge Register**

The DBGRSTAR characteristics are:

**Purpose**

Used to indicate that a debug reset has been completed, as an acknowledgement to a request that was made by using DBGRSTRR.

**Usage constraints**

PRIDR0.DBGRR indicates whether this register is implemented.

DBGRSTAR is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
</tr>
</tbody>
</table>

**Configurations**

Included in all implementations.

**Attributes**

DBGRSTAR is a 32-bit register.

**Field descriptions**

The DBGRSTAR bit assignments are:

\[
\begin{array}{c|c}
31 & 10 \\
\hline
& DBGR\text{A} \\
RES0 & \\
\end{array}
\]

**Bits[31:1]**

RES0.

**DBGRA, bit[0]**

Debug Reset Acknowledge:

\begin{itemize}
  \item [00] The debug reset request is not initiated or not completed.
  \item [01] The debug reset request has been completed.
\end{itemize}

After a power-on reset, this field is set to 00.
Accessing DBGRSTAR

DBGRSTAR can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xC14</td>
</tr>
</tbody>
</table>

D4.5.7  DBGRSTRR, Debug Reset Request Register

The DBGRSTRR characteristics are:

**Purpose**

DBGRSTRR is used to request a reset of debug functionality. DBGRSTRR is used with DBGRSTAR in a handshake mechanism that indicates when a reset has been completed.

**Usage constraints**

PRIDR0.DBGRR indicates whether this register is implemented. Debug reset requests are ignored when invasive debug functionality is disabled. For details, see the description of AUTHSTATUS.

DBGRSTRR is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RW</td>
</tr>
</tbody>
</table>

**Configurations**

Included in all implementations.

**Attributes**

DBGRSTRR is a 32-bit register.

**Field descriptions**

The DBGRSTRR bit assignments are:

![DBGRSTRR Bit Assignment Diagram]

<table>
<thead>
<tr>
<th>Bits[31:1]</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
</tr>
</tbody>
</table>

**DBGRRR, bit[0]**

Debug Reset Request:

- **0b0**: A debug reset is not requested.
- **0b1**: A debug reset is requested. The request remains asserted until this field is explicitly overwritten with the value **0b0**.

After a power-on reset, this field is set to **0b0**.
Whether a debug reset request also resets DBGRSTRR is IMPLEMENTATION DEFINED. If DBGRSTRR is reset by a debug reset, DBGRR is reset to 0b0, and the reset process is complete.

Setting DBGRSTRR.DBGRR to 0b0 when DBGRSTAR.DBGRA is not 0b1 results in UNPREDICTABLE behavior, and a debug reset might or might not occur.

**Accessing DBGRSTRR**

DBGRSTRR can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xC10</td>
</tr>
</tbody>
</table>

**D4.5.8 DEVAFF0-DEVAFF1, Device Affinity Registers**

The DEVAFF0-DEVAFF1 characteristics are:

**Purpose**

Enables a debugger to determine whether two components have an affinity with each other.

**Usage constraints**

DEVAFF0-DEVAFF1 are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
</tr>
</tbody>
</table>

**Configurations**

Included in all implementations.

**Attributes**

DEVAFF0-DEVAFF1 are two 32-bit registers.

**Field descriptions**

The DEVAFF0-DEVAFF1 bit assignments are:

```
  31 0
DEVAFF1
  31 0
DEVAFF0
```

DEVAFF0, bits[31:0]
DEVAFF1, bits[31:0]
RES0.
Accessing DEVAFF0-DEVAFF1

DEVAFF0-DEVAFF1 can be accessed at the following addresses:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>DEVAFF0</td>
<td>0xFA8</td>
</tr>
<tr>
<td>DEVAFF1</td>
<td>0xFAC</td>
</tr>
</tbody>
</table>

**D4.5.9 DEVARCH, Device Architecture Register**

The DEVARCH characteristics are:

**Purpose**

Identifies the architect and architecture of a CoreSight component.

**Usage constraints**

DEVARCH is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th>RO</th>
</tr>
</thead>
</table>

**Configurations**

Included in all implementations.

**Attributes**

DEVARCH is a 32-bit register.

**Field descriptions**

The DEVARCH bit assignments are:

<table>
<thead>
<tr>
<th>Bit</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>31</td>
<td>0x23B</td>
<td>ARM.</td>
</tr>
<tr>
<td>20</td>
<td>0b1</td>
<td>Present.</td>
</tr>
<tr>
<td>19:16</td>
<td>0x0</td>
<td>Revision 0.</td>
</tr>
</tbody>
</table>
| 15:0      | 0x0AF7| ROM Table v0. If this value of ARCHID is found, the debug tool must inspect DEVTYPE and DEVID to determine further information about the ROM Table.
Accessing DEVARCH

DEVARCH can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xFBC</td>
</tr>
</tbody>
</table>

### D4.5.10 DEVID, Device Configuration Register

The DEVID characteristics are:

**Purpose**

Indicates the capabilities of the component.

**Usage constraints**

DEVID is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
</tr>
</tbody>
</table>

**Configurations**

Included in all implementations.

**Attributes**

DEVID is a 32-bit register.

**Field descriptions**

The DEVID bit assignments are:

<table>
<thead>
<tr>
<th>Bits[31:6]</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
</tr>
</tbody>
</table>

**PRR, bit[5]**

Power Request functionality included. This field can have one of the following values:

- **0b0**  
  Power Request functionality not included. If any ROM Table entries contain power domain IDs, a GPR must be present, and pointed to by the ROM Table. The GPR provides functionality to control the power domains. 
  
  **PRIDR0** is not implemented.

- **0b1**  
  Power Request functionality included. If any ROM Table entries contain power domain IDs, they are controlled by the Power Request functionality in the ROM Table. 
  
  **PRIDR0** is implemented.

See also **PRIDR0, Power Request ID Register 0 on page D4-281.**
SYSMEM, bit[4]

System memory present. Indicates whether system memory is present on the bus that connects to the ROM Table. The possible values are:

0b0  System memory is not present on the bus. This value indicates that the bus is a dedicated debug bus.

0b1  System memory is also present on this.

SYSMEM indicates the memory accesses that the ADI can make:

When SYSMEM is 0b0

The ROM Table indicates all the valid addresses in the memory system that the ADI is connected to, and the result of accessing any other address is UNPREDICTABLE. For more information, see The component address on page D2-229.

When SYSMEM is 0b1

There might be other valid addresses in the memory system that the ADI is connected to. The result of accessing these addresses is IMPLEMENTATION DEFINED, and:

• The CoreSight v3 specification does not include any mechanism that the debugger can use to discover what addresses it can access, other than the addresses that are listed in the ROM Table.

• If the ADI accesses addresses that are not in the ROM Table, there can be side effects on the system that the ADI is connected to.

FORMAT, bits[3:0]

ROM format. This field can have one of the following values:

0x0  32-bit format 0.

Values 0x1-0xF are reserved.

Accessing DEVID

DEVID can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xFCC</td>
</tr>
</tbody>
</table>

D4.5.11  DEVID1-DEVID2, Device Configuration Registers

The DEVID1-DEVID2 characteristics are:

Purpose

Indicates the capabilities of the component.

Usage constraints

DEVID1-DEVID2 are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
</tr>
</tbody>
</table>

Configurations

Included in all implementations.
Attributes
DEVID1-DEVID2 are two 32-bit registers.

Field descriptions
The DEVID1-DEVID2 bit assignments are:

DEVID1, bits[31:0]
DEVID2, bits[31:0]
RES0.

Accessing DEVID1-DEVID2
DEVID1-DEVID2 can be accessed at the following addresses:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
<th>DEVID1</th>
<th>DEVID2</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xFC4</td>
<td>0xFC0</td>
<td></td>
</tr>
</tbody>
</table>

D4.5.12 DEVTYPE, Device Type Register
The DEVTYPE characteristics are:

Purpose
A debugger can use DEVTYPE to obtain information about a component that has an unrecognized Part number.

Usage constraints
DEVTYPE is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
<td></td>
</tr>
</tbody>
</table>

Configurations
Included in all implementations.

Attributes
DEVTYPE is a 32-bit register.
Field descriptions

The DEVTYPE bit assignments are:

```
<table>
<thead>
<tr>
<th></th>
<th></th>
<th>8</th>
<th>7</th>
<th>4</th>
<th>3</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>RES0</td>
<td></td>
<td></td>
<td>SUB</td>
<td>MAJOR</td>
<td></td>
</tr>
</tbody>
</table>
```

Bits[31:8]

RES0.

SUB, bits[7:4]

0x0 Other, undefined.

MAJOR, bits[3:0]

0x0 Miscellaneous.

Accessing DEVTYPE

DEVTYPE can be accessed at the following address:

```
<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xFCC</td>
</tr>
</tbody>
</table>
```

D4.5.13 ITCTRL, Integration Mode Control Register

The ITCTRL characteristics are:

**Purpose**

A component can use ITCTRL to dynamically switch between functional mode and integration mode.

For a Class 0x9 ROM Table, this mechanism is not implemented.

**Usage constraints**

ITCTRL is accessible as follows:

```
<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RW</td>
</tr>
</tbody>
</table>
```

**Configurations**

Included in all implementations.

**Attributes**

ITCTRL is a 32-bit register.
Field descriptions

The ITCTRL bit assignments are:

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>31:1</td>
<td>RES0</td>
</tr>
<tr>
<td>0</td>
<td>IME</td>
</tr>
</tbody>
</table>

Bits[31:1]
- RES0

IME, bit[0]
- RAZ/WI, which indicates that no integration functionality is implemented.

Accessing ITCTRL

ITCTRL can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xF00</td>
</tr>
</tbody>
</table>

D4.5.14 LAR and LSR, Software Lock Access Register and Software Lock Status Register

The LAR and LSR characteristics are:

Purpose
- The Software lock mechanism prevents accidental access to the registers of CoreSight components.
- For a Class 0x9 ROM Table, the lock mechanism is not implemented.

Usage constraints
- LAR and LSR are accessible as follows:

<table>
<thead>
<tr>
<th>LAR</th>
<th>LSR</th>
</tr>
</thead>
<tbody>
<tr>
<td>WO</td>
<td>RO</td>
</tr>
</tbody>
</table>

Configurations
- Included in all implementations.

Attributes
- LAR and LSR are two 32-bit registers.
Field descriptions

The LAR and LSR bit assignments are:

\[ \text{LSR, bits}[31:3] \]
RAZ.

\[ \text{nTT, LSR bit}[2] \]
RAZ.

\[ \text{SLK, LSR bit}[1] \]
RAZ.

\[ \text{SLI, LSR bit}[0] \]
RAZ.

\[ \text{KEY, LAR bits}[31:0] \]
WI.

Accessing LSR and LAR

LAR and LSR can be accessed at the following addresses:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>LAR</td>
<td>0xFB0</td>
</tr>
<tr>
<td>LSR</td>
<td>0xFB4</td>
</tr>
</tbody>
</table>

D4.5.15  PIDR0-PIDR7, Peripheral Identification Registers

This section describes the bit assignments for ROM Table components. For a full description of the PIDR, see *PIDR0-PIDR7, Peripheral Identification Registers* on page D1-220.

The PIDR characteristics are:

**Purpose**

Provide information to identify a CoreSight component.
Usage constraints

PIDR0-PIDR7 are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
</tr>
</tbody>
</table>

Configurations

Included in all implementations.

Attributes

PIDR0-PIDR7 are eight 32-bit management registers.

Field descriptions

The PIDR bit assignments are:

<table>
<thead>
<tr>
<th>PIDR_3</th>
<th>31</th>
<th>8</th>
<th>7</th>
<th>4</th>
<th>3</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>REVAND</td>
<td>CMOD</td>
<td>0xFE8</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PIDR_2</th>
<th>31</th>
<th>8</th>
<th>7</th>
<th>4</th>
<th>3</th>
<th>2</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>REVISION</td>
<td>1</td>
<td>DES_1</td>
<td>0xFE8</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PIDR_1</th>
<th>31</th>
<th>8</th>
<th>7</th>
<th>4</th>
<th>3</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>DES_0</td>
<td>PART_1</td>
<td>0xFE4</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

| PIDR_0 | 31 | 8 | 7 | 0 |
|--------|----|----|---|
| RES0   | PART_0 | 0xFE0 |

<table>
<thead>
<tr>
<th>PIDR_7</th>
<th>31</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>0xFD0</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PIDR_6</th>
<th>31</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>0xFD8</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PIDR_5</th>
<th>31</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>0xFD4</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PIDR_4</th>
<th>31</th>
<th>8</th>
<th>7</th>
<th>4</th>
<th>3</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td>SIZE</td>
<td>DES_2</td>
<td>0xFD0</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
REVAND, PIDR3 bits[7:4]

See register descriptions in *PIDR0-PIDR7, Peripheral Identification Registers on page D1-220*.

CMOD, PIDR3 bits[3:0]

See register descriptions in *PIDR0-PIDR7, Peripheral Identification Registers on page D1-220*.

PIDR2 bits[31:8]

RES0.

REVISION, PIDR2 bits[7:4]

See register descriptions in *PIDR0-PIDR7, Peripheral Identification Registers on page D1-220*.

JEDEC, PIDR2 bits[3]

0b1   A JEDEC value is used.

DES_1, PIDR2 bits[2:0]

See register descriptions in *PIDR0-PIDR7, Peripheral Identification Registers on page D1-220*.

PIDR1 bits[31:8]

RES0.

DES_0, PIDR1 bits[7:4]

See register descriptions in *PIDR0-PIDR7, Peripheral Identification Registers on page D1-220*.

PART_1, PIDR1 bits[3:0]

See register descriptions in *PIDR0-PIDR7, Peripheral Identification Registers on page D1-220*.

PIDR0 bits[31:8]

RES0.

PART_0, PIDR0 bits[7:0]

See register descriptions in *PIDR0-PIDR7, Peripheral Identification Registers on page D1-220*.

PIDR7 bits[31:0]

RES0.

PIDR6 bits[31:0]

RES0.

PIDR5 bits[31:0]

RES0.

PIDR4 bits[31:8]

RES0.

SIZE, PIDR4 bits[7:4]

0x0   A ROM Table occupies a single 4KB block of memory.

DES_2, PIDR4 bits[3:0]

See register descriptions in *PIDR0-PIDR7, Peripheral Identification Registers on page D1-220*.
Accessing the PIDR

PIDR0-PIDR7 can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>PIDR0</td>
</tr>
<tr>
<td>ROM Table</td>
<td>0xFE0</td>
</tr>
</tbody>
</table>

D4.5.16 PRIDR0, Power Request ID Register 0

The PRIDR0 characteristics are:

**Purpose**

Indicates the features of the power request functionality.

**Usage constraints**

PRIDR0 is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
</tr>
</tbody>
</table>

**Configurations**

Included in all implementations.

**Attributes**

PRIDR0 is a 32-bit register.

**Field descriptions**

The PRIDR0 bit assignments are:

<table>
<thead>
<tr>
<th>Bits[31:6]</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
</tr>
</tbody>
</table>

**SYSRR, bit[5]**

Indicates whether the system reset request functionality is present. This field can have one of the following values:

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0b0</td>
<td>The system reset request functionality is not implemented.</td>
</tr>
<tr>
<td>0b1</td>
<td>The system reset request functionality, and the SYSRSTRR and SYSRSTAR, which provide status information for system resets, are implemented.</td>
</tr>
</tbody>
</table>
DBGRR, bit[4]

Indicates whether the debug reset request functionality is present. This field can have one of the following values:

- 0b0: The debug reset request functionality is not implemented.
- 0b1: The system reset request functionality, and the DBGRSTRR and DBGRSTAR, which provide status information for debug resets, are implemented.

VERSION, bits[3:0]

Indicates the version of the reset request functionality. This field can have one of the following values:

- 0b0000: The power request functionality is not implemented.
- 0b0001: The power request functionality version 0, and the DBGPCR<n>, DBGPSR<n>, SYSPCR<n>, and SYSPSR<n>, which provide controls for power requests, are implemented.
- Values 0b0010 - 0b1111 are reserved.

Accessing PRIDR0

PRIDR0 can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xC00</td>
</tr>
</tbody>
</table>

D4.5.17 ROMENTRY<n>, Class 0x9 ROM Table entries

The ROMENTRY<n> characteristics are:

Purpose

A Class 0x9 ROM Table contains up to 512 ROM Table entries. Each entry that is present, ROMENTRY<n>, provides the address offset of the address space of one CoreSight component, component n, along with information about its power domain.

Note

For ADIv5 implementations, ROM Table entries must be 32 bits wide.

The series of ROM Table entries starts at the base address of the Class 0x9 ROM Table:

- The first entry, entry 0, has offset 0x000.
- ROMENTRY<n> has the offset 0x000 + n×4, where 0 ≤ n ≤ 511.
- If the number of components, N, is lower than the maximum supported number, 512, the offsets of the ROM Table entries are in the following range:
  - ROM Table entries representing components have offsets from 0x000 to (N−1)×4.
  - The ROMENTRY<n> at offset N×4, which has a PRESENT field with the value 0b00, indicates the end of the ROM Table.
- If the number of components is equal to the maximum supported number, the ROM Table entries have offsets from 0x000 to 0x7FC. If a ROM Table entry is present at offset 0x7FC, its PRESENT field must have a value of either 0b00 or 0b11, and it must be interpreted as the final entry of the ROM Table, even if its PRESENT field has the value 0b11.

A component that requires differentiation between external and internal accesses may provide two views, one for internal and one for external accesses. For these components, ARM strongly recommends that ROM Tables provide a pointer only to the external view. See also ROM Table hierarchies on page D2-231.
Usage constraints

A ROM Table does not have to use power domain IDs. If none of the ROM Table entries provides a power domain ID, all the components that pointed to by the ROM Table are in the same power domain as the ROM Table. For more information, see Use of power domain IDs on page D4-254.

ARM recommends the power requestor that is described in the CoreSight Architecture Specification.

The ROMENTRY<\texttt{n}> are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
</tr>
</tbody>
</table>

Configurations

Included in all implementations.

Attributes

ROMENTRY<\texttt{n}> are up to 512 32-bit registers.

Field descriptions

The ROMENTRY<\texttt{n}> bit assignments are:

\[
\begin{array}{cccccccc}
31 & 12 & 11 & 9 & 8 & 4 & 3 & 2 & 1 & 0 \\
\hline
\text{OFFSET} & \text{RES0} & \text{POWERID} & \text{RES0} & \text{POWERIDVALID} & \text{FORMAT} & \text{PRESENT} \\
\end{array}
\]

OFFSET, bits[31:12]

The component address, relative to the base address of this ROM Table. The component address is calculated using the following equation:

\[
\text{Component Address} = \text{ROM Table Base Address} + (\text{OFFSET} \ll 12).
\]

If a component occupies more than a single 4KB block, OFFSET points to the 4KB block which contains the Peripheral ID and Component ID registers for the component.

Negative values of OFFSET are permitted, using two’s complement.

---

**Note**

If FORMAT and PRESENT both have a value that is not equal to \texttt{0b0}, OFFSET must not be zero, because a zero address offset points back to the ROM Table that contains this ROMENTRY<\texttt{n}>.

See also The component address on page D2-229.

Bits[11:9]

RES0.

POWERID, bits[8:4]

The power domain ID of the component. This field:

- Supports up to 32 power domains using values \texttt{0x00} to \texttt{0x1F}.
- Is only valid if the POWERIDVALID field, which consists of bit[2] of the same ROMENTRY<\texttt{n}>, is \texttt{0b1}, otherwise this field must be \texttt{RES0}.

Bit[3]

RES0.

POWERIDVALID, bit[2]
Indicates if the Power domain ID field contains a Power domain ID:

0b0    A power domain ID is not provided.
0b1    The POWERID field, which consists of bits[8:4] of the same ROMENTRY<n>, provides a power domain ID.

PRESENT, bits[1:0]
Indicates whether an entry is present at this location in the ROM Table. This field can have one of the following values:

0b00    The ROM entry is not present, and this ROMENTRY<n> is the final entry in the ROM Table. If PRESENT has this value, all other fields in this ROMENTRY<n> must be zero.
0b01    Reserved.
0b10    The ROM entry is not present, and this ROMENTRY<n> is not the final entry in a ROM Table with fewer than 512 entries. If PRESENT has this value, all other fields in this entry are UNKNOWN.
0b11    The ROM Entry is present.

If the number of components is 512, the last ROM Table entry is not required to have a PRESENT field with the value 0b00.

Accessing the ROMENTRY<n>

The ROMENTRY<n> for component n can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0x000 + n×4</td>
</tr>
</tbody>
</table>

D4.5.18 SYSPCR<n>, Debug Power Control Registers

The SYSPCR<n> characteristics are:

Purpose

Power request version 0 supports up to 32 system power domains, with separate registers for each domain providing controls for power requests.

The register that controls power requests for system power domain n is SYSPCR<n>. SYSPCR<n> is used for the following purposes:

• To indicate whether a power request mechanism is implemented for system power domain n.
• To request power to system power domain n.

Usage constraints

System power requests are ignored when all debug functionality is disabled. For details, see the description of AUTHSTATUS.

The SYSPCR<n> are accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th>RW</th>
</tr>
</thead>
</table>

### Configurations

Included in all implementations.

### Attributes

SYSPCR<\(n\)> are up to 32 32-bit registers.

### Field descriptions

The SYSPCR<\(n\)> bit assignments are:

```
+-------------------+-------------------+
| 31:2              | 2:1:0             |
| RES0              | 0xB00+n*4         |
+-------------------+-------------------+
| PR                | PRESENT           |
+-------------------+-------------------+
| Number of registers, 31:0 | 2:1:0             |
+-------------------+-------------------+
```

**Bits[31:2]**

`RES0`.

**PR, bit[1]**

Power request. This field can have one of the following values:

- **0b0**: Power is not requested for system power domain \(n\).
- **0b1**: Power is requested for system power domain \(n\).

This field is reserved if power requests are not implemented for system power domain \(n\), which is the case if SYSPCR<\(n\>).PRESENT has the value 0b0.

**PRESENT, bit[0]**

This RO field indicates whether the power request for system power domain \(n\) is implemented. PRESENT can have one of the following values:

- **0b0**: Power request for system power domain \(n\) is not implemented.
- **0b1**: Power request for system power domain \(n\) is implemented, and therefore SYSPCR<\(n\>).PR and SYSPSR<\(n\)> are also implemented.

### Accessing the SYSPCR<\(n\)>

The SYSPCR<\(n\)> for system power domain \(n\) can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xB00 + n*4</td>
</tr>
</tbody>
</table>

### D4.5.19 SYSPSR<\(n\)>, System Power Status Registers

The SYPSR<\(n\)> characteristics are:

**Purpose**

Power request version 0 supports up to 32 system power domains, with separate registers for each domain providing controls for power requests.

The register that indicates the current power status for system power domain \(n\) is SYSPSR<\(n\)>.

**Usage constraints**

SYSPCR<\(n\>).PRESENT indicates whether this register is implemented.
The SYSPSR<\text{n}> are accessible as follows:

**Default**

**RO**

<table>
<thead>
<tr>
<th>31 0</th>
<th>RES0</th>
<th>PS</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xB80+n*4</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Configurations

Included in all implementations.

### Attributes

SYSPSR<\text{n}> are up to 32 32-bit registers.

### Field descriptions

The SYSPSR<\text{n}> bit assignments are:

- **Bits[31:2]**
  - RES0.

- **PS, bits[1:0]**
  - Power status of system power domain \text{n}. This field can have one of the following values:
    - 0b00: System power domain \text{n} might not be powered.
    - 0b01: System power domain \text{n} is powered.
    - 0b10: Reserved.
    - 0b11: System power domain \text{n} is powered and must remain powered until SYSPCR<\text{n}>.PR is set to 0b0.

An implementation of the power request mechanism is not expected to be capable of indicating both the 0b01 and 0b11 values of SYSPSR<\text{n}>.PS.

- When SYSPSR<\text{n}>.PS reads as 0b01, power is applied to system power domain \text{n}. If SYSPCR<\text{n}>.PR is 0b1, ARM recommends that power to system power domain \text{n} is continually maintained until SYSPCR<\text{n}>.PR is set to 0b0, to ensure that system-related programmed state is not lost during a debug session.

- When SYSPSR<\text{n}>.PS can read as 0b11, the four-phase handshake with SYSPCR<\text{n}>.PR that is shown in Figure D4-10 on page D4-287 guarantees that system power domain \text{n} is powered when required:
  - At t0, SYSPCR<\text{n}>.PR is written with 0b1 to request power.
  - At t1, SYSPSR<\text{n}>.PS is set to 0b11 to indicate that the power request has been seen and power has been provided and is maintained.
  - At t2, SYSPCR<\text{n}>.PR is written with 0b0 to clear the power request.
  - At t3, SYSPSR<\text{n}>.PS is cleared to 0b00 to acknowledge that the power request has been removed.
Between t1 and t2, power must be supplied to power domain n, and must not be removed. If t1 is never reached because the system cannot power up the domain, SYSPSR<n>.PS must remain 0b00. The debugger might choose to remove the power request by writing 0b0 to SYSPCR<n>.PR, although this practice is not recommended. SYSPCR<n>.PR must not be used to initiate a power request when SYSPSR<n>.PS reads as 0b11, because this value indicates that the handshake from a previous request is still completing.

### Accessing the SYSPSR<n>

The SYSPSR<n> for system power domain n can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xB80 + n×4</td>
</tr>
</tbody>
</table>

---

**D4.5.20 SYSRSTAR, System Reset Acknowledge Register**

The SYSRSTAR characteristics are:

**Purpose**

Used to indicate that a system reset has been completed, as an acknowledgement to a request that was made by using SYSRSTRR.

**Usage constraints**

PRIDR0.SYSRR indicates whether this register is implemented.

SYSRSTAR is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>RO</td>
<td></td>
</tr>
</tbody>
</table>

**Configurations**

Included in all implementations.

**Attributes**

SYSRSTAR is a 32-bit register.
Field descriptions

The SYSRSTAR bit assignments are:

<table>
<thead>
<tr>
<th>Bits[31:1]</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>RES0</td>
<td></td>
</tr>
</tbody>
</table>

SYSRA, bit[0]

System Reset Acknowledge:

- 0b0: The system reset request is not initiated or not completed.
- 0b1: The system reset request has been completed.

After a power-on reset, this field is set to 0b0.

Accessing SYSRSTAR

SYSRSTAR can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xC1C</td>
</tr>
</tbody>
</table>

D4.5.21 SYSRSTRR, System Reset Request Register

The SYSRSTRR characteristics are:

Purpose

SYSRSTRR is used to request a reset of the entire system or subsystem. The scope of this reset is IMPLEMENTATION DEFINED.

SYSRSTRR is used with SYSRSTAR in a handshake mechanism that indicates when a reset has been completed.

Usage constraints

PRIDR0.SYSRR indicates whether this register is implemented.

System reset requests are ignored when invasive debug functionality is disabled. For details, see the description of the AUTHSTATUS register.

SYSRSTRR is accessible as follows:

<table>
<thead>
<tr>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>RW</td>
</tr>
</tbody>
</table>

Configurations

Included in all implementations.

Attributes

SYSRSTRR is a 32-bit register.
Field descriptions

The SYSRSTR bit assignments are:

```
  31  1  0
     |   |
     RES0

SYSRR
```

**Bits[31:1]**

RES0.

**SYSRR, bit[0]**

System Reset Request:

- 0b0: A system reset is not requested.
- 0b1: A system reset is requested. The request remains asserted until this field is explicitly overwritten with the value 0b0.

After a power-on reset, this field is set to 0b0.

**Accessing SYSRSTRR**

SYSRSTRR can be accessed at the following address:

<table>
<thead>
<tr>
<th>Component</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM Table</td>
<td>0xC18</td>
</tr>
</tbody>
</table>
Part E
Appendixes
Appendix E1
Standard Memory Access Port Definitions

This appendix provides information on implementing the Memory Access Port (MEM-AP). It contains the following sections:

- *AMBA AXI3 and AXI4* on page E1-295.
- *AMBA AXI4 with ACE-Lite* on page E1-297.
- *AMBA AHB3* on page E1-300.
- *AMBA AHB5* on page E1-302.
- *AMBA APB2 and APB3* on page E1-304.
E1.1 Introduction

The Memory Access Port (MEM-AP) programmers’ model includes IMPLEMENTATION DEFINED features. This appendix provides reference implementation options for implementers and users of MEM-APs when connecting to standard memory interfaces. In particular, it provides the recommended interpretations of the following fields:

- CSW.Prot.
- CSW.SPIDEN.
- CSW.Type.
- CSW.AddrInc.
- CSW.Size.
E1.2 AMBA AXI3 and AXI4

This section describes the implementation of the CSW register for AMBA AXI3 and AXI4 implementations. For more information, see AMBA® AXI™ and ACE™ Protocol Specification AXI3™, AXI4™, and AXI4-Lite™, ACE and ACE-Lite™.

E1.2.1 CSW register implementation

DbgSwEnable, bit[31]

See CSW, Control/Status Word register on page C2-176.

Prot, bits[30:24]

For reads, the CSW.Prot field drives the AXI ARCACHE and ARPROT signals.

For writes, the CSW.Prot field drives the AXI AWCACHE and AWPROT signals.

The settings for the CSW.Prot field are:

PROT[2:0], bits[30:28]

Drives AxPROT[2:0], where x is R for reads and W for writes, see Table E1-1.

<table>
<thead>
<tr>
<th>Bit</th>
<th>ARPROT signal</th>
<th>AWPROT signal</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>28</td>
<td>ARPROT[0]</td>
<td>AWPROT[0]</td>
<td>Privileged</td>
</tr>
</tbody>
</table>

CSW.Prot[29], Non-secure, specifies a non-secure transfer. Its behavior depends on the vale of CSW.SPIDEN. For values in CSW.Prot[29]:

0b1  Non-secure transfer requested. ARPROT[1] or AWPROT[1] is HIGH.

0b0  Secure transfer requested. If CSW.SPIDEN is 0b1, ARPROT[1] or AWPROT[1] is LOW. If CSW.SPIDEN is 0b0, no transfer is initiated, and ARM recommends that an error response is returned to the DP if an access is made to the DRW or Banked Data registers.
CACHE[3:0], bits[27:24]
Drives AxCACHE[3:0], where x is R for reads and W for writes, see Table E1-2.

<table>
<thead>
<tr>
<th>Bit</th>
<th>ARCACHE signal</th>
<th>AWCACHE signal</th>
</tr>
</thead>
<tbody>
<tr>
<td>24</td>
<td>ARCACHE[0]</td>
<td>AWCACHE[0]</td>
</tr>
</tbody>
</table>

Note
AMBA AXI4 requires asymmetrical usage of ARCACHE and AWCACHE.

The reset value of CSW.Prot is 0b01100000.

SPIDEN, bit[23]
The CSW.SPIDEN bit reflects the state of the CoreSight authentication signal, SPIDEN.

Bits[22:16]
RES0.

Type, bits[15:12]
RES0.

Mode, bits[11:8]
RES0.

TrInProg, bit[7]
See CSW, Control/Status Word register on page C2-176.

DeviceEn, bit[6]
See CSW, Control/Status Word register on page C2-176.

AddrInc, bits[5:4]
CSW.AddrInc supports the Increment Packed mode of transfer. See Packed transfers on page C2-158.

Bit[3]
RES0.

Size, bits[2:0]
CSW.Size must support word, half-word, and byte size accesses. It is IMPLEMENTATION DEFINED whether larger access sizes are supported.
E1.3 AMBA AXI4 with ACE-Lite

This section describes the register implementation for AMBA AXI4 implementations with ACE-Lite. For more information, see the *AMBA® AXI™ and ACE™ Protocol Specification AXI3™, AXI4™, and AXI4-Lite™*, *ACE and ACE-Lite™*.

The following registers are covered:

- CSW register implementation.
- MBT register implementation on page E1-299.

E1.3.1 CSW register implementation

![Register Diagram]

DbgSwEnable, bit[31]

See [CSW, Control/Status Word register](#) on page C2-176.

Prot, bits[30:24]

For reads, the CSW.Prot field drives the AXI ARCACHE and ARPROT signals.

For writes, the CSW.Prot field drives the AXI AWCACHE and AWPROT signals.

The settings for the CSW.Prot field are:

- **PROT[2:0]**, bits[30:28]: Drives AXPROT[2:0], where x is R for reads and W for writes, see Table E1-3.
- **CSW.Prot[29]**, Non-secure, specifies a non-secure transfer. Its behavior depends on the value of CSW.SPIDEN. For values in CSW.Prot[29]:
  - **0b1**: Non-secure transfer requested. ARPROT[1] or AWPROT[1] is HIGH.
  - **0b0**: Secure transfer requested. If CSW.SPIDEN is 0b1, ARPROT[1] or AWPROT[1] is LOW. If CSW.SPIDEN is 0b0, no transfer is initiated, and ARM recommends that an error response is returned to the DP if an access is made to the DRW or Banked Data registers.

<table>
<thead>
<tr>
<th>Bit</th>
<th>ARPROT signal</th>
<th>AWPROT signal</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>28</td>
<td>ARPROT[0]</td>
<td>AWPROT[0]</td>
<td>Privileged</td>
</tr>
</tbody>
</table>
CACHE[3:0], bits[27:24]

Drives AxCACHE[3:0], where x is R for reads and W for writes, see Table E1-4.

--- Note ---

AMBA AXI4 requires asymmetrical usage of ARCACHE and AWCACHE.

The reset value of CSW.Prot is 0b01100000.

SPIDEN, bit[23]

The CSW.SPIDEN bit reflects the state of the CoreSight authentication signal, SPIDEN.

Bits[22:16]

RES0.

Type, bits[15:12]

The CSW.Type field drives the AXI AxDOMAIN signals, where x is R for reads and W for writes.

The settings for the CSW.Type bit field are:

<table>
<thead>
<tr>
<th>Bit</th>
<th>ARCACHE signal</th>
<th>AWCACHE signal</th>
</tr>
</thead>
<tbody>
<tr>
<td>24</td>
<td>ARCACHE[0]</td>
<td>AWCACHE[0]</td>
</tr>
</tbody>
</table>

The reset value of this field is 0b11.

EnMBT, bit[12]

Enable MBT accesses.

It is IMPLEMENTATION DEFINED whether this field is RW or RAO. If it is RW, the reset value is 0b0, and must be set to 0b1 before writing to the MBT register.

Mode, bits[11:8]

It is IMPLEMENTATION DEFINED whether this field is RW or RO. If it is RW, the reset value is 0b0000, and must be set to 0b0001 before writing to the MBT register. If it is RO, then it has the fixed value 0b0001.

TrInProg, bit[7]

See CSW, Control/Status Word register on page C2-176.

DeviceEn, bit[6]

See CSW, Control/Status Word register on page C2-176.
AddrInc, bits[5:4]

CSW.AddrInc supports the Increment Packed mode of transfer. See Packed transfers on page C2-158.

Bit[3]

RES0.

Size, bits[2:0]

CSW.Size must support word, half-word, and byte size accesses. It is IMPLEMENTATION DEFINED whether larger access sizes are supported.

E1.3.2 MBT register implementation

<table>
<thead>
<tr>
<th>31</th>
<th>30</th>
<th>29</th>
<th>28</th>
<th>27</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>RES0</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>BarTran</td>
<td>Bit [0]</td>
</tr>
</tbody>
</table>

Attributes

MBT register is a read/write register.

Bits[31:3]

Reserved, RES0.

BarTran, bits[2:1]

Possible values are:
0b00  Reserved
0b01  Memory barrier
0b10  Reserved
0b11  Synchronization barrier.

Bit[0]

On reads:
0b0  Barrier transaction in progress.
0b1  No barrier transaction in progress.

SBO on writes.
This section describes the implementation of the CSW register for AMBA AHB implementations. For more information, see the AMBA® Specification (Rev 2.0) and the AMBA® 3 AHB-Lite™ Protocol Specification.

### E1.4.1 CSW register implementation

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
<th>Description when not implemented at the AHB master interface</th>
</tr>
</thead>
<tbody>
<tr>
<td>27</td>
<td>HPROT[3]</td>
<td>Cacheable</td>
</tr>
<tr>
<td>26</td>
<td>HPROT[2]</td>
<td>Bufferable</td>
</tr>
<tr>
<td>25</td>
<td>HPROT[1]</td>
<td>Privileged</td>
</tr>
<tr>
<td>24</td>
<td>HPROT[0]</td>
<td>Data</td>
</tr>
</tbody>
</table>

The reset value of CSW.Prot is 0b1000011.

### DbgSwEnable, bit[31]

See CSW, Control/Status Word register on page C2-176.

### Prot, bits[30:24]

The CSW.Prot field drives the AHB HPROT signals. The settings for the CSW.Prot field are:

- **Bit[30]**
  - Reserved, SBO. If this bit is written as 0b0, the behavior of an AHB-AP transaction is UNPREDICTABLE.

- **MasterType, bit[29]**
  - Master Type bit. MasterType permits the AHB-AP to mimic a second AHB master by driving a different value on HMASTER[3:0]. Support for this function is IMPLEMENTATION DEFINED. Valid values for this bit are:
    - 0b1: Drive HMASTER[3:0] with the bus master ID for the AHB-AP.
    - 0b0: Drive HMASTER[3:0] with the bus master ID for the second bus master.

- **HPROT[4], Allocate, bit[28]**
  - Drives HPROT[4], Allocate. HPROT[4] is an ARMv5 extension to AHB. For more information, see the ARM1136JF-S™ and ARM1136J-S™ Technical Reference Manual.

  If the AHB master interface does not support the ARMv5 extension to AHB, this bit is RAZ/WI.

- **HPROT[3:0], bits[27:24]**
  - Drives HPROT[3:0]. See Table E1-5. Support for each HPROT signal in the AHB master interface is IMPLEMENTATION DEFINED.
**SPIDEN, bit[23]**

It is IMPLEMENTATION DEFINED whether the CSW.SPIDEN bit reflects the state of the CoreSight authentication signal, **SPIDEN**. Otherwise, the CSW.SPIDEN bit is RAZ. This bit is always read-only.

---

**Note**

AMBA AHB does not support Security Extensions.

---

**Bits[22:16]**

RES0.

**Type, bits[15:12]**

RES0.

**Mode, bits[11:8]**

RES0.

**TrInProg, bit[7]**

See *CSW, Control/Status Word register* on page C2-176.

**DeviceEn, bit[6]**

See *CSW, Control/Status Word register* on page C2-176.

**AddrInc, bits[5:4]**

Support for the *Increment Packed* mode of transfer is IMPLEMENTATION DEFINED. See *Packed transfers* on page C2-158.

**Bit[3]**

RES0.

**Size, bits[2:0]**

CSW.Size must support word, half-word, and byte size accesses.
E1.5 AMBA AHB5

This section describes the implementation of the CSW register for AMBA AHB implementations. For more information, see the AMBA® Specification (Rev 2.0) and the ARM® AMBA® 5 AHB Protocol Specification.

E1.5.1 CSW register implementation

<table>
<thead>
<tr>
<th>31 30 29 28 27</th>
<th>24 23 22</th>
<th>16 15 12 11</th>
<th>8 7 6 5 4 3 2 0</th>
</tr>
</thead>
<tbody>
<tr>
<td>HPROT</td>
<td>RES0</td>
<td>Type</td>
<td>Mode</td>
</tr>
<tr>
<td>RES0</td>
<td>SPIDEN</td>
<td>RES0</td>
<td>AddrInc</td>
</tr>
<tr>
<td>MasterType</td>
<td>HNONSEC</td>
<td>DeviceEn</td>
<td>TrInProg</td>
</tr>
<tr>
<td>HNONSEC</td>
<td>RES0</td>
<td>Type</td>
<td>Mode</td>
</tr>
<tr>
<td>RES0</td>
<td></td>
<td>RES0</td>
<td></td>
</tr>
</tbody>
</table>

**DbgSwEnable, bit[31]**

See CFG, Configuration register on page C2-174.

**HNONSEC, Bit[30]**

Drives the value of HNONSEC. It is implementation defined whether the HNONSEC field is supported.

If implemented, the reset value of this field is 0b1.

**MasterType, bit[29]**

Master Type field. MasterType permits the AHB-AP to mimic a second AHB master by driving a different value on HMASTER[3:0]. Support for this function is IMPLEMENTATION DEFINED. Valid values for this field are:

- 0b1: Drive HMASTER[3:0] with the bus master ID for the AHB-AP.
- 0b0: Drive HMASTER[3:0] with the bus master ID for the second bus master.

If this function is not implemented, the field is RES0.

**Bit[28]**

RES0.

**HPROT, bits[27:24]**

Drives the value of HPROT[6:0]:

- Support for each HPROT signal is IMPLEMENTATION DEFINED.
- HPROT[5] is always driven with the value 0.
- Bit[27] drives HPROT[6], HPROT[4], and HPROT[3].
- Bit[26] drives HPROT[2].
- Bit[24] drives HPROT[0].

**SPIDEN, bit[23]**

It is IMPLEMENTATION DEFINED whether CSW.SPIDEN reflects the state of the CoreSight authentication interface. If Secure debug is not supported, CSW.SPIDEN is RES0.

This field is always read-only.

**Bits[22:16]**

RES0.

**Type, bits[15:12]**

RES0.
Mode, bits[11:8]

RES0.

TrInProg, bit[7]

Transfer in progress. This field has one of the following values:

0b0 The connection to the memory system is idle.

0b1 A transfer is in progress on the connection to the memory system.

After an ABORT operation, debug software can read this bit to check whether the aborted transaction completed.

DeviceEn, bit[6]

Device enabled.

This field has one of the following values:

0b0 The MEM-AP is not enabled.

0b1 Transactions can be issued through the MEM-AP.

This bit corresponds to the value of the DEVICEEN signal, which is a control input to the DAP. If DEVICEEN is not implemented this bit is RAO. See also Enabling access to the connected debug device or memory system on page C2-152.

This field is read-only.

AddrInc, bits[5:4]

Support for the Increment Packed mode of transfer is IMPLEMENTATION DEFINED. See Packed transfers on page C2-158.

Bit[3]

RES0.

Size, bits[2:0]

CSW. Size must support word, half-word, and byte size accesses.
### E1.6 AMBA APB2 and APB3

This section describes the implementation of the CSW register for AMBA APB2 and APB3 implementations. For more information see the *AMBA® Specification (Rev 2.0)*, and the *AMBA® APB Protocol Specification Version: 2.0*.

#### E1.6.1 CSW register implementation

<table>
<thead>
<tr>
<th></th>
<th>31</th>
<th>30</th>
<th>24</th>
<th>23</th>
<th>22</th>
<th>16</th>
<th>15</th>
<th>12</th>
<th>11</th>
<th>8</th>
<th>7</th>
<th>6</th>
<th>5</th>
<th>4</th>
<th>3</th>
<th>2</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Prot</td>
<td>RES0</td>
<td>Type</td>
<td>Mode</td>
<td>Size</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**DbgSwEnable, bit[31]**

See *CSW, Control/Status Word register on page C2-176*

**Prot, bits[30:24]**

RES0.

**SPIDEN, bit[23]**

RES0.

**Bits[22:16]**

RES0.

**Type, bits[15:12]**

RES0.

**Mode, bits[11:8]**

RES0.

**TrInProg, bit[7]**

See *CSW, Control/Status Word register on page C2-176*.

**DeviceEn, bit[6]**

See *CSW, Control/Status Word register on page C2-176*.

**AddrInc, bits[5:4]**

*CSW*.AddrInc does not support the *Increment Packed* mode of transfer, and reads as 0b00. See also *Packed transfers on page C2-158*.

**Bit[3]**

RES0.

**Size, bits[2:0]**

*CSW*.Size only supports word accesses, and reads as 0b010. Writes to *CSW*.Size are ignored.
E1.7 AMBA APB4

This section describes the implementation of the CSW register for AMBA APB4 implementations. For more information see the AMBA® APB Protocol Version: 2.0.

E1.7.1 CSW register implementation

<table>
<thead>
<tr>
<th>31</th>
<th>30</th>
<th>28</th>
<th>27</th>
<th>24</th>
<th>23</th>
<th>22</th>
<th>16</th>
<th>15</th>
<th>12</th>
<th>11</th>
<th>8</th>
<th>7</th>
<th>6</th>
<th>5</th>
<th>4</th>
<th>3</th>
<th>2</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
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<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

DbgSwEnable, bit[31]

See CSW, Control/Status Word register on page C2-176.

Prot[2:0], bits[30:28]

Drives PPROT[2:0].

Bit[29], Non-secure, corresponds to Prot[1], and specifies a non-secure transfer. This bit can have one of the following values:

0b1 Non-secure transfer requested. PPROT[1] is HIGH.
0b0 Secure transfer requested. The resulting behavior depends on the value of the CSW.SPIDEN field:

- If CSW.SPIDEN is 0b1, PPROT[1] is LOW.
- If CSW.SPIDEN is 0b0, no transfer is initiated, and ARM recommends that, if an access is made to the DRW or BD0-BD3 registers, an error response is returned.

Bits[27:24]

RES0.

SPIDEN, bit[23]

It is IMPLEMENTATION DEFINED whether CSW.SPIDEN reflects the state of the CoreSight authentication interface. If Secure debug is not supported, CSW.SPIDEN is RES0. This field is always read-only.

Bits[22:16]

RES0.

Type, bits[15:12]

RES0.

Mode, bits[11:8]

RES0.

TrInProg, bit[7]

See CSW, Control/Status Word register on page C2-176.

DeviceEn, bit[6]

See CSW, Control/Status Word register on page C2-176.
AddrInc, bits[5:4]

CSW.AddrInc does not support the Increment Packed mode of transfer, and reads as 0b00. See also Packed transfers on page C2-158.

Bit[3]

RES0.

Size, bits[2:0]

CSW.Size only supports word accesses, and reads as 0b10. Writes to CSW.Size are ignored.
Appendix E2
Cross-over with the ARM Architecture

This appendix describes the required or recommended options for the ARM Debug Interface for the ARMv6-M and all ARMv7 and ARMv8 architecture profiles. It contains the following sections:

- Introduction on page E2-308.
- ARMv6-M, ARMv7-M, and ARMv8-M architecture profiles on page E2-309.
- ARMv7-A without Large Physical Address Extension, ARMv7-R, and ARMv8-R on page E2-310.
- ARMv7-A with Large Physical Address Extension, and ARMv8-A on page E2-311.
- Summary of the requirements for ADIv5 implementations on page E2-312.
E2.1 Introduction

The ARM Debug Interface v5 is the recommended external debug interface for ARMv6-M, all ARMv7, and all ARMv8 architecture profiles.

When designing with ARM Cortex™ processor cores and ARM CoreSight technology, the choice of Debug Access Port (DAP) features might be at the discretion of the system designer. ARM recommends that system designers choose a DAP that implements all the recommended features for each ARM architecture processing element (PE) that is contained in the design.

ADIv5 might also be used with other architecture variants. For example, an ADIv5 JTAG Access Port (JTAG-AP) might access a Debug Test Access Port (DBGTAP), as defined by ARM Debug Interface v4 (ADIv4) for ARMv6 architecture processors.
E2.2 ARMv6-M, ARMv7-M, and ARMv8-M architecture profiles

ARM recommends that a DP that implements ADIV5 is used to access the debug features of the ARMv6-M, ARMv7-M, or ARMv8-M architecture.

ARM recommends that the DP implements the SWD interface, either through an SW-DP or SWJ-DP. A JTAG-DP is permitted.

When accessing debug features of the ARMv6-M architecture, or the ARMv8-M architecture without the Main Extension, ARM recommends that the DP implements the MINDP model. See MINDP, Minimal DP extension on page B1-40.

There must be one MEM-AP for each PE, which complies with the following rules:

- The MEM-AP must be able to address the complete memory space visible to the PE, including all debug peripherals and the NVIC.
- The MEM-AP must support byte, half-word, and word size accesses to memory.
- A MEM-AP that is used to access debug features of the ARMv6-M architecture, or the ARMv8-M architecture without the Main Extension, is not required to support the packed increment transfer mode.
- A MEM-AP that is used to access debug features of the ARMv7-M architecture, or the ARMv8-M architecture with the Main Extension, is permitted to support the packed increment transfer mode.

Other APs can be connected to the DAP.
E2.3 ARMv7-A without Large Physical Address Extension, ARMv7-R, and ARMv8-R

The ARMv7-A, ARMv7-R, and ARMv8-R architecture profiles do not require a DAP that is compliant with ADIv5. The ARM development tools, however, do require a DAP that is compliant with ADIv5.

Where a DAP that is compliant with ADIv5 is implemented, ARM recommends that the DP implements the JTAG and SWD interfaces through an SWJ-DP.

Many PEs can be connected to a single MEM-AP. The MEM-AP must only be able to address the debug peripherals of the connected PEs. If the MEM-AP can only address the debug peripherals, it is only required to support word size accesses to memory, and therefore is not required to support the packed increment transfer mode.

ARM recommends that debug implementations include a MEM-AP that can address the complete memory space visible to the PE or PEs. This MEM-AP might be a second MEM-AP in the DAP. ARM recommends that a MEM-AP that can access the complete memory space supports byte, half-word, and word size accesses to memory. This MEM-AP is permitted to support the packed increment transfer mode.

Other APs can also be connected to the DAP.

--- Note ---

Do not confuse the ARMv7-A or ARMv8-A Large Physical Address Extension with the ADI MEM-AP Large Physical Address Extension.
E2.4 ARMv7-A with Large Physical Address Extension, and ARMv8-A

The requirements for ARMv7-A with Large Physical Address Extension and ARMv8-A architecture profiles are the same as for the ARMv7-A without Large Physical Address Extension and ARMv7-R architecture profiles, with the following additions for any MEM-AP with system access:

- MEM-AP Large Physical Address Extension, up to at least the size that is supported by the PE.
- For ARMv7-A systems with the Large Physical Address Extension, ARM recommends that the MEM-AP implements the Large Data Extension providing at least doubleword accesses, to allow for atomic update of page table entries.
- For ARMv8-A systems, the MEM-AP must implement the Large Data Extension providing at least doubleword accesses.
### Summary of the requirements for ADIv5 implementations

Table E2-1 summarizes the required and recommended components of an ADI implementation for each of the ARM architecture variants for which ADIv5 is the required or recommended DAP.

<table>
<thead>
<tr>
<th>Component</th>
<th>ARMv6-M and ARMv8-M without Main Extension</th>
<th>ARMv7-M and ARMv8-M with Main Extension</th>
<th>ARMv7-A without Large Physical Address Extension, ARMv7-R, and ARMv8-R</th>
<th>ARMv7-A with Large Physical Address Extension and ARMv8-A</th>
</tr>
</thead>
<tbody>
<tr>
<td>DAP</td>
<td>Required</td>
<td>Required</td>
<td>Recommended</td>
<td>Recommended</td>
</tr>
<tr>
<td>DP</td>
<td>JTAG-DP</td>
<td>Permitted</td>
<td>Permitted</td>
<td>Permitted</td>
</tr>
<tr>
<td></td>
<td>SWJ-DP</td>
<td>-</td>
<td>Permitted</td>
<td>Permitted</td>
</tr>
<tr>
<td></td>
<td>SWJ-DP or SW-DP</td>
<td>Recommended</td>
<td>Recommended</td>
<td>-</td>
</tr>
<tr>
<td>MEM-AP</td>
<td>One per PE</td>
<td>Required</td>
<td>Required</td>
<td>Permitted</td>
</tr>
<tr>
<td></td>
<td>Access to system memory</td>
<td>Required</td>
<td>Required</td>
<td>Permitted</td>
</tr>
<tr>
<td></td>
<td>Support for 8-bit and 16-bit accesses</td>
<td>Required</td>
<td>Required only if system access is supported</td>
<td>Required only if system access is supported</td>
</tr>
<tr>
<td></td>
<td>Support for 32-bit accesses</td>
<td>Required</td>
<td>Required</td>
<td>Required</td>
</tr>
<tr>
<td></td>
<td>Support for 64-bit accesses</td>
<td>Permitted</td>
<td>Permitted</td>
<td>Required</td>
</tr>
<tr>
<td></td>
<td>Support for large physical addresses</td>
<td>Not permitted</td>
<td>Permitted</td>
<td>Required if system access is supported</td>
</tr>
<tr>
<td></td>
<td>Support for packed increment transfers</td>
<td>Permitted</td>
<td>Permitted</td>
<td>Permitted</td>
</tr>
</tbody>
</table>
Appendix E3
Pseudocode Definition

This appendix provides a definition of the pseudocode used in this document, and lists the helper procedures and functions used by pseudocode to perform useful architecture-specific jobs. It contains the following sections:

- About ARM pseudocode on page E3-314.
- Data types on page E3-315.
- Expressions on page E3-319.
- Operators and built-in functions on page E3-321.
- Statements and program structure on page E3-326.
E3.1 About ARM pseudocode

ARM pseudocode provides precise descriptions of some areas of the architecture. The following sections describe the ARMv7 pseudocode in detail:

- Data types on page E3-315.
- Expressions on page E3-319.
- Operators and built-in functions on page E3-321.
- Statements and program structure on page E3-326.

E3.1.1 General limitations of ARM pseudocode

The pseudocode statements IMPLEMENTATION_DEFINED, SEE, SUBARCHITECTURE_DEFINED, UNDEFINED, and UNPREDICTABLE indicate behavior that differs from that indicated by the pseudocode being executed. If one of them is encountered:

- Earlier behavior indicated by the pseudocode is only specified as occurring to the extent required to determine that the statement is executed.
- No subsequent behavior indicated by the pseudocode occurs. This means that these statements terminate pseudocode execution.

For more information, see Simple statements on page E3-326.
E3.2 Data types

This section describes:

- General data type rules.
- Bitstrings.
- Integers on page E3-316.
- Reals on page E3-316.
- Booleans on page E3-316.
- Enumerations on page E3-316.
- Lists on page E3-317.
- Arrays on page E3-318.

E3.2.1 General data type rules

ARM architecture pseudocode is a strongly-typed language. Every constant and variable is of one of the following types:

- Bitstring.
- Integer.
- Boolean.
- Real.
- Enumeration.
- List.
- Array.

The type of a constant is determined by its syntax. The type of a variable is normally determined by assignment to the variable, with the variable being implicitly declared to be of the same type as whatever is assigned to it. For example, the assignments \( x = 1 \), \( y = '1' \), and \( z = \text{TRUE} \) implicitly declare the variables \( x \), \( y \), and \( z \) to have types integer, bitstring of length 1, and Boolean, respectively.

Variables can also have their types declared explicitly by preceding the variable name with the name of the type. This is most often done in function definitions for the arguments and the result of the function.

The remaining subsections describe each data type in more detail.

E3.2.2 Bitstrings

A bitstring is a finite-length string of 0s and 1s. Each length of bitstring is a different type. The minimum permitted length of a bitstring is 1.

The type name for bitstrings of length \( N \) is \( \text{bits}(N) \). A synonym of \( \text{bits}(1) \) is \( \text{bit} \).

Bitstring constants are written as a single quotation mark, followed by the string of 0s and 1s, followed by another single quotation mark. For example, the two constants of type \( \text{bit} \) are \( '0' \) and \( '1' \). Spaces can be included in bitstrings for clarity.

A special form of bitstring constant with 'x' bits is permitted in bitstring comparisons, see Equality and non-equality testing on page E3-321.

Every bitstring value has a left-to-right order, with the bits being numbered in standard little-endian order. That is, the leftmost bit of a bitstring of length \( N \) is bit \((N-1)\) and its right-most bit is bit 0. This order is used as the most-significant-to-least-significant bit order in conversions to and from integers. For bitstring constants and bitstrings derived from encoding diagrams, this order matches the way they are printed.

Bitstrings are the only concrete data type in pseudocode, in the sense that they correspond directly to the contents of, for example, registers, memory locations, and instructions. All of the remaining data types are abstract.
E3.2.3   Integers

Pseudocode integers are unbounded in size and can be either positive or negative. That is, they are mathematical integers rather than what computer languages and architectures commonly call integers. Computer integers are represented in pseudocode as bitstrings of the appropriate length, associated with suitable functions to interpret those bitstrings as integers.

The type name for integers is `integer`.

Integer constants are normally written in decimal, such as 0, 15, –1234. They can also be written in C-style hexadecimal, such as 0x55 or 0x80000000. Hexadecimal integer constants are treated as positive unless they have a preceding minus sign. For example, 0x80000000 is the integer +2^31. If –2^31 must be written in hexadecimal, it must be written as –0x80000000.

E3.2.4   Reals

Pseudocode reals are unbounded in size and precision. That is, they are mathematical real numbers, not computer floating-point numbers. Computer floating-point numbers are represented in pseudocode as bitstrings of the appropriate length, associated with suitable functions to interpret those bitstrings as reals.

The type name for reals is `real`.

Real constants are written in decimal with a decimal point. This means 0 is an integer constant but 0.0 is a real constant.

E3.2.5   Booleans

A Boolean is a logical true or false value.

The type name for Booleans is `boolean`. This is not the same type as `bit`, which is a length–1 bitstring. Boolean constants are `TRUE` and `FALSE`.

E3.2.6   Enumerations

An enumeration is a defined set of symbolic constants, such as:

```plaintext
enumeration InstrSet {InstrSet_A32, InstrSet_T32, InstrSet_A64};
```

An enumeration always contains at least one symbolic constant, and a symbolic constant must not be shared between enumerations.

Enumerations must be declared explicitly, although a variable of an enumeration type can be declared implicitly by assigning one of the symbolic constants to it. By convention, each of the symbolic constants starts with the name of the enumeration followed by an underscore. The name of the enumeration is its type name, or `type`, and the symbolic constants are its possible `constants`.

--- Note ---

A Boolean is a pre-declared enumeration that does not follow the normal naming convention and it has a special role in some pseudocode constructs, such as if statements, for example:

```plaintext
enumeration boolean {FALSE, TRUE};
```
E3.2.7 Lists

A list is an ordered set of other data items, separated by commas and enclosed in parentheses, for example:

\[(\text{bits}(32) \text{ shifter\_result}, \text{bit} \text{ shifter\_carry\_out})\]

A list always contains at least one data item.

Lists are often used as the return type for a function that returns multiple results. For example, this list at the start of this section is the return type of the function `Shift\_C()` that performs a standard ARM shift or rotation, when its first operand is of type `\text{bits}(32)`.

Some specific pseudocode operators use lists surrounded by other forms of bracketing than the `(..)` parentheses. These are:

- Bitstring extraction operators, that use lists of bit numbers or ranges of bit numbers surrounded by angle brackets `<..>`.
- Array indexing, that uses lists of array indexes surrounded by square brackets `[..]`.
- Array-like function argument passing, that uses lists of function arguments surrounded by square brackets `[..]`.

Each combination of data types in a list is a separate type, with type name given by listing the data types. This means that the example list at the start of this section is of type `(\text{bits}(32), \text{bit})`. The general principle that types can be declared by assignment extends to the types of the individual list items in a list. For example:

\[(\text{shift}\_t, \text{shift}\_n) = ('00', 0)\]

implicitly declares `\text{shift}\_t`, `\text{shift}\_n`, and `(\text{shift}\_t, \text{shift}\_n)` to be of types `\text{bits}(2)`, `\text{integer}`, and `(\text{bits}(2), \text{integer})`, respectively.

A list type can also be explicitly named, with explicitly named elements in the list. For example:

```pseudocode
type ShiftSpec is (\text{bits}(2) \text{ shift}, \text{integer} \text{ amount});
```

After this definition and the declaration:

```pseudocode
ShiftSpec abc;
```

the elements of the resulting list can then be referred to as `abc\_shift`, and `abc\_amount`. This qualified naming of list elements is only permitted for variables that have been explicitly declared, not for those that have been declared by assignment only.

Explicitly naming a type does not alter what type it is. For example, after the definition of `ShiftSpec`, `ShiftSpec`, and `(\text{bits}(2), \text{integer})` are two different names for the same type, not the names of two different types. To avoid ambiguity in references to list elements, it is an error to declare a list variable multiple times using different names of its type or to qualify it with list element names not associated with the name by which it was declared.

An item in a list that is being assigned to can be written as `-` to indicate that the corresponding item of the assigned list value is discarded. For example:

```pseudocode
(shifted, -) = LSL\_C(operand, amount);
```

List constants are written as a list of constants of the appropriate types, for example the `('00', 0)` in the earlier example.
E3.2.8 Arrays

Pseudocode arrays are indexed by either enumerations or integer ranges. An integer range is represented by the lower inclusive end of the range, then \ldots, then the upper inclusive end of the range.

For example:

```plaintext
// The names of the Banked core registers.

enumeration RName {RName_0usr, RName_1usr, RName_2usr, RName_3usr, RName_4usr, RName_5usr,
                 RName_6usr, RName_7usr, RName_8usr, RName_8fiq, RName_9usr, RName_9fiq,
                 RName_10usr, RName_10fiq, RName_11usr, RName_11fiq, RName_12usr, RName_12fiq,
                 RName_SPusr, RName_SPfiq, RName_SPirq, RName_SPsvc,
                 RName_SPabt, RName_SPund, RName_SPmon, RName_SPhyp,
                 RName_LRusr, RName_LRfiq, RName_LRirq, RName_LRsvc,
                 RName_LRabt, RName_LRund, RName_LRmon,
                 RName_PC};

array bits(8) _Memory[0..0xFFFFFFFF];
```

Arrays are always explicitly declared, and there is no notation for a constant array. Arrays always contain at least one element, because:

• Enumerations always contain at least one symbolic constant.
• Integer ranges always contain at least one integer.

Arrays do not usually appear directly in pseudocode. The items that syntactically look like arrays in pseudocode are usually array-like functions such as `R[i]`, `MemU[address, size]` or `Elem[vector, i, size]`. These functions package up and abstract additional operations normally performed on accesses to the underlying arrays, such as register banking, memory protection, endian-dependent byte ordering, exclusive-access housekeeping and Advanced SIMD element processing.
E3.3 Expressions

This section describes:

- General expression syntax.
- Operators and functions - polymorphism and prototypes on page E3-320.
- Precedence rules on page E3-320.

E3.3.1 General expression syntax

An expression is one of the following:

- A constant.
- A variable, optionally preceded by a data type name to declare its type.
- The word `UNKNOWN` preceded by a data type name to declare its type.
- The result of applying a language-defined operator to other expressions.
- The result of applying a function to other expressions.

Variable names normally consist of alphanumeric and underscore characters, starting with an alphabetic or underscore character.

Each register described in the text is to be regarded as declaring a correspondingly named bitstring variable, and that variable has the stated behavior of the register. For example, if a bit of a register is defined as RAZ/WI, then the corresponding bit of its variable reads as 0 and ignore writes.

An expression like `bits(32) UNKNOWN` indicates that the result of the expression is a value of the given type, but the architecture does not specify what value it is and software must not rely on such values. The value produced must not constitute a security hole and must not be promoted as providing any useful information to software.

--- Note ---

Some earlier documentation describes this as an UNPREDICTABLE value. UNKNOWN values are similar to the definition of UNPREDICTABLE, but do not indicate that the entire architectural state becomes unspecified.

Only the following expressions are assignable. This means that these are the only expressions that can be placed on the left-hand side of an assignment.

- Variables.
- The results of applying some operators to other expressions.
  The description of each language-defined operator that can generate an assignable expression specifies the circumstances under which it does so. For example, those circumstances might require that one or more of the expressions the operator operates is an assignable expression.
- The results of applying array-like functions to other expressions. The description of an array-like function specifies the circumstances under which it can generate an assignable expression.

Every expression has a data type:

- For a constant, this data type is determined by the syntax of the constant.
- For a variable, there are the following possible sources for the data type:
  - An optional preceding data type name.
  - A data type the variable was given earlier in the pseudocode by recursive application of this rule.
  - A data type the variable is being given by assignment, either by direct assignment to the variable, or by assignment to a list of which the variable is a member.
  
  It is a pseudocode error if none of these data type sources exists for a variable, or if more than one of them exists and they do not agree about the type.
- For a language-defined operator, the definition of the operator determines the data type.
- For a function, the definition of the function determines the data type.
Operators and functions - polymorphism and prototypes

Operators and functions in pseudocode can be polymorphic, producing different functionality when applied to different data types. Each resulting form of an operator or function has a different prototype definition. For example, the operator + has forms that act on various combinations of integers, reals, and bitstrings.

One particularly common form of polymorphism is between bitstrings of different lengths. This is represented by using bits(N), bits(M), or similar, in the prototype definition.

Precedence rules

The precedence rules for expressions are:

1. Constants, variables, and function invocations are evaluated with higher priority than any operators using their results.

2. Expressions on integers follow the normal operator precedence rules of exponentiation before multiply/divide before add/subtract, with sequences of multiply/divides or add/subtracts evaluated left-to-right.

3. Other expressions must be parenthesized to indicate operator precedence if ambiguity is possible, but this is not necessary if all permitted precedence orders under the type rules necessarily lead to the same result. For example, if i, j, and k are integer variables, i > 0 && j > 0 && k > 0 is acceptable, but i > 0 && j > 0 || k > 0 is not.
E3.4 Operators and built-in functions

This section describes:
• Operations on generic types.
• Operations on Booleans.
• Bitstring manipulation.
• Arithmetic on page E3-324.

E3.4.1 Operations on generic types

The following operations are defined for all types.

Equality and non-equality testing

Any two values \(x\) and \(y\) of the same type can be tested for equality by the expression \(x == y\) and for non-equality by the expression \(x != y\). In both cases, the result is of type boolean.

A special form of comparison is defined with a bitstring constant that includes \('x'\) bits in addition to \('0'\) and \('1'\) bits. The bits corresponding to the \('x'\) bits are ignored in determining the result of the comparison. For example, if opcode is a 4-bit bitstring, \(\text{opcode} == '1x0x'\) is equivalent to \(\text{opcode<3> == '1'} \& \& \text{opcode<1> == '0'}\).

--- Note ---

This special form is permitted in the implied equality comparisons in when parts of case .. of .. structures.

Conditional selection

If \(x\) and \(y\) are two values of the same type and \(t\) is a value of type boolean, then \(\text{if } t \text{ then } x \text{ else } y\) is an expression of the same type as \(x\) and \(y\) that produces \(x\) if \(t\) is TRUE and \(y\) if \(t\) is FALSE.

E3.4.2 Operations on Booleans

If \(x\) is a Boolean, then \(!x\) is its logical inverse.

If \(x\) and \(y\) are Booleans, then \(x \&\& y\) is the result of ANDing them together. As in the C language, if \(x\) is FALSE, the result is determined to be FALSE without evaluating \(y\).

If \(x\) and \(y\) are Booleans, then \(x \mid\mid y\) is the result of ORing them together. As in the C language, if \(x\) is TRUE, the result is determined to be TRUE without evaluating \(y\).

If \(x\) and \(y\) are Booleans, then \(x \wedge y\) is the result of exclusive-ORing them together.

E3.4.3 Bitstring manipulation

The following bitstring manipulation functions are defined:

Bitstring length and most significant bit

If \(x\) is a bitstring:
• The bitstring length function \(\text{Len}(x)\) returns the length of \(x\) as an integer.
• \(\text{TopBit}(x)\) is the leftmost bit of \(x\). Using bitstring extraction, this means:
  \[\text{TopBit}(x) = x_{\text{Len}(x)-1}\].

Bitstring concatenation and replication

If \(x\) and \(y\) are bitstrings of lengths \(N\) and \(M\) respectively, then \(x:y\) is the bitstring of length \(N+M\) constructed by concatenating \(x\) and \(y\) in left-to-right order.
If \( x \) is a bitstring and \( n \) is an integer with \( n > 0 \):

- \( \text{Replicate}(x, n) \) is the bitstring of length \( n \cdot \text{Len}(x) \) consisting of \( n \) copies of \( x \) concatenated together.
- \( \text{Zeros}(n) = \text{Replicate}('0', n) \), \( \text{Ones}(n) = \text{Replicate}('1', n) \).

### Bitstring extraction

The bitstring extraction operator extracts a bitstring from either another bitstring or an integer. Its syntax is \( x<\text{integer\_list}> \), where \( x \) is the integer or bitstring being extracted from, and \( \text{integer\_list} \) is a list of integers enclosed in angle brackets rather than the usual parentheses. The length of the resulting bitstring is equal to the number of integers in \( \text{integer\_list} \). In \( x<\text{integer\_list}> \), each of the integers in \( \text{integer\_list} \) must be:

- \( \geq 0 \)
- \(< \text{Len}(x) \) if \( x \) is a bitstring.

The definition of \( x<\text{integer\_list}> \) depends on whether \( \text{integer\_list} \) contains more than one integer:

- If \( \text{integer\_list} \) contains more than one integer, \( x<i, j, k, \ldots, n> \) is defined to be the concatenation:
  \[ x<i> : x<j> : x<k> : \ldots : x<n>. \]
- If \( \text{integer\_list} \) consists of one integer \( i \), \( x<i> \) is defined to be:
  - If \( x \) is a bitstring, \( '0' \) if bit \( i \) of \( x \) is a zero and \( '1' \) if bit \( i \) of \( x \) is a one.
  - If \( x \) is an integer, let \( y \) be the unique integer in the range \( 0 \) to \( 2^{|i+1|-1} \) that is congruent to \( x \) modulo \( 2^{i+1} \). Then \( x<i> \) is \( '0' \) if \( y < 2^i \) and \( '1' \) if \( y \geq 2^i \).

Loosely, this definition treats an integer as equivalent to a sufficiently long two’s complement representation of it as a bitstring.

In \( \text{integer\_list} \), the notation \( i:j \) with \( i \geq j \) is shorthand for the integers in order from \( i \) down to \( j \), with both end values included. For example, \( \text{instr<31:28>} \) is shorthand for \( \text{instr<31, 30, 29, 28>} \).

The expression \( x<\text{integer\_list}> \) is assignable provided \( x \) is an assignable bitstring and no integer appears more than once in \( \text{integer\_list} \). In particular, \( x<i> \) is assignable if \( x \) is an assignable bitstring and \( 0 \leq i < \text{Len}(x) \).

Encoding diagrams for registers frequently show named bits or multi-bit fields. For example, the encoding diagram for the \textsc{ABORT} register shows its bit<3> as WDERRCLR. In such cases, the syntax \textsc{ABORT.<WDERRCLR>} is used as a more readable synonym for \textsc{ABORT<3>}.

### Logical operations on bitstrings

If \( x \) is a bitstring, \( \text{NOT}(x) \) is the bitstring of the same length obtained by logically inverting every bit of \( x \).

If \( x \) and \( y \) are bitstrings of the same length, \( x \text{ AND } y \), \( x \text{ OR } y \), and \( x \text{ EOR } y \) are the bitstrings of that same length obtained by logically ANDing, ORing, and exclusive-ORing corresponding bits of \( x \) and \( y \) together.

### Bitstring count

If \( x \) is a bitstring, \( \text{BitCount}(x) \) produces an integer result equal to the number of bits of \( x \) that are ones.
Testing a bitstring for being all zero or all ones

If x is a bitstring:

- IsZero(x) produces TRUE if all of the bits of x are zeros and FALSE if any of them are ones.
- IsZeroBit(x) produces '1' if all of the bits of x are zeros and '0' if any of them are ones.

IsOnes(x) and IsOnesBit(x) work in the corresponding ways. This means:

\[
\begin{align*}
\text{IsZero}(x) &= (\text{BitCount}(x) == 0) \\
\text{IsOnes}(x) &= (\text{BitCount}(x) == \text{Len}(x)) \\
\text{IsZeroBit}(x) &= \text{if IsZero}(x) \text{ then '1' else '0'} \\
\text{IsOnesBit}(x) &= \text{if IsOnes}(x) \text{ then '1' else '0'}
\end{align*}
\]

Lowest and highest set bits of a bitstring

If x is a bitstring, and N = Len(x):

- LowestSetBit(x) is the minimum bit number of any of its bits that are ones. If all of its bits are zeros, LowestSetBit(x) = N.
- HighestSetBit(x) is the maximum bit number of any of its bits that are ones. If all of its bits are zeros, HighestSetBit(x) = -1.
- CountLeadingZeroBits(x) is the number of zero bits at the left end of x, in the range 0 to N. This means:
  \[\text{CountLeadingZeroBits}(x) = N - 1 - \text{HighestSetBit}(x)\]
- CountLeadingSignBits(x) is the number of copies of the sign bit of x at the left end of x, excluding the sign bit itself, and is in the range 0 to N-1. This means:
  \[\text{CountLeadingSignBits}(x) = \text{CountLeadingZeroBits}(x<\text{N-1}:1> \text{EOR } x<\text{N-2}:0>)\]

Zero-extension and sign-extension of bitstrings

If x is a bitstring and i is an integer, then ZeroExtend(x, i) is x extended to a length of i bits, by adding sufficient zero bits to its left. That is, if i == Len(x), then ZeroExtend(x, i) = x, and if i > Len(x), then:

\[
\text{ZeroExtend}(x, i) = \text{Replicate('0', i-Len(x))) : x}
\]

If x is a bitstring and i is an integer, then SignExtend(x, i) is x extended to a length of i bits, by adding sufficient copies of its leftmost bit to its left. That is, if i == Len(x), then SignExtend(x, i) = x, and if i > Len(x), then:

\[
\text{SignExtend}(x, i) = \text{Replicate(TopBit(x), i-Len(x))) : x}
\]

It is a pseudocode error to use either ZeroExtend(x, i) or SignExtend(x, i) in a context where it is possible that \(i < \text{Len}(x)\).

Converting bitstrings to integers

If x is a bitstring, SInt(x) is the integer whose two's complement representation is x:

```plaintext
// SInt()
// ======
integer SInt(bits(N) x)
result = 0;
for i = 0 to N-1
    if x<i> == '1' then result = result + 2^i;
    if x<N-1> == '1' then result = result - 2^N;
return result;
```

UInt(x) is the integer whose unsigned representation is x:

```plaintext
// UInt()
// ======
```
Appendix E3 Pseudocode Definition

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integer UInt(bits(N) x)
result = 0;
for i = 0 to N-1
  if x<i> == '1' then result = result + 2^i;
return result;

Int(x, unsigned) returns either SInt(x) or UInt(x) depending on the value of its second argument:

  // Int()
  // ===

integer Int(bits(N) x, boolean unsigned)
result = if unsigned then UInt(x) else SInt(x);
return result;

E3.4.4 Arithmetic

Most pseudocode arithmetic is performed on integer or real values, with operands being obtained by conversions from bitstrings and results converted back to bitstrings afterwards. As these data types are the unbounded mathematical types, no issues arise about overflow or similar errors.

Unary plus, minus, and absolute value

If x is an integer or real, then +x is x unchanged, -x is x with its sign reversed, and Abs(x) is the absolute value of x. All three are of the same type as x.

Addition and subtraction

If x and y are integers or reals, x+y and x-y are their sum and difference. Both are of type integer if x and y are both of type integer, and real otherwise.

Addition and subtraction are particularly common arithmetic operations in pseudocode, and so it is also convenient to have definitions of addition and subtraction acting directly on bitstring operands.

If x and y are bitstrings of the same length N, so that N = Len(x) = Len(y), then x+y and x-y are the least significant N bits of the results of converting them to integers and adding or subtracting them. Signed and unsigned conversions produce the same result:

  x+y = (SInt(x) + SInt(y))<N–1:0>
  = (UInt(x) + UInt(y))<N–1:0>
  x−y = (SInt(x) − SInt(y))<N–1:0>
  = (UInt(x) − UInt(y))<N–1:0>

If x is a bitstring of length N and y is an integer, x+y and x−y are the bitstrings of length N defined by x+y = x+y<N-1:0> and x−y = x− y<N-1:0>. Similarly, if x is an integer and y is a bitstring of length N, x+y and x−y are the bitstrings of length N defined by x+y = x+y<N-1:0> + y and x−y = x+y<N-1:0> − y.

Comparisons

If x and y are integers or reals, then x == y, x != y, x < y, x <= y, x > y, and x >= y are equal, not equal, less than, less than or equal, greater than, and greater than or equal comparisons between them, producing Boolean results. In the case of == and !=, this extends the generic definition applying to any two values of the same type to also act between integers and reals.

Multiplication

If x and y are integers or reals, then x * y is the product of x and y. It is of type integer if x and y are both of type integer, and real otherwise.

Division and modulo

If x and y are integers or reals, then x/y is the result of dividing x by y, and is always of type real.
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If \( x \) and \( y \) are integers, then \( x \text{ DIV} \ y \) and \( x \text{ MOD} \ y \) are defined by:

\[
\begin{align*}
\text{DIV} & \quad x \text{ DIV} y = \text{RoundDown}(x/y) \\
\text{MOD} & \quad x \text{ MOD} y = x - y \times (x \text{ DIV} y)
\end{align*}
\]

It is a pseudocode error to use any of \( x/y \), \( x \text{ MOD} y \), or \( x \text{ DIV} y \) in any context where \( y \) can be zero.

**Square root**

If \( x \) is an integer or a real, \( \sqrt{x} \) is its square root, and is always of type \text{real}.

**Rounding and aligning**

If \( x \) is a real:

- \( \text{RoundDown}(x) \) produces the largest integer \( n \) such that \( n \leq x \).
- \( \text{RoundUp}(x) \) produces the smallest integer \( n \) such that \( n \geq x \).
- \( \text{RoundTowardsZero}(x) \) produces \( \text{RoundDown}(x) \) if \( x > 0.0 \), 0 if \( x == 0.0 \), and \( \text{RoundUp}(x) \) if \( x < 0.0 \).

If \( x \) and \( y \) are both of type \text{integer}, \( \text{Align}(x, y) = y \times (x \text{ DIV} y) \) is of type \text{integer}.

If \( x \) is of type \text{bitstring} and \( y \) is of type \text{integer}, \( \text{Align}(x, y) = (\text{Align}(\text{UInt}(x), y))_{\text{Len}(x)-1:0} \) is a bitstring of the same length as \( x \).

It is a pseudocode error to use either form of \( \text{Align}(x, y) \) in any context where \( y \) can be 0. In practice, \( \text{Align}(x, y) \) is only used with \( y \) a constant power of two, and the bitstring form used with \( y = 2^n \) has the effect of producing its argument with its \( n \) low-order bits forced to zero.

**Scaling**

If \( n \) is an integer, \( 2^n \) is the result of raising 2 to the power \( n \) and is of type \text{real}.

If \( x \) and \( n \) are of type \text{integer}, then:

- \( x \ll n = \text{RoundDown}(x \times 2^n) \).
- \( x \gg n = \text{RoundDown}(x \times 2^{-n}) \).

**Maximum and minimum**

If \( x \) and \( y \) are integers or reals, then \( \text{Max}(x, y) \) and \( \text{Min}(x, y) \) are their maximum and minimum respectively. Both are of type \text{integer} if \( x \) and \( y \) are both of type \text{integer}, and \text{real} otherwise.
E3.5 Statements and program structure

The following sections describe the control statements used in the pseudocode:

- Simple statements.
- Compound statements on page E3-327.
- Comments on page E3-330.

E3.5.1 Simple statements

Each of the following simple statements must be terminated with a semicolon, as shown.

Assignments

An assignment statement takes the form:

<assignable_expression> = <expression>;

Procedure calls

A procedure call takes the form:

<procedure_name>(<arguments>);

Return statements

A procedure return takes the form:

return;

and a function return takes the form:

return <expression>;

where <expression> is of the type declared in the function prototype line.

UNDEFINED

This subsection describes the statement:

UNDEFINED;

This statement indicates a special case that replaces the behavior defined by the current pseudocode, apart from behavior required to determine that the special case applies. The replacement behavior is that the Undefined Instruction exception is taken.

UNPREDICTABLE

This subsection describes the statement:

UNPREDICTABLE;

This statement indicates a special case that replaces the behavior defined by the current pseudocode, apart from behavior required to determine that the special case applies. The replacement behavior is UNPREDICTABLE.

SEE...

This subsection describes the statement:

SEE <reference>;
This statement indicates a special case that replaces the behavior defined by the current pseudocode, apart from behavior required to determine that the special case applies. The replacement behavior is that nothing occurs as a result of the current pseudocode because some other piece of pseudocode defines the required behavior. The <reference> indicates where that other pseudocode can be found.

It usually refers to another instruction but can also refer to another encoding or note of the same instruction.

**IMPLEMENTATION_DEFINED**

This subsection describes the statement:

```
IMPLEMENTATION_DEFINED {<text>};
```

This statement indicates a special case that replaces the behavior defined by the current pseudocode, apart from behavior required to determine that the special case applies. The replacement behavior is IMPLEMENTATION DEFINED. An optional <text> field can give more information.

**SUBARCHITECTURE_DEFINED**

This subsection describes the statement:

```
SUBARCHITECTURE_DEFINED <text>;
```

This statement indicates a special case that replaces the behavior defined by the current pseudocode, apart from behavior required to determine that the special case applies. The replacement behavior is SUBARCHITECTURE DEFINED. An optional <text> field can give more information.

### E3.5.2 Compound statements

Indentation normally indicates the structure in compound statements. The statements contained in structures such as `if ... then ... else ...` or procedure and function definitions are indented more deeply than the statement itself, and their end is indicated by returning to the original indentation level or less.

Indentation is normally done by four spaces for each level.

**if ... then ... else ...**

A multi-line `if ... then ... else ...` structure takes the form:

```
if <boolean_expression> then
    <statement 1>
    <statement 2>
    ...
    <statement n>
elseif <boolean_expression> then
    <statement a>
    <statement b>
    ...
    <statement z>
else
    <statement A>
    <statement B>
    ...
    <statement Z>
```

The block of lines consisting of `elsif` and its indented statements is optional, and multiple such blocks can be used.

The block of lines consisting of `else` and its indented statements is optional.

Abbreviated one-line forms can be used when there are only simple statements in the `then` part and in the `else` part, if it is present, such as:

```
if <boolean_expression> then <statement 1>
if <boolean_expression> then <statement 1> else <statement A>
if <boolean_expression> then <statement 1> <statement 2> else <statement A>
```
Note

In these forms, `<statement 1>`, `<statement 2>` and `<statement A>` must be terminated by semicolons. This and the fact that the else part is optional are differences from the `if .. then .. else ..` expression.
repeat … until …

A repeat .. until .. structure takes the form:

```
repeat
  <statement 1>
  <statement 2>
  ...
  <statement n>
until <boolean_expression>;
```

while … do

A while .. do structure takes the form:

```
while <boolean_expression> do
  <statement 1>
  <statement 2>
  ...
  <statement n>
```

for …

A for .. structure takes the form:

```
for <assignable_expression> = <integer_expr1> to <integer_expr2>
  <statement 1>
  <statement 2>
  ...
  <statement n>
```

case … of …

A case .. of .. structure takes the form:

```
case <expression> of
  when <constant values>
    <statement 1>
    <statement 2>
    ...
    <statement n>
  ... more "when" groups ...
  otherwise
    <statement A>
    <statement B>
    ...
    <statement Z>
```

In this structure, <constant values> consists of one or more constant values of the same type as <expression>, separated by commas. Abbreviated one line forms of when and otherwise parts can be used when they contain only simple statements.

If <expression> has a bitstring type, <constant values> can also include bitstring constants containing ‘x’ bits. For details see Equality and non-equality testing on page E3-321.
Procedure and function definitions

A procedure definition takes the form:

<pre>
<procedure name>({<argument prototypes>})
  <statement 1>
  <statement 2>
  ...
  <statement n>
</pre>

where <argument prototypes> consists of zero or more argument definitions, separated by commas. Each argument definition consists of a type name followed by the name of the argument.

--- Note ---

This first prototype line is not terminated by a semicolon. This helps to distinguish it from a procedure call.

---

A function definition is similar but also declares the return type of the function:

<pre>
<return type> <function name>({<argument prototypes>})
  <statement 1>
  <statement 2>
  ...
  <statement n>
</pre>

An array-like function is similar but with square brackets:

<pre>
<return type> <function name>[{<argument prototypes>}]
  <statement 1>
  <statement 2>
  ...
  <statement n>
</pre>

An array-like function also usually has an assignment prototype:

<pre>
<function name>[{<argument prototypes>}] = <value prototypes>
  <statement 1>
  <statement 2>
  ...
  <statement n>
</pre>

E3.5.3 Comments

Two styles of pseudocode comment exist:

•  // starts a comment that is terminated by the end of the line.
•  /* starts a comment that is terminated by */.
This glossary describes some of the terms that are used in ARM documentation.

**Abort**

An abort occurs when an illegal memory access causes an exception. An abort can be generated by the hardware that manages memory accesses, or by the external memory system.

**ADI**

See ARM Debug Interface (ADI).

**AHB**

An AMBA bus protocol supporting pipelined operation, with the address and data phases occurring during different clock periods, meaning that the address phase of a transfer can occur during the data phase of the previous transfer. AHB provides a subset of the functionality of the AMBA AXI protocol.

See also AMBA.

**Aligned**

A data item stored at an address that is exactly divisible by the number of bytes that defines its data size. Aligned doublewords, words, and halfwords have addresses that are divisible by eight, four, and two respectively. An aligned access is one where the address of the access is aligned to the size of each element of the access.

**AMBA**

The AMBA family of protocol specifications is the ARM open standard for on-chip buses. AMBA provides solutions for the interconnection and management of the functional blocks that make up a System-on-Chip (SoC). Applications include the development of embedded systems with one or more processors or signal processors and multiple peripherals.

**APB**

An AMBA bus protocol for ancillary or general-purpose peripherals such as timers, interrupt controllers, UARTs, and I/O ports. It connects to the main system bus through a system-to-peripheral bus bridge that helps reduce system power consumption.

**ARM Debug Interface (ADI)**

The ADI connects a debugger to a device. The ADI is used to access memory-mapped components in a system, such as processors and CoreSight components. The ADI protocol defines the physical wire protocols permitted, and the logical programmers model.
AXI
An AMBA bus protocol that supports:
• Separate phases for address or control and data.
• Unaligned data transfers using byte strobes.
• Burst-based transactions with only start address issued.
• Separate read and write data channels.
• Issuing multiple outstanding addresses.
• Out-of-order transaction completion.
• Optional addition of register stages to meet timing or repropagation requirements.

The AXI protocol includes optional signaling extensions for low-power operation.

Big-endian
In the context of the ARM architecture, big-endian is defined as the memory organization in which the least significant byte of a word is at a higher address than the most significant byte, for example:
• A byte or halfword at a word-aligned address is the most significant byte or halfword in the word at that address.
• A byte at a halfword-aligned address is the most significant byte in the halfword at that address.

See also Little-endian and Endianness.

Boundary scan chain
A boundary scan chain is made up of serially-connected devices that implement boundary scan technology using a standard JTAG TAP interface. Each device contains at least one TAP controller containing shift registers that form the chain connected between TDI and TDO, through which test data is shifted. A core can contain several shift registers, enabling a scan to access selected parts of the device.

Burst
A group of transfers that form a single transaction. With AMBA protocols, only the first transfer of the burst includes address information, and the transfer type determines the addresses used for subsequent transfers.

Cold reset
A cold reset has the same effect as starting the processor by turning the power on. This clears main memory and many internal settings. Some program failures can lock up the core and require a cold reset to restart the system.

This is also known as power-on or powerup reset.

See also Processing Element (PE), Warm reset.

Core reset
See Warm reset.

DAP
See Debug Access Port (DAP).

Data Link layer
The layer of an ADIv5 implementation that provides the functional and procedural means to transfer data between the external debugger and the Debug Port (DP). ADIv5 and upwards define two Data Link layers, one based on the IEEE 1149.1 Standard Test Access Port and Boundary Scan Architecture, referred to as JTAG, and one based on the ARM Serial Wire Debug protocol interface, referred to as SW-DP.

DATA LINK DEFINED
Means that the behavior is not defined by the base architecture, but must be defined and documented by individual Data Link layers of the architecture.

When DATA LINK DEFINED appears in body text, it is always in SMALL CAPITALS.

DBGTAP
See Debug Test Access Port (DBGTAP).

Debug Access Port (DAP)
A block that acts as an AMBA, AHB, or AHB-Lite master on a system bus, to provide access to the debug target.

Debug Test Access Port (DBGTAP)
A debug control and data interface based on IEEE 1149.1 JTAG Test Access Port (TAP).

Debugger
A debugging system that includes a program, used to detect, locate, and correct software faults, together with custom hardware that supports software debugging.

Doubleword
A 64-bit data item. Doublewords are normally at least word-aligned in ARM systems.
Doubleword-aligned
A data item having a memory address that is divisible by eight.

Embedded Trace Macrocell (ETM)
A hardware macrocell that, when connected to a core, outputs trace information on a trace port. The ETM provides core-driven trace through a trace port compliant to the ATB protocol. An ETM always supports instruction trace, and might support data trace.

Endianness
The scheme that determines the order of the successive bytes of data in a larger data structure when that structure is stored in memory.
See also Little-endian and Big-endian.

ETM
See Embedded Trace Macrocell (ETM).

Halfword
A 16-bit data item. Halfwords are normally halfword-aligned in ARM systems.

Halfword-aligned
A data item having a memory address that is divisible by 2.

Host
A computer that provides data and other services to another computer. In the context of an ARM debugger, a computer providing debugging services to a target being debugged.

IMP DEF
See IMPLEMENTATION DEFINED.

IMPLEMENTATION DEFINED
Behavior that is not defined by the architecture, but must be defined and documented by individual implementations.

When IMPLEMENTATION DEFINED appears in body text, it is always in SMALL CAPITALS.

Joint Test Action Group (JTAG)
An IEEE group focussed on silicon chip testing methods. Many debug and programming tools use a Joint Test Action Group (JTAG) interface port to communicate with processors.


JTAG
See Joint Test Action Group (JTAG).

JTAG Access Port (JTAG-AP)
An optional component of the DAP that provides debugger access to on-chip scan chains.

JTAG Debug Port (JTAG-DP)
An optional external interface for the DAP that provides a standard JTAG interface for debug access.

JTAG-AP
See JTAG Access Port (JTAG-AP).

JTAG-DP
See JTAG Debug Port (JTAG-DP).

Little-endian
In the context of the ARM architecture, little-endian is defined as the memory organization in which the most significant byte of a word is at a higher address than the least significant byte.
See also Big-endian and Endianness.

PE
See Processing Element (PE).

Powerup reset
See Cold reset.

Processing Element (PE)
The abstract machine defined in the ARM architecture, as documented in an ARM Architecture Reference Manual. A PE implementation that is compliant with the ARM architecture must conform with the behaviors described in the corresponding ARM Architecture Reference Manual.

RAO
See Read-As-One (RAO).

RAO/WI
Read-as-One, Writes Ignored.
Hardware must implement the field as Read-as-One, and must ignore writes to the field. Software can rely on the field reading as all 1s, and on writes being ignored. This description can apply to a single bit that reads as 0b1, or to a field that reads as all 1s.

See also Read-As-One (RAO).

**RAZ**

See Read-As-Zero (RAZ).

**RAZ/WI**

Read-as-Zero, Writes ignored.

Hardware must implement the field as Read-as-Zero, and must ignore writes to the field. Software can rely on the field reading as all 0s, and all writes being ignored. This description can apply to a single bit that reads as 0b0, or to a field that reads as all 0s.

See also Read-As-Zero (RAZ).

**Read-As-One (RAO)**

Hardware must implement the field as reading as all 1s. Software can rely on the field reading as all 1s. This description can apply to a single bit that reads as 0b1, or to a field that reads as all 1s.

**Read-As-Zero (RAZ)**

Hardware must implement the field as reading as all 0s. Software can rely on the field reading as all 0s. This description can apply to a single bit that reads as 0b0, or to a field that reads as all 0s.

**RES0**

A reserved bit or field with Should-Be-Zero-or-Preserved (SBZP) behavior. Used for fields in register descriptions, and for fields in architecturally-defined data structures that are held in memory, for example in translation table descriptors.

---

**Note**

RES0 is not used in descriptions of instruction encodings.

Within the architecture, there are some cases where a register bit or bitfield:

- Is RES0 in some defined architectural context.
- Has different defined behavior in a different architectural context.

This means the definition of RES0 for register fields is:

**If a bit is RES0 in all contexts**

It is IMPLEMENTATION DEFINED whether:

1. The bit is hardwired to 0b0. In this case:
   
   - Reads of the bit always return 0b0.
   
   - Writes to the bit are ignored.

   The bit might be described as RES0, WI, to distinguish it from a bit that behaves as described in 2.

2. The bit can be written. In this case:
   
   - An indirect write to the register sets the bit to 0b0.
   
   - A read of the bit returns the last value successfully written to the bit.

---

**Note**

As indicated in this list, this value might be written by an indirect write to the register.

If the bit has not been successfully written since reset, then the read of the bit returns the reset value if there is one, or otherwise returns an UNKNOWN value.

- A direct write to the bit must update a storage location associated with the bit.
- The value of the bit must have no effect on the operation of the core, other than determining the value read back from the bit.
Whether RES0 bits or fields follow behavior 1 or behavior 2 is implementation defined on a field-by-field basis.

If a bit is RES0 only in some contexts

When the bit is described as RES0:

• An indirect write to the register sets the bit to 0b0.
• A read of the bit must return the value last successfully written to the bit, regardless of the use of the register when the bit was written.

Note

As indicated in this list, this value might be written by an indirect write to the register.

If the bit has not been successfully written since reset, then the read of the bit returns the reset value if there is one, or otherwise returns an unknown value.

• A direct write to the bit must update a storage location associated with the bit.
• While the use of the register is such that the bit is described as RES0, the value of the bit must have no effect on the operation of the core, other than determining the value read back from that bit.

For any RES0 bit, software:

• Must not rely on the bit reading as 0b0.
• Must use an SBZP policy to write to the bit.

The RES0 description can apply to bits or bitfields that are read-only, or are write-only:

• For a read-only bit, RES0 indicates that the bit reads as 0b0, but software must treat the bit as UNKNOWN.
• For a write-only bit, RES0 indicates that software must treat the bit as SBZ.

This RES0 description can apply to a single bit that should be written as its preserved value or as 0b0, or to a field that should be written as its preserved value or as all 0s.

In body text, the term RES0 is shown in SMALL CAPITALS.

See also Read-As-Zero (RAZ), Should-Be-Zero-or-Preserved (SBZP), UNKNOWN.

RES1

A reserved bit or field with Should-Be-One-or-Preserved (SBOP) behavior. Used for fields in register descriptions, and for fields in architecturally-defined data structures that are held in memory, for example in translation table descriptors.

Note

RES1 is not used in descriptions of instruction encodings.

Within the architecture, there are some cases where a register bit or bitfield:

• Is RES1 in some defined architectural context.
• Has different defined behavior in a different architectural context.

This means the definition of RES1 for register fields is:

If a bit is RES1 in all contexts

It is IMPLEMENTATION DEFINED whether:

1. The bit is hardwired to 0b1. In this case:
   • Reads of the bit always return 0b1.
   • Writes to the bit are ignored.

The bit might be described as RES1, WI, to distinguish it from a bit that behaves as described in 2.
2. The bit can be written. In this case:
   • An indirect write to the register sets the bit to \(0b1\).
   • A read of the bit returns the last value successfully written to the bit.

   **Note**
   As indicated in this list, this value might be written by an indirect write to the register.

   If the bit has not been successfully written since reset, then the read of the bit returns the reset value if there is one, or otherwise returns an UNKNOWN value.
   • A direct write to the bit must update a storage location associated with the bit.
   • The value of the bit must have no effect on the operation of the core, other than determining the value read back from the bit.

Whether RES1 bits or fields follow behavior 1 or behavior 2 is implementation defined on a field-by-field basis.

**If a bit is RES1 only in some contexts**

When the bit is described as RES1:
   • An indirect write to the register sets the bit to \(0b1\).
   • A read of the bit must return the value last successfully written to the bit, regardless of the use of the register when the bit was written.

   **Note**
   As indicated in this list, this value might be written by an indirect write to the register.

   If the bit has not been successfully written since reset, then the read of the bit returns the reset value if there is one, or otherwise returns an unknown value.
   • A direct write to the bit must update a storage location associated with the bit.
   • While the use of the register is such that the bit is described as RES1, the value of the bit must have no effect on the operation of the core, other than determining the value read back from that bit.

For any RES1 bit, software:
   • Must not rely on the bit reading as \(0b1\).
   • Must use an **SBOP** policy to write to the bit.

The RES1 description can apply to bits or bitfields that are read-only, or are write-only:
   • For a read-only bit, RES1 indicates that the bit reads as \(0b1\), but software must treat the bit as UNKNOWN.
   • For a write-only bit, RES1 indicates that software must treat the bit as **SBO**.

This RES1 description can apply to a single bit that should be written as its preserved value or as \(0b0\), or to a field that should be written as its preserved value or as all 1s.

In body text, the term RES1 is shown in SMALL CAPITALS.

See also **Read-As-One (RAO)**, **Should-Be-One-or-Preserved (SBOP)**, **UNKNOWN**.

**Reserved**

Unless otherwise stated in the architecture or product documentation:
   • Reserved instruction and 32-bit system control register encodings are unpredictable.
   • Reserved 64-bit system control register encodings are undefined.
   • Reserved register bit fields are UNK/SBZP.

**SBO**

See **Should-Be-One (SBO)**.

**SBOP**

See **Should-Be-One-or-Preserved (SBOP)**.

**SBZ**

See **Should-Be-Zero (SBZ)**.
SBZP

See Should-Be-Zero-or-Preserved (SBZP).

Scan chain

A scan chain is made up of serially-connected devices that implement boundary scan technology using a standard JTAG TAP interface. Each device contains at least one TAP controller containing shift registers that form the chain connected between TDI and TDO, through which test data is shifted. Processors can contain several shift registers to enable you to access selected parts of the device.

Serial Wire debug (SWD)

A debug implementation that uses a serial connection between the SoC and a debugger. This connection normally requires a bidirectional data signal and a separate clock signal, rather than the four to six signals required for a JTAG connection.

Serial Wire Debug Port (SW-DP)

The interface for Serial Wire Debug.

Serial Wire JTAG Debug Port (SWJ-DP)

The SWJ-DP is a combined JTAG-DP and SW-DP that you can use to connect either a Serial Wire Debug (SWD) or JTAG probe to a target.

Should-Be-One (SBO)

Hardware must ignore writes to the field.

Software should write the field as all 1s. If software writes a value that is not all 1s, it must expect an UNPREDICTABLE result.

This description can apply to a single bit that should be written as 0b1, or to a field that should be written as all 1s.

Should-Be-One-or-Preserved (SBOP)

The ARMv7 Large Physical Address Extension modified the definition of SBOP to apply to register fields that are SBOP in some but not all contexts. From the introduction of ARMv8 such register fields are described as RES1, see RES1. The definition of SBOP given here applies only to fields that are SBOP in all contexts.

Hardware must ignore writes to the field.

If software has read the field since the core implementing the field was last reset and initialized, it should preserve the value of the field by writing the value that it previously read from the field. Otherwise, it should write the field as all 1s.

If software writes a value to the field that is not a value previously read for the field and is not all 1s, it must expect an UNPREDICTABLE result.

This description can apply to a single bit that should be written as its preserved value or as 0b1, or to a field that should be written as its preserved value or as all 1s.

See also Should-Be-Zero-or-Preserved (SBZP), Should-Be-One (SBO).

Should-Be-Zero (SBZ)

Hardware must ignore writes to the field.

Software should write the field as all 0s. If software writes a value that is not all 0s, it must expect an UNPREDICTABLE result.

This description can apply to a single bit that should be written as 0b0, or to a field that should be written as all 0s.

Should-Be-Zero-or-Preserved (SBZP)

The ARMv7 Large Physical Address Extension modified the definition of SBZP to apply to register fields that are SBZP in some but not all contexts. From the introduction of ARMv8 such register fields are described as RES0, see RES0. The definition of SBZP given here applies only to field that are SBZP in all contexts.

Hardware must ignore writes to the field.

If software has read the field since the core implementing the field was last reset and initialized, it must preserve the value of the field by writing the value that it previously read from the field. Otherwise, it must write the field as all 0s.

If software writes a value to the field that is not a value previously read for the field and is not all 0s, it must expect an UNPREDICTABLE result.
This description can apply to a single bit that should be written as its preserved value or as $0b0$, or to a field that should be written as its preserved value or as all $0s$.

See also Should-Be-One-or-Preserved (SBOP), Should-Be-Zero (SBZ).

**SWD**

See Serial Wire debug (SWD).

**SW-DP**

See Serial-Wire Debug Port (SW-DP).

**SWJ-DP**

See Serial Wire JTAG Debug Port (SWJ-DP)

**TAP**

See Test Access Port (TAP).

**Test Access Port (TAP)**

The collection of four mandatory and one optional terminals that form the input/output and control interface to a JTAG boundary-scan architecture. The mandatory terminals are **TDI**, **TDO**, **TMS**, and **TCK**. In the JTAG standard, the **nTRST** signal is optional, but this signal is mandatory in ARM processors because it is used to reset the debug logic.

See also Joint Test Action Group (JTAG), Debug Test Access Port (DBGTAP).

**Trace port**

A port on a device, such as a processor or ASIC, to output trace information.

**Unaligned**

An unaligned access is an access where the address of the access is not aligned to the size of the elements of the access.

See also Aligned.

**UNKNOWN**

An UNKNOWN value does not contain valid data, and can vary from moment to moment, instruction to instruction, and implementation to implementation. An UNKNOWN value must not return information that cannot be accessed at the current or a lower level of privilege using instructions that are not UNPREDICTABLE or CONSTRAINED UNPREDICTABLE and do not return UNKNOWN values.

An UNKNOWN value must not be documented or promoted as having a defined value or effect.

When UNKNOWN appears in body text, it is always in SMALL CAPITALS.

**UNP**

See UNPREDICTABLE.

**UNPREDICTABLE**

For an ARM processor, UNPREDICTABLE means the behavior cannot be relied upon. UNPREDICTABLE behavior must not perform any function that cannot be performed at the current or a lower level of privilege using instructions that are not UNPREDICTABLE.

UNPREDICTABLE behavior must not be documented or promoted as having a defined effect. An instruction that is UNPREDICTABLE can be implemented as UNDEFINED.

In an implementation that supports Virtualization, the Non-secure execution of unpredictable instructions at a lower level of privilege can be trapped to the hypervisor, provided that at least one instruction that is not unpredictable can be trapped to the hypervisor if executed at that lower level of privilege.

For an ARM trace macrocell, UNPREDICTABLE means that the behavior of the macrocell cannot be relied on. Such conditions have not been validated. When applied to the programming of an event resource, only the output of that event resource is UNPREDICTABLE. UNPREDICTABLE behavior can affect the behavior of the entire system, because the trace macrocell can cause the core to enter Debug state, and external outputs can be used for other purposes.

--- Note ---

In issue A of this document, UNPREDICTABLE also meant an UNKNOWN value.

When UNPREDICTABLE appears in body text, it is always in SMALL CAPITALS.

**W1C**

Hardware must implement the bit as follows:

- Writing a $0b1$ to the bit clears the bit to $0b0$.
- Writing a $0b0$ to the bit has no effect.
Warm reset

Also known as a core reset. Initializes most of the processor functionality, excluding the debug controller and debug logic. This type of reset is useful if you are using the debugging features of a processor.

See also Cold reset.

WI

Hardware must ignore writes to the field. Software can rely on writes being ignored. This description can apply to a single bit, or to a field.

Word

A 32-bit data item. Words are normally word-aligned in ARM systems.

Word-aligned

A data item having a memory address that is divisible by four.